

SWARM-EX Educational Programs in the Development of a Collaborative CubeSat Swarm

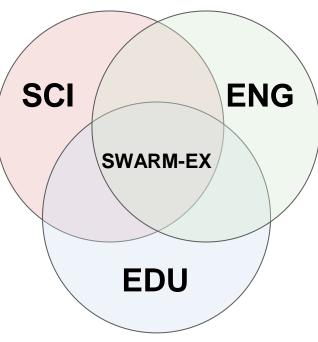
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Program Goals

- Persistence and correlation in EIA/ETA features
- Changes in EIA/ETA features that occur over timescales of <90 minutes



- Formation flying
- Collision avoidance
- Detach & reconnect
- Propulsion
- UHF crosslink
- CDMA downlink

- Intercollegiate CubeSat Mentoring Program
- CQ Slack channel
- Efforts to track student engagement/progress



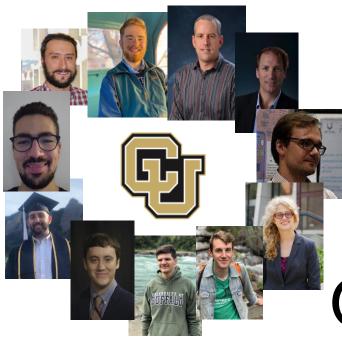


Multi-University Collaboration

- Six institutions: The University of Southern Alabama (USA), Stanford University (SU), The University of Colorado Boulder (CU), Georgia Tech (GT), Olin College, and Western Michigan University (WMU)
- The SWARM-EX mission provides a unique opportunity for STEM education and allows for cross-institutional mentorship between experienced and new CubeSat programs











Our Team











Georgia Tech















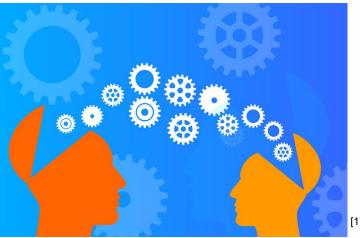






Current Efforts

- Providing cross-institutional \bullet mentoring activities
- Development and implementation • of a repository for CubeSat knowledge and expertise
- A survey of student participants
- Seminar Series







Cross-Institutional Mentoring







Surveys

- Four Surveys
 - Demographic
 - Entry
 - \circ Annual
 - Exit





During your participation in SWARM-EX in the last year, which three subsystems were you most involved in?



Survey Purpose

- Identify and track students technical capabilities and CubeSat knowledge levels throughout their time working on the SWARM-EX project
- The outcome of surveys is to gain a better understanding of what participants bring and take away from the project

Which of the	e following	most	accurately	describes	your	major fie	eld of
study?							

O Aerospace Engineering	
O Business	
O Civil Engineering	
O Computer Engineering	
O Computer Science	
O Electrical Engineering	
O Engineering Physics	
O Industrial Operations	
O Math	
O Mechanical Engineering	
O Physics	

	1: Most involved	2: Second most involved	3: Third most involved
Attitude Determination and Control System	0	0	0
Command and Data Handling	0	0	0
Communications	0	0	0
Electrical Power System	0	0	0
Guidance Navigation and Controls	0	0	0
Ground Station	0	0	0
Integration and testing	0	0	0
Operations	0	0	0
Propulsion	0	0	0
Science instrument	0	0	0
Structures	0	0	0
Systems	0	0	0
Thermal	0	0	0
Education & Public Outreach	0	0	0

What skills have you gained while working on SWARM-EX regarding small satellites? (Check all that apply)

SolidWorks, Ansys, or other structural modeling software	Altium & Eagle
MATLAB, Python, or other coding software	Embedded Systems
Electronics assembly, such as soldering	Electromagnetic Design Software
Electronics troubleshooting	Engineering Design
Thermal Desktop	Version Control GIT & SVN
How to develop a Requirement Verification Matrix (RVM)	Other



Space Science
 Other



slack

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Launching Cubesat Questions

of Engineering

Current CubeSat Resources & The SWARM-EX CubeSat Slack Channel

Search small satellite information .	Q	
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Ve make it easy to build CubeSats.		
	Gedati was bulit te empower students who are buliding satellities. We give your team time basit, to fearur an exercitive satellitig profession. Menorizate attendition buliding foreitant, the anting particular menorizate attendition buliding foreita, the anting particular segments is due to every particular, locating, sectorements.	NASA CubeSat Launch Initiative for Adde Waters - Neuron Band Charler 2007



