



Design, Testing, and Operation of a Beacon Laser for a Portable Satellite Laser Communication Ground Terminal

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- Presentation Overview
- CLICK Mission and Optical Ground Station (PorTel)
- 2. Beacon Laser Design + Implementation
 - Electronics
 - Software
- 3. Testing & Safety
 - Electrical
 - Optical
- 4. Lessons Learned







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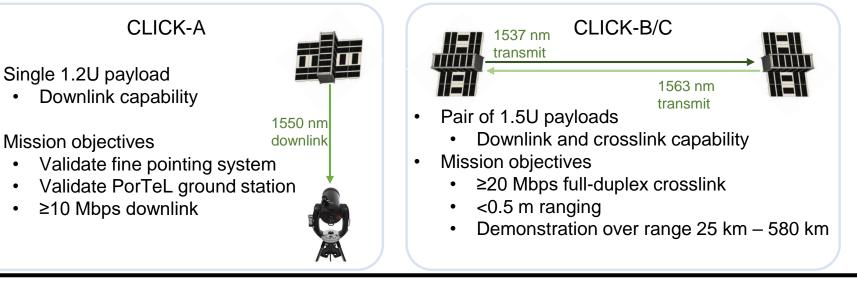
CLICK Mission



- CubeSat Laser Infrared CrosslinK (CLICK)
 - Demonstration of optical communication
 - **3U CubeSats**
- Portable Telescope for Lasercom (PorTel)
 - **Custom Optical Ground Station**
 - Built with 28 cm commercial telescope

See CDW '23 talk by Peter Grenfell "On-Orbit Operations and Lasercom Experiment Results for the CLICK-A Mission"

See thesis by Jacob Harburg "On-Orbit Operations and Lasercom Experiment Results for the CLICK-A Mission"



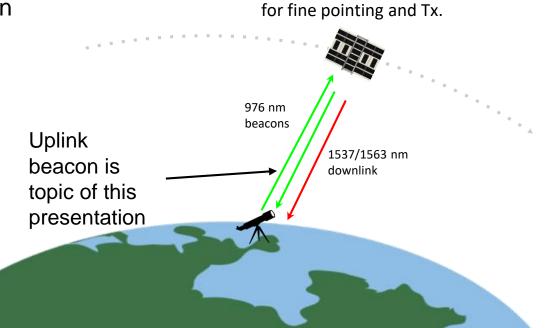




- Spacecraft needs to point at ground station and ground station at spacecraft
- Data laser FWHM (B/C) is 121 µrad

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- Challenging for open loop pointing (bus uncertainty and TLEs become stale)
- Solution: Achieve initial pointing with beacon



Acquire ground beacon

Beacon Board

Mounting Location

Beacon Requirements / Challenges

- 5 Watts peak optical power
 - 5000x safe level for invisible wavelength
- Form factor compatible with mounting on PorTel
 - ~100s grams
- Modulation with 3 kHz sine
- Temperature regulation for outside environment + laser temp stability

