PROVES Electronics

Unlocking Space with Modularity and Affordability

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Agenda



- PROVES
- Challenges
- Background
- Yearling
- Xmera (Chimera)
- Subsystems
- Impact

PROVES: Pleaides Rapid **Orbital** Verification **Experimental System**

Rapid Verification Experimental

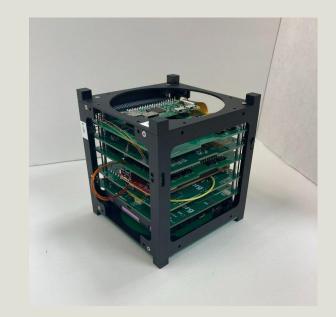
Challenges

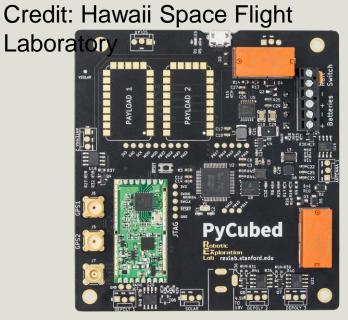
- Space is really hard
 - \circ $\,$ We failed twice before success $\,$
- Space is expensive
 - o Intention is to get it right the first time
 - BroncoSat-1 cost about \$48k in just components
- Stop reinventing the wheel
 - o Offer up a standard
- Difficult to scale designs up
- Make design expandable



Background

- Two architecture paths
 - o PC/104 mounting hole pattern
 - Artemis CubeSat Kit
 - PyCubed
 - o Backplane
- Which one to use?
 - Yearling satellites used PC/104
 - Xmera satellite will use backplane





Credit: Max Holliday, REX Lab, Stanford

Yearling

Used PC/104-mounting hole pattern

Yearling-1
used the
PyCubed

- Launched January 3rd, 2023
- Failed to deploy

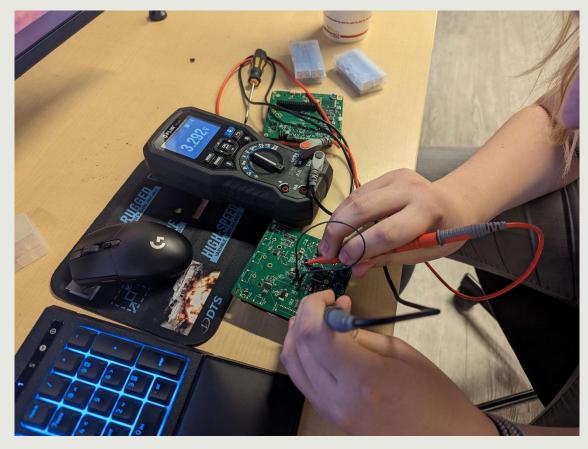
Yearling-2 used the 3PySquared

- Launched April 14th, 2023
- First received packet April 15th, 2023



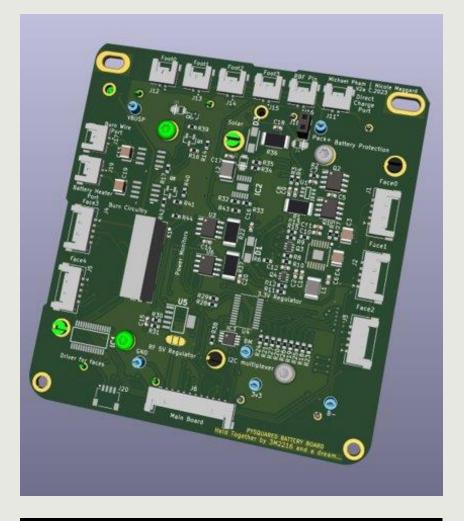
Design

- Drivers of off-the-shelf components
 - Increase accessibility
- Fast Design Turnaround
 - o Internal organization goals
 - Readily available hardware
- Open Source
 - Access software and hardware designs
 - End user can easily adjust standards to their needs
 - Tutorials in the pipeline



PC/104 Key Features

- Held in place by brackets or standoffs
- Can connect cards with stackable connectors or cables
- Boards can function independently of each
 other
- Not limited to backplane connections
 - Physical Spacing
 - Electrical interface
- Can densely stack electronics



