

Presenting a  
**New Attachment  
Technology** for  
**In-space  
attachment to  
Unprepared  
Surfaces**

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# eTAP

## General On-Orbit Attachment Technology



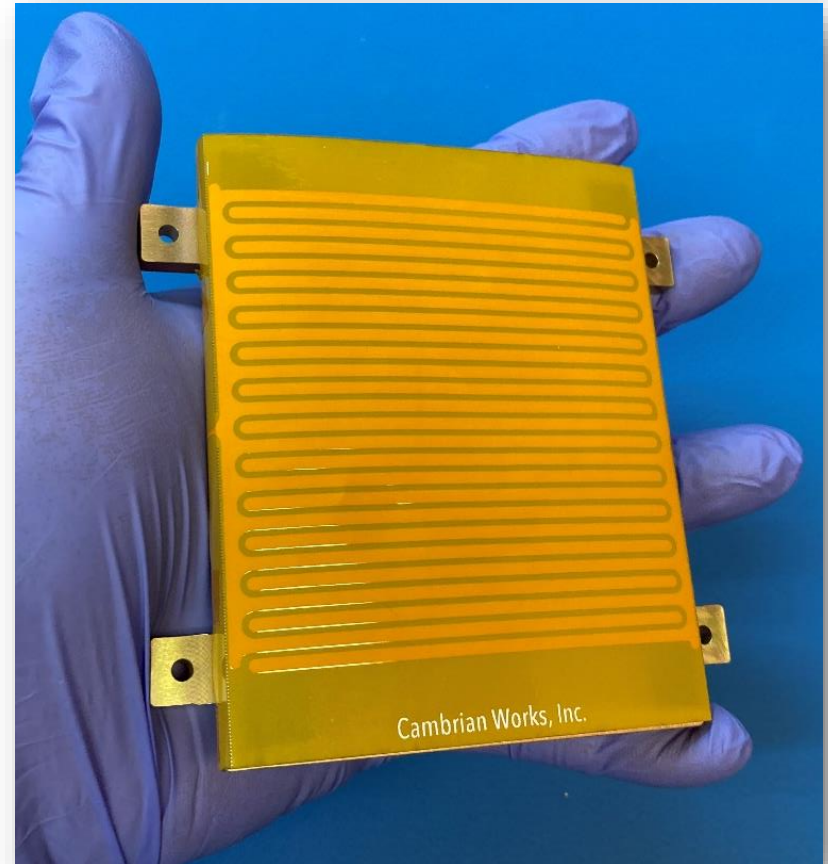
### Features

- Uses the principle of electro adhesion
- Instant attachment
- Attaches to conductors and insulators
- Attaches to unprepared surfaces
- Conform to non-planar surfaces
- On/Off attachment
- Built with space rated materials