Together these requirements necessitate a custom implementation

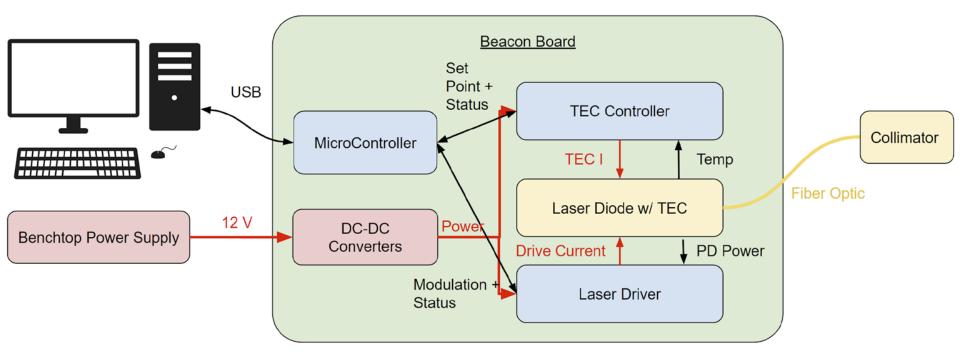
















Laser Diode

Gooch & Housego EM336

- 5 W
- Multimode fiber coupled
- Integrated TEC

Collimator

Thorlabs ZC618APC-B

- Adjustable focus
- APC Connector

Microcontroller

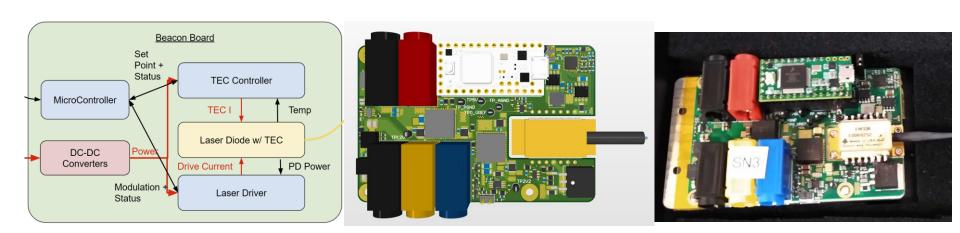
PJRC Teensy3.2

- Integrated DAC/ADC
- Small form-factor
- Arduino IDE supported





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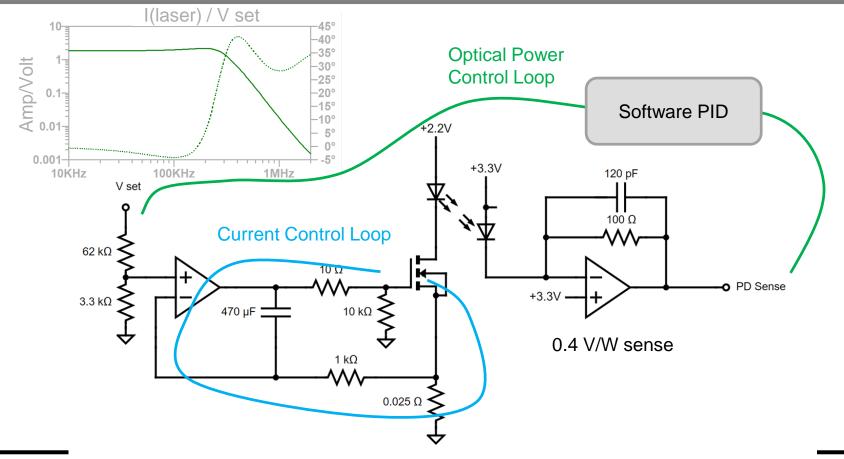


https://github.com/MIT-STARLab/PorTeL-Beacon



Laser Driver

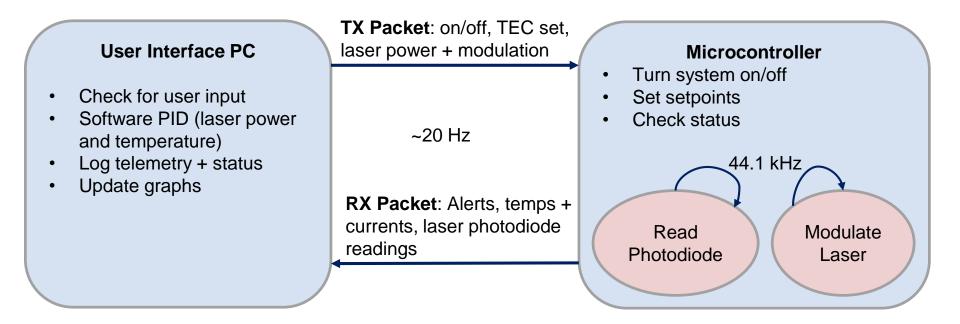






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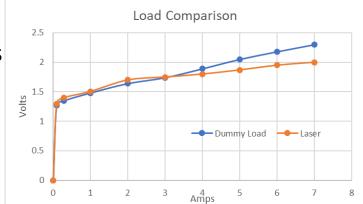
https://github.com/MIT-STARLab/PorTel-Beacon-sw

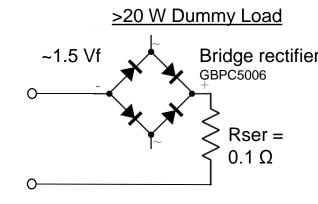






- Incrementally verify system
- Mitigate safety risks to laser diode and operators
- Start with PCB without laser installed, verify electronics
 - 1. Visual inspection
 - 2. Check power supply levels
 - 3. Verify safety interlock
 - 4. Verify communication loop with user interface
 - 5. Operate system with dummy load
 - 6. Install laser, repeat operations tests with fiber beam dump
 - 7. Connect to collimator





