# CONNECT

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Cooperative Node Network Command Test Patrick Anselmo Donovan, E.I.T. - Space Cooperative, Inc.

#### Today's Presentation

1. Our Mission

2. Current Progress

3. Next Steps

4. Q & A

## "Going to Space, Together."

#### How will it work?

Our goals:

reduces cost

lowers barriers to entry

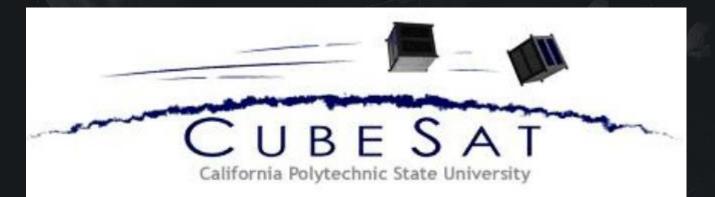
promotes user-friendliness

enables new types of missions

supports existing community

#### Affordability

#### Preaching to the choir, a.k.a.

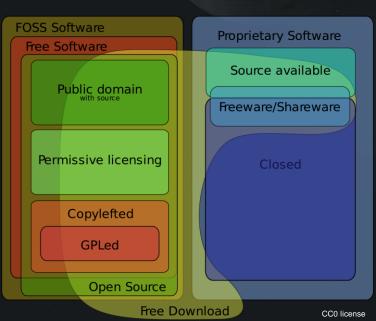


#### Lowering Barriers to Entry

Open-source licensing Code publication

Collaborative design on our (in development) Platform

SPACE



#### Lowering Barriers to Entry - with our Platform

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#### GOING TO SPACE, TOGETHER.

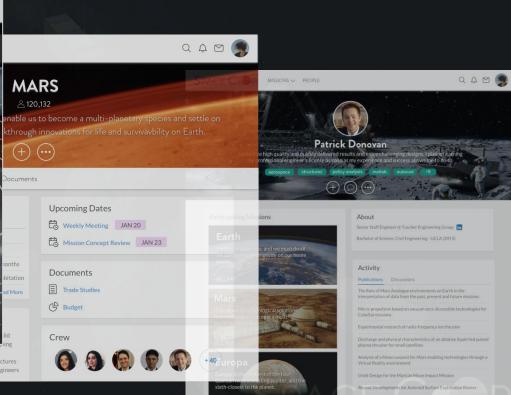
Most of us dream of a future where Earth is a better place and where we have traveled outside our solar system. We are creating a social collaboration platform where we can work on these shared dreams together.



If we develop technological solutions that enable us to become a multi-planetary species and settle on Mars, we will then in parallel have breakthrough innovations for life and survivaxbility on Earth.

≗ 120,132

elegant, large scale, hemispherical architectures can challenge both engineers





#### Ease of Use

To transform mission control from this...



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#### **Enabling New Mission Types**

Inspections

Prospecting

Support



artist credit: NASA S114-E-6642

#### Supporting Existing Community

### Enthusiasts & students





Scientists & other professionals

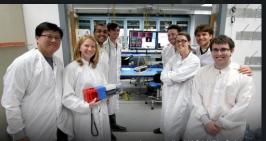


photo credit: NASA/JPL-Caltech

### Current Progress

#### Step 1: Simulate

Physics: Anaconda distribution of Python 2.7

Models: Autodesk Inventor

Animation: Unity

Data Output: csv



#### Fundamental Swarm Rules

Collision avoidance Maximum swarm diameter Minimum allowable swarm distance



#### Physics: Hill-Clohessy-Wiltshire

Pros:

- 1. Conceptually simpler
- 2. Faster computation
- 3. Local linearity
- 4. Flexible to future perturbation models

1. Long-term error

Cons:

2. Limited to operations in gravity wells

#### Step 2: Estimate

Assume: all current COTS hardware and software Primary focus on: **Movement** propulsion attitude control Communications inter-drone ranging/ remote sensing **Command input** 

#### Step 3: Iterate

#### Step 4: Grow

Are you passionate about living in space and cooperation? The following experts are highest in demand for our immediate trajectory:

**Space Mission Engineers** 

Software Developers

Interaction Designers ITAR Compliance

Please talk with me afterwards, email <u>curious@space.coop</u>, or visit <u>www.space.coop/membership</u> for more details!

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#### Fellow Space Co-op Team Members

## Q & A