### Demonstrated successfully with

Aluminum Alloys  
Anodized Al  
Steel  
Titanium

Glass  
Kapton  
Multi-Layer  
Insulation  
Carbon Fiber



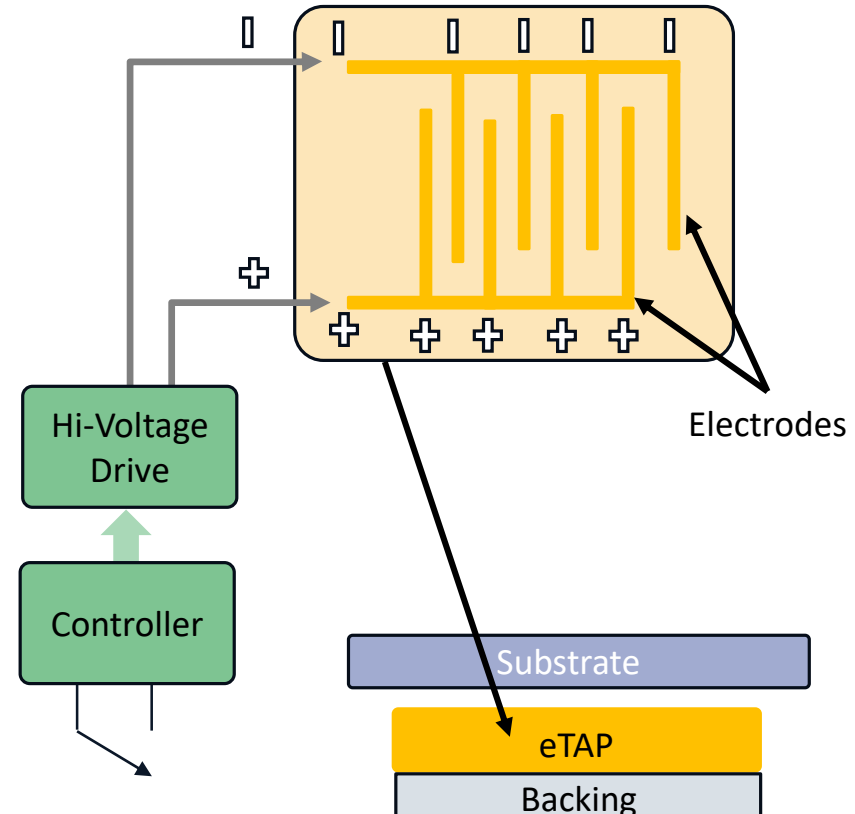
# How It Works

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# Electro-adhesion Anatomy



- **High Voltage Supply**
  - 1500V or higher
- **Electrodes**
  - High-voltage electrodes generate the electric fields
- **Dielectric**
  - Electrodes encapsulated within a dielectric for safe handling
  - Very thin package (<0.2mm)
- **Substrate**
  - Target surface for attachment



# Electro-adhesion Operating Principles



## • Conducting Substrates

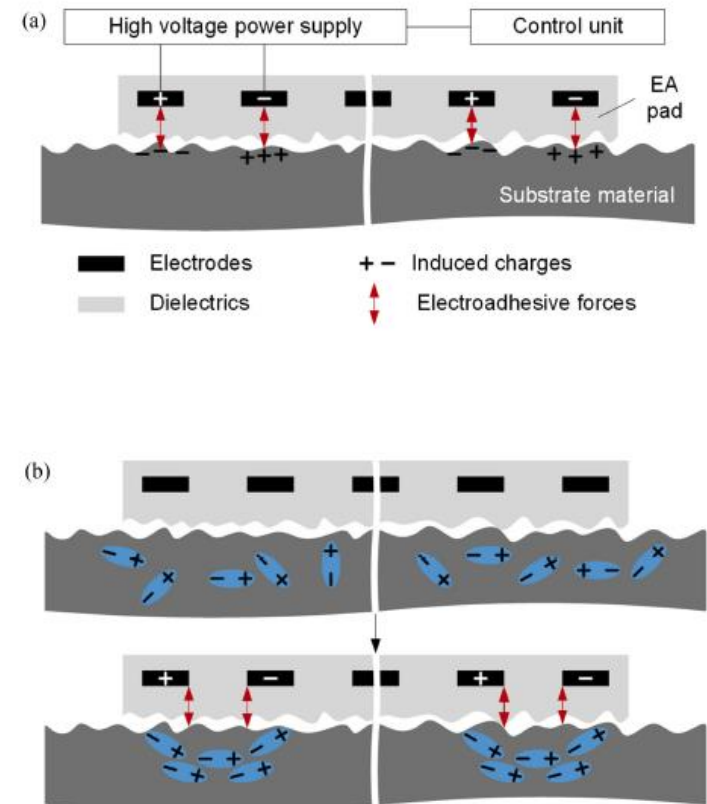
- eTAP field mirrors charges in a substrate opposing the fields imposed on the substrate surface. (Image courtesy Guo, et al. 2020)

## • Dielectric Substrates

- eTAP field affects the polarization of molecules within the opposing surface. (Image courtesy Guo, et al. 2020)