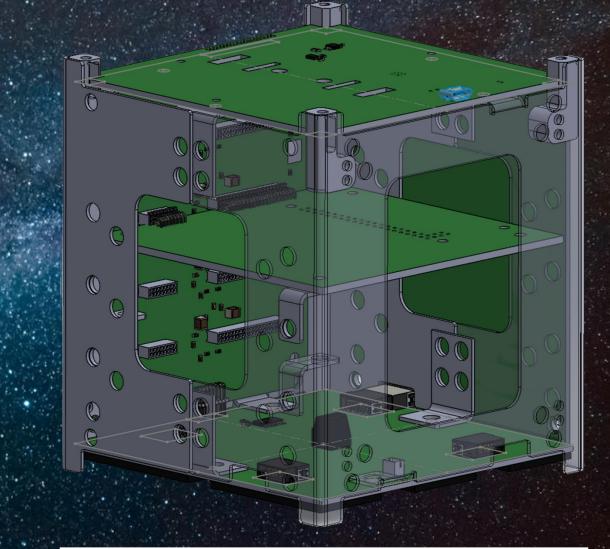
Xmera

Implements backplane architecture

Uses similar components as Yearling

Work-in-progress

Has potential to be expanded

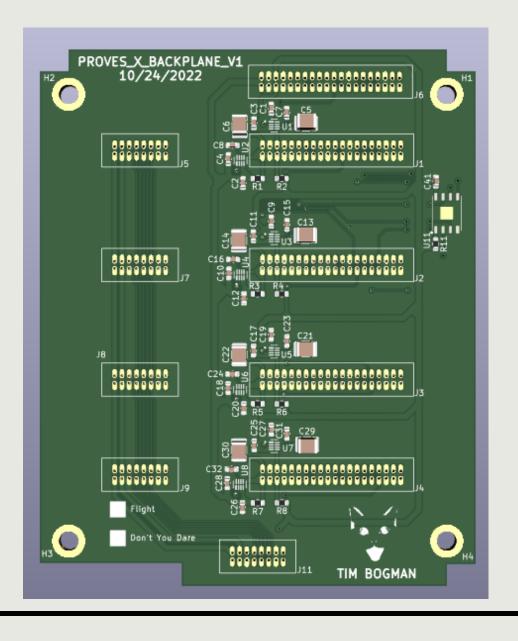


Design

Driverspen-Source

- Cards slot directly with backplane
 - Minimal cabling
 - Easier access to internal cards
 - Easier to troubleshoot
 - Adds structural support
- Scalability
- Modular Subsystems
 - Easily customizable





Backplane Key Features

- Cards held in place by brackets and electrical interface
- Standardized spacing
 - Larger cards skip slots
- Mix and Match cards for mission needs
 - Ex: Multiple EPS cards can be easily stacked for additional power budget
 - Ex: Extra flight computer for redundancy
- Backplane expandable for larger satellites
- No wiring
- Possible standardized interface connector

Subsystems

Command and Data Handling (C&DH)

Attitude Determination Control System (ADCS)

Electrical Power System (EPS)

Solar

Software

Payload

Command and Data Handling

Similarities:

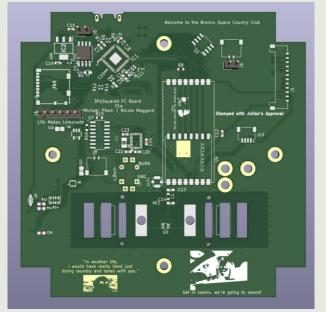
- Utilizes a HopeRF RFM9x module
 - LoRa modulation
 - o 430MHz range
- Utilizes an RP2040
 - Flight heritage
 - Extremely inexpensive

PC/104:

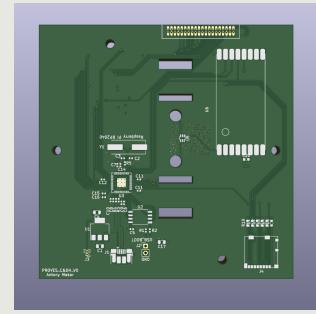
Integrated attitude control

Backplane:

• Designed as top cap but could be slotted internally



From Yearling-2 (PC/104)



From Xmera (BP)

Attitude Determination Control System

Similarities:

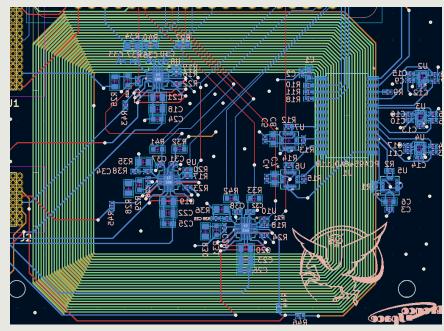
Contains accelerometers, gyroscopes, and magnetometers

PC/104:

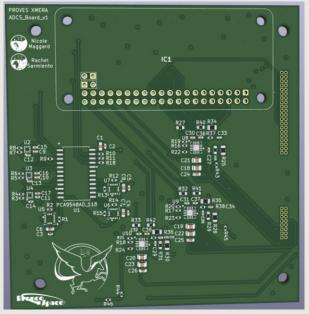
Integrated on Command and Data Handling board

Backplane:

- 40 pin breakout
 - Could interface with Raspberry Pi zero
 - Could interface with custom compute module
- Embedded magnetorquer coil
- Contains motor drivers
 - Interfaces with magnetorquer coils, reaction wheels, or other attitude control device through the Backplane



Both From Xmera (BP)



Electrical Power System

Similarities:

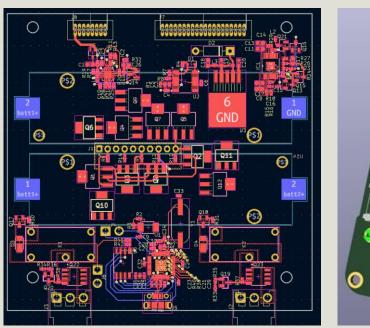
- Utilizes LT3652 to charge batteries from solar power
- Maintains all controls for battery heater
- Contains inputs for inhibit switches

PC/104:

Cabled directly to C&DH board, solar boards and switches individually

Backplane:

• Utilize an RP2040 to track power consumption, and make power-based decisions for the satellite



From Xmera (BP)

From Yearling-2 (PC/104)

Solar

Similarities:

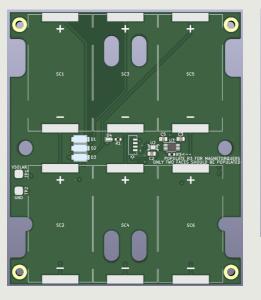
- Off-the-shelf components
 and sensors
- Embedded magnetorquer coil **PC/104**•

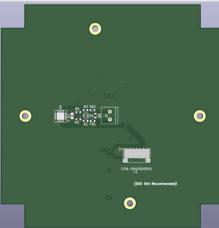
PC/104:

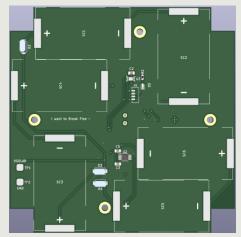
- Each face cabled to Battery Board
- Integrated motor drivers

Backplane:

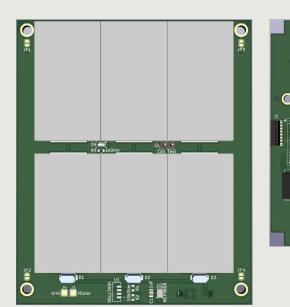
Fully modular subsystem
 with single backplane
 interface

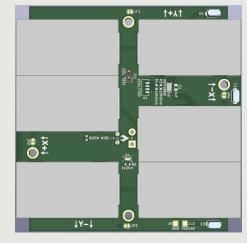






From Yearling-2 (PC/104)





16

From Xmera (BP)

0





382V



[MAIN]Looking to send face data	
[Functions]Sending Face Data	
[Field]Sending face 1/6: [20.875, 45,9648]	
Field[Sending packet 1/006:	
Field]Listening for transmissions, 10	
Fleid]packet received	
Field]msg: True, RSSI: -6	
ield]Sending face 2/6: [21.3125, 49.248] ield]Sending packet 2/006:	
ield]Sending packet 2/006:	
ield]Listening for transmissions, 10	
ield]packet received	
ield]msg: True, RSSI: 3	
ield]Sending face 3/6: [21.25, 28.512]	I
leld]Sending packet 3/006:	
eld]Listening for transmissions, 10	
eld]packet received	
eld]msg: True, RSSI: 4	
eld]Sending face 4/6: [21.1875, 97.1712]	
eld]Sending packet 4/006:	
ld]Listening for transmissions, 10	
ld]packet received	
ld]msg: True, RSSI: 4	
ld]Sending face 5/6: [20.875, 81.504, (21.25, 0	9.0, 0.0)]
d]Sending packet 5/006:	
d]Listening for transmissions, 10	
d]packet received	
d]msg: True, RSSI: 3	
ared]Started to manage battery	
ared]BATTERY Temp: 30 C	
area Jurchocournell EP Temp: 19 1801 C	
ared]MICROCONTROLLER Temp: 19.1801 C	
ared]Turning heatpad on	tage: 7.19
ared]draw current: 4.81798mA, and battery vol	ages stars
red]system voltage: 6.99405V	
TA]Creating Face Objects	
TA IDone I	
TA][ACTIVE][Temperature Sensor]	