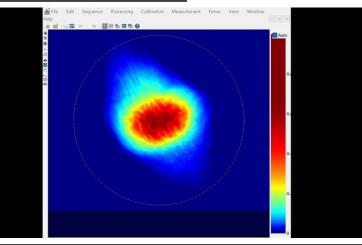


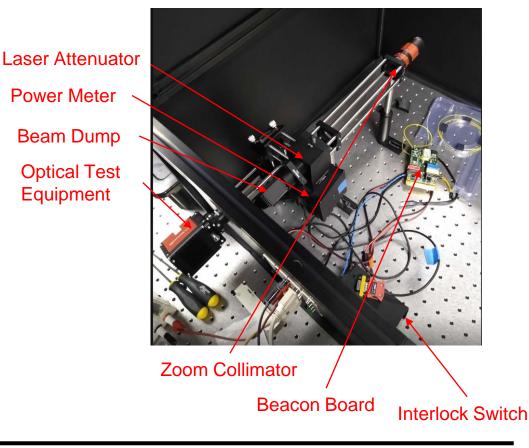
Optical Testing



- Measure optical power
- Adjust zoom collimator to 5.5 mrad FWHM
- Check profile

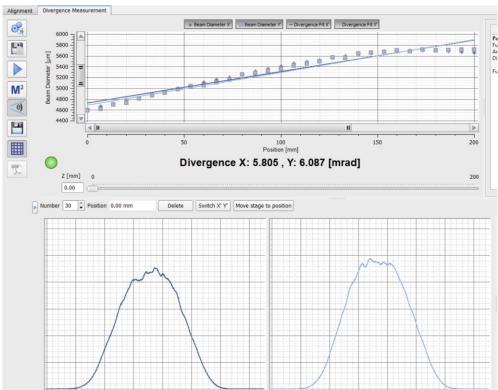
Multi-Mode Beam Profile











Screenshot from Thorlabs Beam 7.0

Parameter	Value
Divergence	5.9 mrad
Total Optical Power	4.7 W
M^2	26
Waist Diameter	2.1 mm
Rayleigh Length	70 mm
Divergence Asymmetry	1%







- 5 W, Class IV, Invisible Laser
- Safety plans made in coordination with MIT EHS

<u>Testing</u>

- OD 5+ Protective Eyewear
- Optical Box with door-interlock
- Fiber-coupled or cage-mounted optics
 - ~0.05% power into OD filter to free space and outside test equipment



Operation

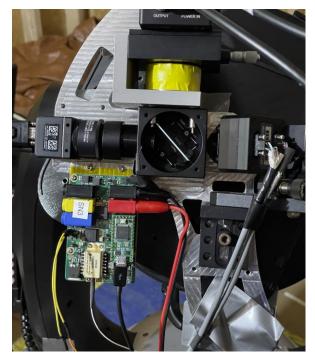
- Keyed interlock prevents operation with people inside shed
- Minimum beam elevation 20° avoids public exposure
- Optical hazard distance for aircraft is 184 ft
 - FAA Evaluated and provided a "Letter of Non-Objection"



PorTel Integration



Beacon Board on PorTel Backend



Collimator mounted to front of PorTel



Optical Ground Station Shed





CLICK-A Operations



Operators with PorTel



Video of Tracking Satellite Laser from Ground







- It is difficult to independently check optical power output in the field
 - Need to be able to trust interface
- It is very difficult to measure divergence with long Rayleigh length
 - Long free space optics create safety hazards
- Expanding the beam into a large aperture would eliminate the need for some of the safety-imposed operation limits
- Operation software should include hooks for scripting





- Optical communication yields improved data rates for small SWaP form factors, but requires challenging pointing
- One method to achieve fine pointing is a large beamwidth beacon
- The CLICK beacon is a custom electronics system built around a commercially available laser diode component
- This beacon was used for the CLICK-A mission and will be used for CLICK-B/C







Software GitHub: https://github.com/MIT-STARLab/PorTel-Beacon-sw/tree/api

Questions?