## • General Notes

- Adhesion force varies with material properties and surface contact
- Attractive force scales with (eTAP) area and voltage
- Shear attractive forces are particularly strong: about 10x normal forces
- System-level power consumption (including high-power generation) is on the order of milliwatts
- Fields penetrate only to a shallow “skin depth”: EMI/EMC concerns are minimal
- Minimal impact to substrates (i.e. no residues)



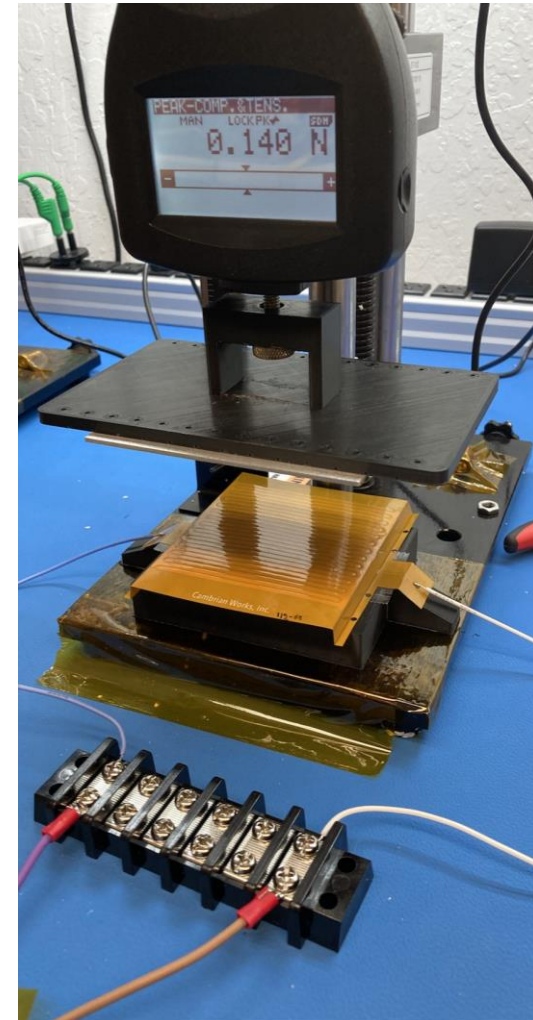
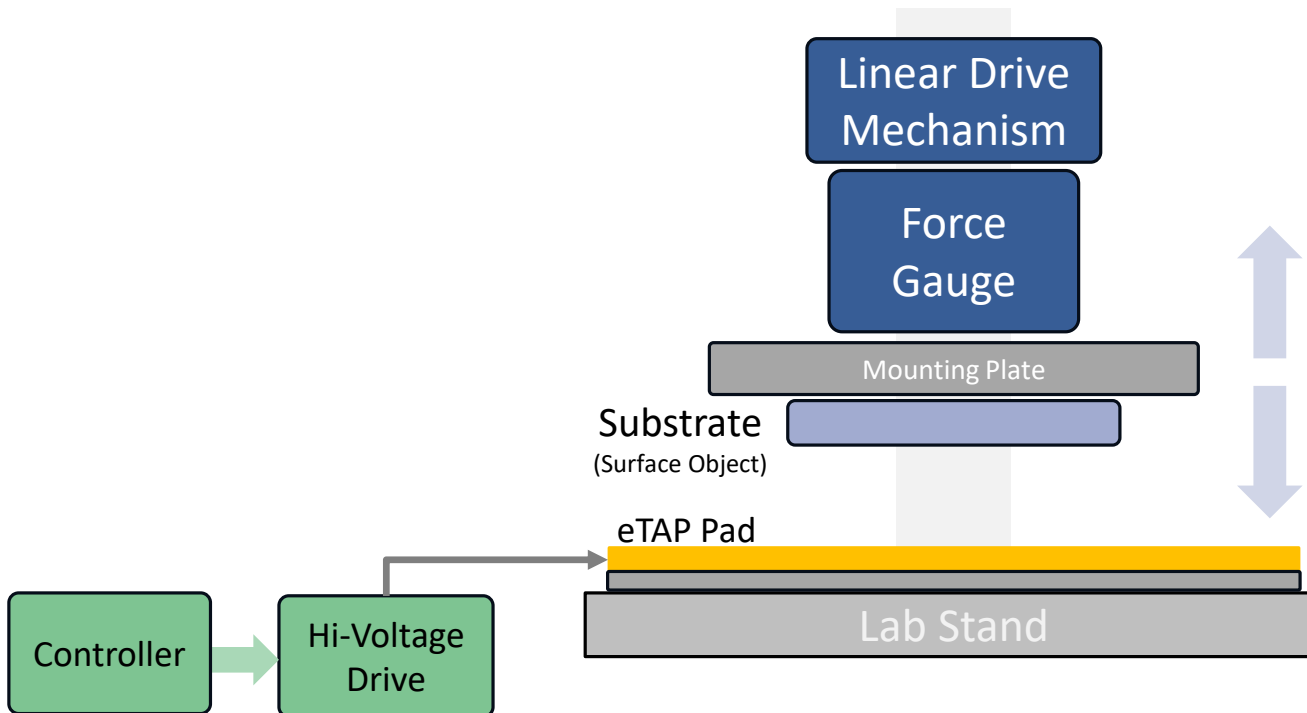
# Demonstration Results