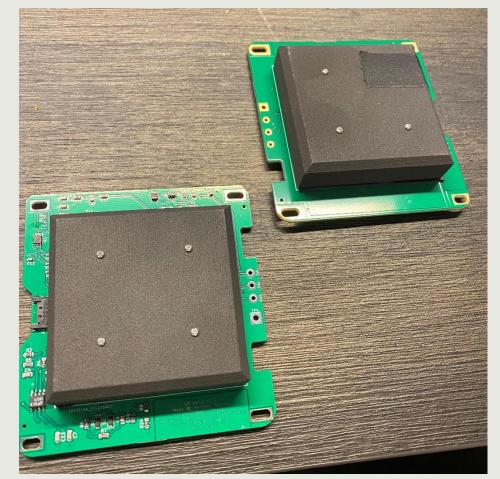
381', 'MT:20.1164'1 391, M120.1084 J Message Received 2/2{['FLD': True, 'Face4': True, 'IMU': True, 'Radio1': True 'Neopixe1': True, 'Face6': True, 'Face1': True, 'Face2': True, 'Face3': True 'SDcard': True, 'PWR': True, 'WDT': False, 'LiDAR': True) with RSSI -33 ue, 'Face4': True, 'TMU': True, 'Radio1': True, 'Neopixe1': True, 'Face6': e, 'Face1': True, 'Face2': True, 'Face3': True, 'SDcard': True, 'PWR': True WDT': False, 'LiDAR': True} ue, 'Face4': True, 'IMU': True, 'Radio1': True, 'Neopixe1': True, 'Face0': T e, 'Face1': True, 'Face2': True, 'Face3': True, 'SDcard': True, 'PWR': True, WDT': False, 'LiDAR': True} Message Received packet1/006: [20.875, 45.9648] with RSSI -35 [20.875, 45.9648] going to iterate for 006 cycles Message Received packet2/006: [21.3125, 49.248] [21.3125, 49.248] Message Received packet3/006: [21.25, 28.512] [21.25, 28.512] Message Received packet4/006: [21.1875, 97.1712] [21.1875, 97.1712] Message Received packet5/006: [20.875, 81.504, (21.25, 0.0, 0.0)] [20.875, 81.504, (21.25, 0.0, 0.0)] Message Received KN6NAQ Hello I am Yearling! I am in: normal power mode. V_B t = 7.19317V. IHBPFJASTMNE! KN6NAQ I am Yearling! I am in: normal power mode. V_Batt = 7.19317V. IHBPFJASTMNE! 6NAQ Message Received Yearling State of Health 1/2['PM:normal', 'VB:7.1939', 'TB .1875', 'ID:4.79998', 'VS:6.99453', 'MT:19.1801'] e of Health 1/2['PM:normal', 'VB:7.1939', 'TB:21.1875', 'ID:4.79998', 'VS: 453', 'MT:19.1801'] [20.875, 45.9648][21.3125, 49.248][21.25, 28.512][21.1875, 97.1712][20.875 .504, (21.25, 0.0, 0.0)]I am Yearling! I am in: normal power mode. V_Batt 19317V. IHBPFJASTMNE! KN6NAQe of Health 1/2['PM:normal', 'VB:7.1939', 'TB 875', 'ID:4.79998', 'VS:6.99453', 'MT:19.1801']

- Utilizes CircuitPython
- Beginner Friendly
- Maintained by Adafruit
- Teaches Object Oriented Programming
- Easy to debug

CDH]Getting Battery Data
MAIN]normal
BIG_DATA]Creating Face Objects
BIG_DATA]Done!
BIG_DATA][ERROR][Face0 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face1 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face2 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face3 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face4 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face5 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA]Faces Initialized
BIG_DATA]Creating Face List
BIG_DATA]All Face test error:function takes 2 positional arguments but 3 were given
FUNCTIONS]{'Face4': False, 'Face5': False, 'WDT': False, 'Neopixel': True, 'Face0': False, 'Face1'
se}
FUNCTIONS]['PM:normal', 'VB:0.0', 'IC:0.0', 'TB:20', 'MT:31.3517']
CDH]Getting Battery Data
MAIN_normal
MAIN]Looking to send face data
CDH]Getting Battery Data
MAIN]normal
MAIN]Getting face data
BIG_DATA]Creating Face Objects
BIG_DATA]Done!
BIG_DATA][ERROR][Face0 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face1 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face2 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face3 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face4 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA][ERROR][Face5 Initialization]function takes 2 positional arguments but 3 were given
BIG_DATA]Faces Initialized
BIG_DATA]Creating Face List BIG DATA]All Face test error:function takes 2 positional arguments but 3 were given
DIG_DATAJAII FACE TEST error: function takes 2 positional arguments but 3 were given

Payload

- Unlimited Variations
- Unlimited Expansion
- Unlimited Extrapolation
- Limited only by Creativity



Cosmic Watch

Impact

- Great educational tool
- Opportunity for industry progress
- Space for All
 - Be inspired
 - o Take the leap
 - Do cool science



Bronco Space and Stanford Student Space Initiative Teams together after AOS

012345678KN6NA Q Hello I am Yearl ing! I am in: maxi mum power mode. V_ Batt = 8. 02806V. I HBPFJASTM NE! KN6NA Q



Thank You For Listening! Any Questions?



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