Nicholas Belsten Email: nbelsten@mit.edu

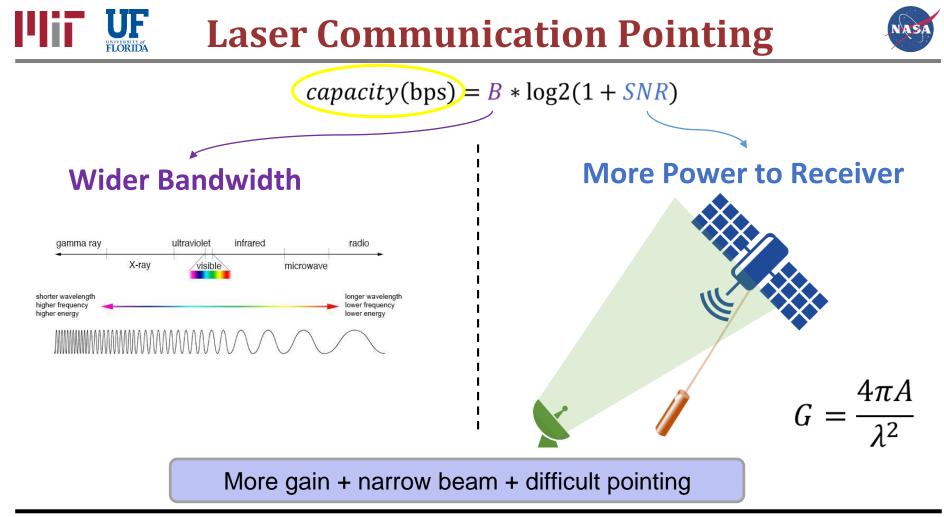


Hardware GitHub: https://github.com/MIT-STARLab/PorTeL-Beacon





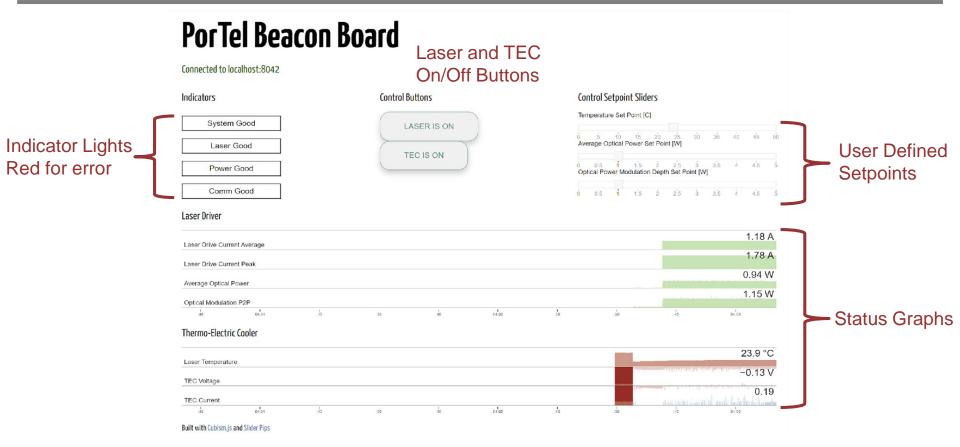
Backup





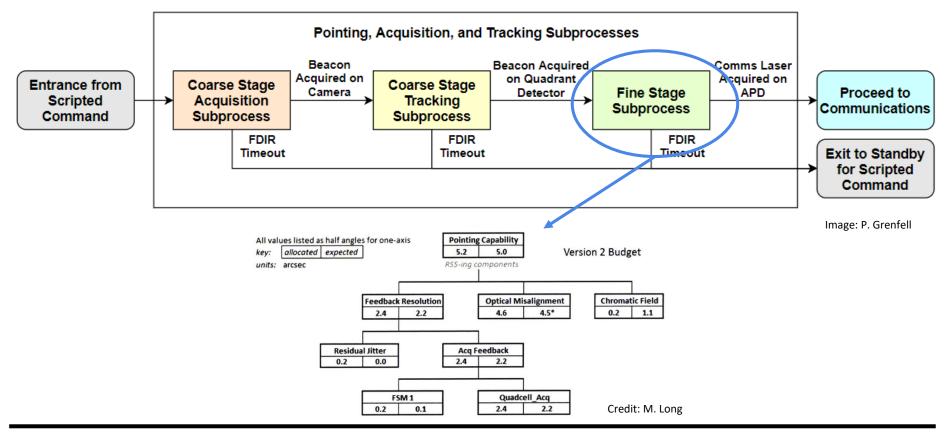


















[1] Grenfell, Peter, et al. "Pointing, Acquisition, and Tracking for Small Satellite Laser Communications." Proceedings of the AIAA/USU Conference on Small Satellites, Advanced Concepts I, SSC18-WKI-01. 2018.

[2] Riesing, Kathleen Michelle. "Portable optical ground stations for satellite communication." PhD diss., Massachusetts Institute of Technology, 2018.

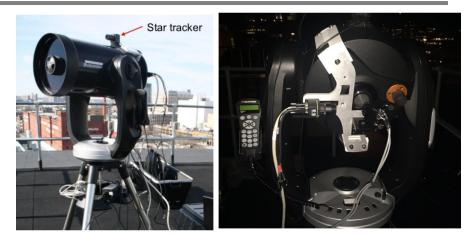
[3] Riesing, K. M., Yoon, H., & Cahoy, K. L. (2018). Rapid telescope pointing calibration: a quaternion-based solution using low-cost hardware. Journal of Astronomical Telescopes, Instruments, and Systems, 4(3), 034002.