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# eTAP Normal Force Testing



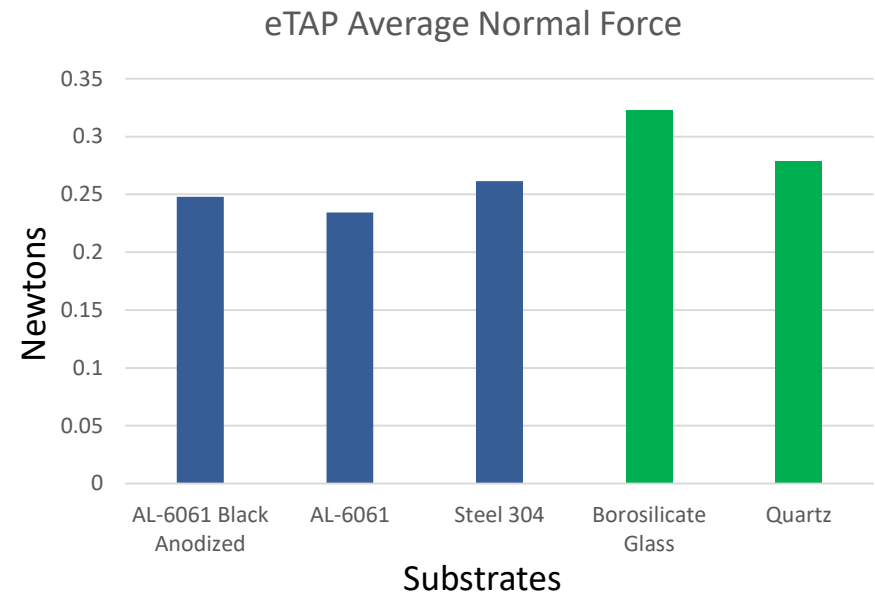
- Normal force testing setup allows for force measurement for different eTAP pad designs, material types, and voltage levels
- Different force gauges are used for different force level measurements.