CubeSat Slack Channel

- The CubeSat Questions Slack Channel introduces students and new CubeSat teams to experts and experienced teams
- Subject matter experts from 16+ universities
- Total Members: 98

































Georgia

Tech











My name is Max, and I am with Western Michigan University's satellite team where we are developing a 6U Cubesat. As we have been developing our flight software, some questions have come up. We are looking for information that would apply for a general/conventional LEO CubeSat mission. My questions are as follow:

1. When considering GPS telemetry and housekeeping data collection (component voltage/current/temperature reading, battery health data, etc.) while the satellite is in orbit, what is a typical time interval for collect that data? Once every 10 sec.?, 30 sec.?, 5 min.? And on the same note, what is a typical time frame for downlinking that data? Once an orbit?, Every chance we get? We understand that every mission will have different downlink and data collection requirements, but is there a general baseline we can build off of?

2. What is typically done by Cubesats directly after leaving the deployer? Is there a switch that triggers activation of the satellite after leaving the deployer? Is there an order of operations that a Cubesat follows for initial system checkouts/detumble/battery charging/downlinking?

7 months ago

7 replies

We usually take those readings once every < 10 seconds. I think we've done 1 and 3 seconds before and that's been a comfortable rate. With UHF downlink only, there's usually not enough bandwidth to downlink all of that so we set things up so that we can easily request "decimated" data, e.g., just one sample every 10 minutes. It all stays onboard for months so we can always go back and request higher cadence data if needed.



7 months ago

- 2. There's usually a period of time required by the launch provider that the CubeSat can't do any deployments or radio transmissions (e.g., 30 minutes). The deployers usually have requirements for where to put the switches in your CubeSat (in a foot or along the rails) that keeps your CubeSat powered off inside and as soon as the switch releases as it exits the deployer, the CubeSat powers on and starts its software timer for deployments and radio transmissions (beacons). Detumble can occur right after deployment I believe, but we usually don't trigger that until the timer completes either. That means its important to make sure your spacecraft is power positive during a tumble in its lowest power consumption mode. The order of operations that we've usually followed is:
- 1. deploy CDH and EPS power up, X minute countdown timer started
- 2. timer completes
- 3. deploy antennas and begin beacons every ~10 seconds
- 4. (optional) 30 seconds later or so autonomously deploy solar panels (alternative option is that this can only be commanded from the ground but we've always opted to do it autonomously)
- 5. Aside: Repeat 3-4 every -60 minutes or so until ground contact is established and a special command sent to disable the repeated deployment attempts
- 6. a minute or so later, begin periodic checks of battery voltage to determine if there's enough charge to auto-promote to nominal safe mode, which among other things, powers on ADCS and let it run its detumble algorithm and establishes coarse sun pointing
- 7. hopefully ground contact has been established at this point and commissioning can begin
- (edited) <u>↓</u>1 ©[†] 7 months ago Thank you, this is very helpful
- 7 months ago
- Others may have different approaches but that's worked for us for a few that have flown already

Read Read 7 months ago With regards to the data collection cadence you should consider the rates at which the signals change. For example making a thermal measurement every minute is probably sufficient, but it can be annoving to have to record data at different data rates so you may record temperature every second because that is the sample rate used for current and voltage measurements. Additionally storage is cheap so you can sample fast but only downlink a small subset of data as needed and you would have high rate data available if needed for anomaly troubleshooting 📥 1 🤤

- Student from Western Michigan University asking questions on GPS telemetry, housekeeping data, and CubeSat deployment
- They received responses from experts with detailed • explanations







CubeSat Knowledge Documents

- Academic Material: Lectures and Webinars
- Frequently Asked Questions Document
- Getting Started Document for CubeSat





Seminar Series

- The seminar series is a set of lectures covering various topics put on by members of the SWARM-EX project allowing students' to participate in discussions on topics which interests them improving their general knowledge in applied STEM
- Upcoming Topic: In-situ measurements and science instruments & SWARM-EX Presenter: Dr. Marcin Pilinski instrumentation
- **Previous Topics**
 - CU-E3 CubeSat Mission Ο
 - Academic Journey and Past Research Projects Ο
 - Application of Engineering Principles to Army/MFO Operations in Eqypt Ο



Presenter: Brodie Wallace

Presenter: Dr. Scott Palo

Presenter: Shane Lowe



Future Work

- Cross-institutional mentoring
- The CQ Slack Channel will continue to be open to additional groups and institutions
- Completing of surveys
- Continuing of seminar series





Questions?





References

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