[4] Čierny, Ondrej, and Kerri L. Cahoy. "On-orbit beam pointing calibration for nanosatellite laser communications." Optical Engineering 58.4 (2018): 041605.

Optical Ground Terminal



- MIT-developed Portable Telescope for Lasercom (PorTeL)
- Based on Ø28 cm Celestron CPC1100
- Fitted with a custom backend & star camera
- Rapid setup and pointing calibration based on star camera quaternion solution (<15 min)



Credit: K. Riesing [2,3]

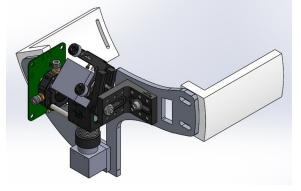


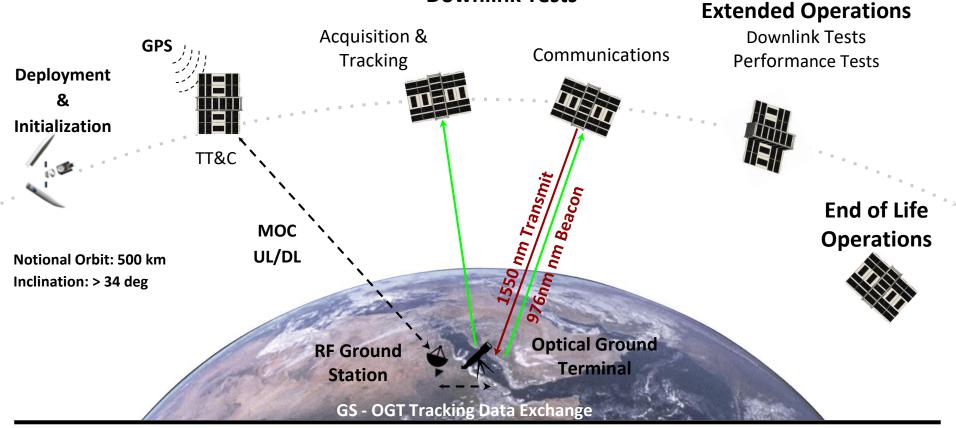
Image: T. Sevigny



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Downlink Tests

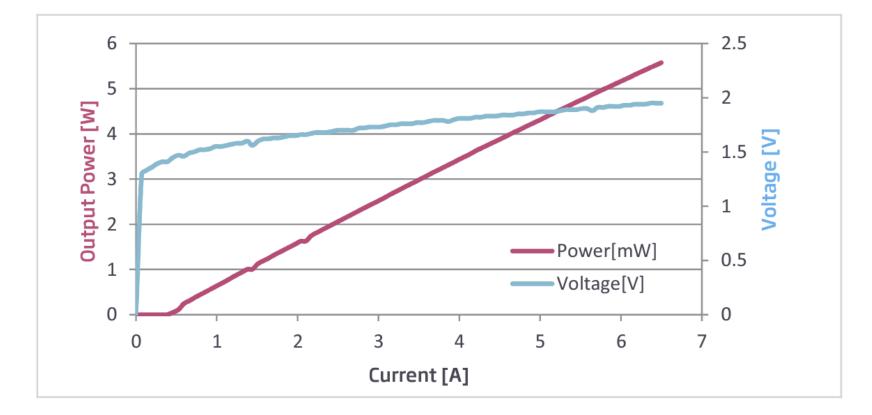


PorTel Beacon Laser CDW 2023

Beacon Laser Power Curve

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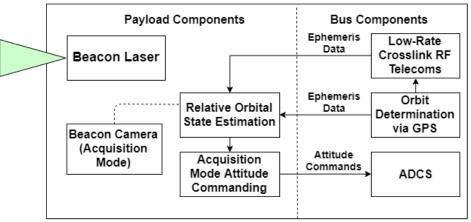




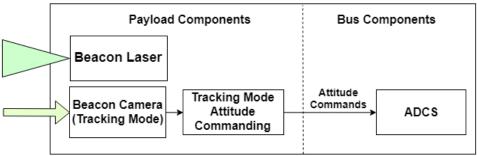
CLICK B/C Coarse PAT



Coarse Stage Acquisition Subsystems



Coarse Stage Tracking Subsystems



Images: P. Grenfell