# eTAP Testing Results



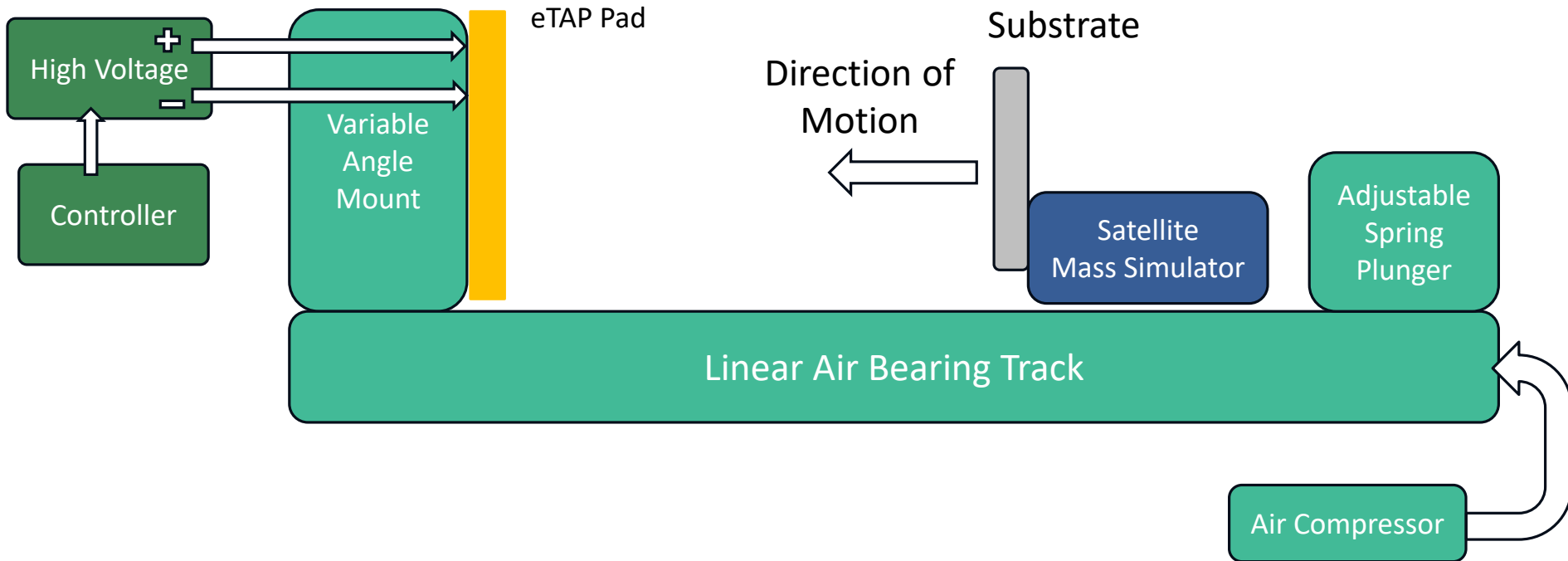
- Normal attractive forces are typically 15 mN/cm<sup>2</sup> at ambient pressure for a 4x4cm pad.
- Non-conductive coatings on conductive material do not affect attachment force.
- Insulator substrates have slightly higher normal attachment force than conductors.
- Normal force scales linearly with the attached area.
- Normal force attachment is significantly higher in vacuum than at ambient pressure.
- Mechanical design and mounting of the pads has a significant impact on the maximum attachment performance.



Data from example pads of 16 cm<sup>2</sup> area.



# Linear Velocity Capture Testing



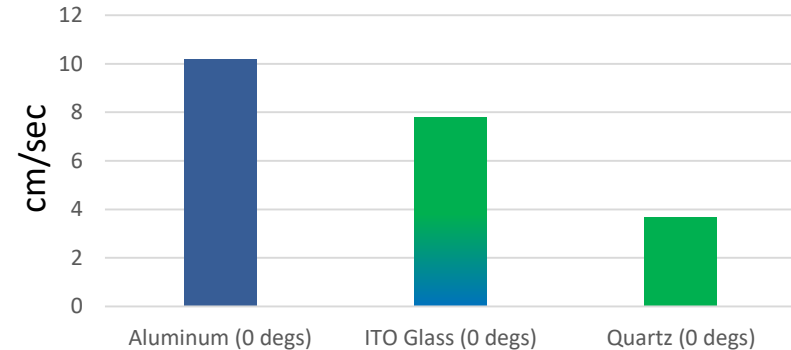
- Evaluate collision dynamics
- Repeatable impulsive docking at several velocities and angles
- Substrates can be swapped out
- Accommodates a satellite mass of 0.2kg

# Linear Velocity Capture Results

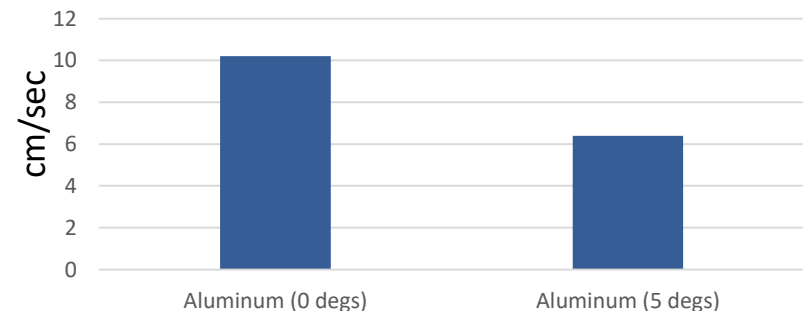


- Conductive substrates have a faster electrical response time (0.02sec) compared to dielectric materials, and a resulting ability to capture objects with a higher velocity.
- Dielectric substrates coated with a resistive layer ( $\leq 15\text{ohm/sq}$ , 135nm thickness) behave more like conductive materials and allow capture at higher velocities
- 5 degrees off normal reduces the capture velocity

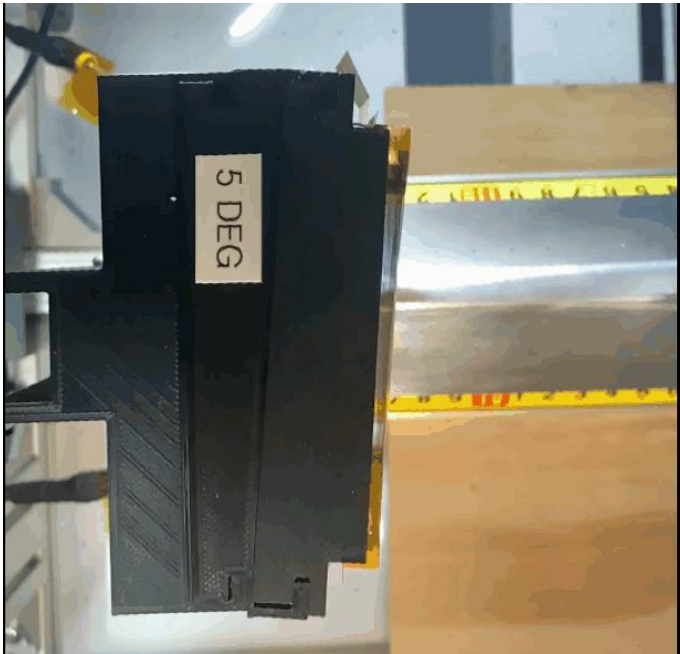
Average Capture Velocities of Different Substrates at 0° off angle



Average Capture Velocity at 5° Off Normal



# Velocity Capture Video



- Direction of motion is linear, allow us to understand the behavior of the flexible pads when it approaches with off-normal angles (e.g.  $2^\circ$  and  $5^\circ$ )
- Image shows eTAP pad conformance at an off-normal angle of 5.

# Applications

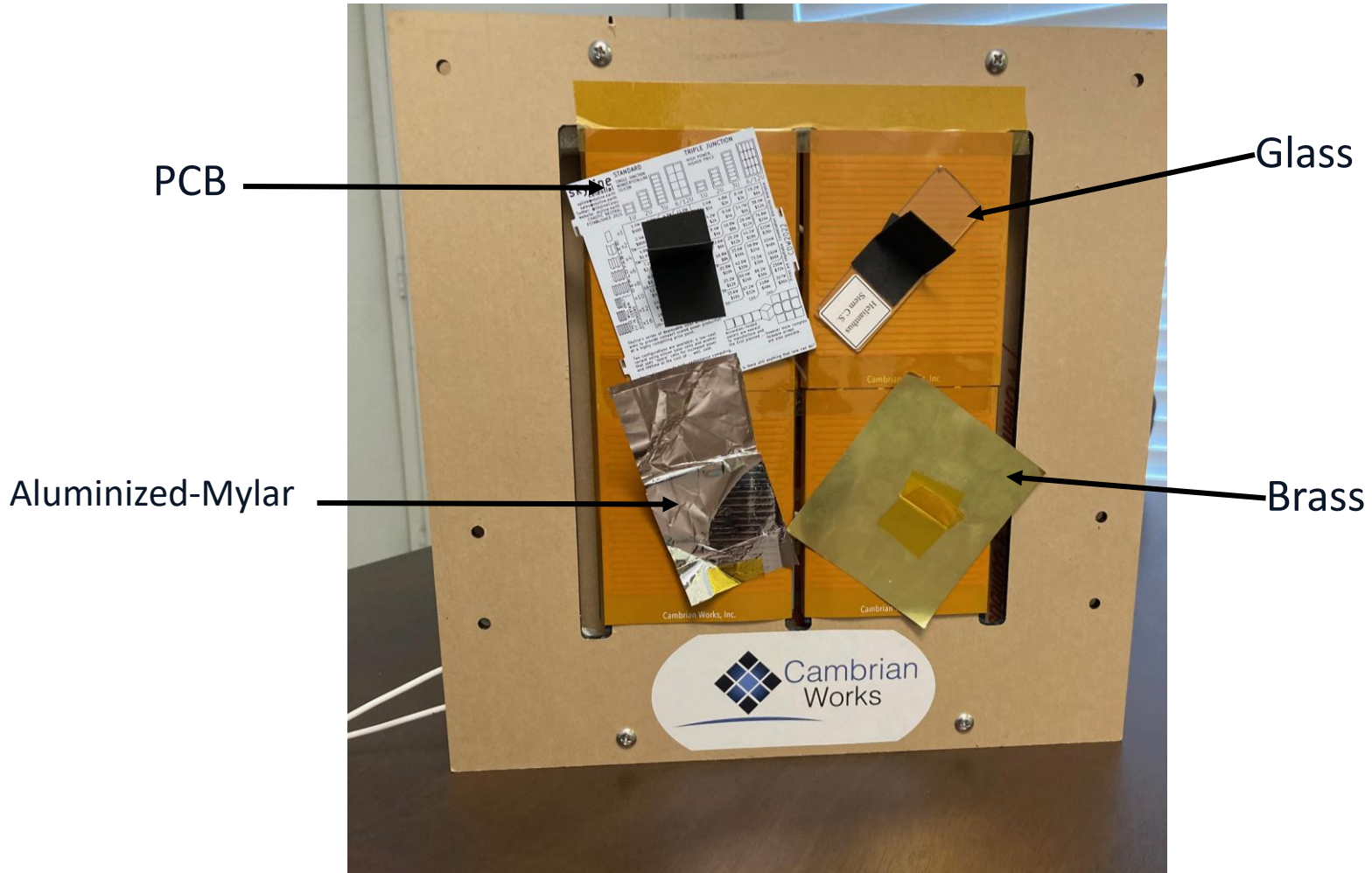
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# eTAP™ Useful for a Wide Variety of Applications



- **Unprepared / Non-Cooperative Docking**
  - First soft capture
  - Repeatable release and redock
  
- **Generalized Workspace Management**
  - Tool and component management (eTAP wall™)
  - Workspace augmentation (camera mounts, anchor points, etc.)
  
- **Tele-Robotic and Servicing Assistance**
  - Attractive “touch” – pull objects in, and absorb incoming momentum
  - Augment existing mechanical graspers for in-space assembly

# eTAP™ Wall – Come Try It Out!



A Micro-Gravity Workspace

# Questions?

# Thank you!

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