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A Testbed for Demonstration and Performance Analysis of an Autonomous Scheduling System for Communications Nanosatellites

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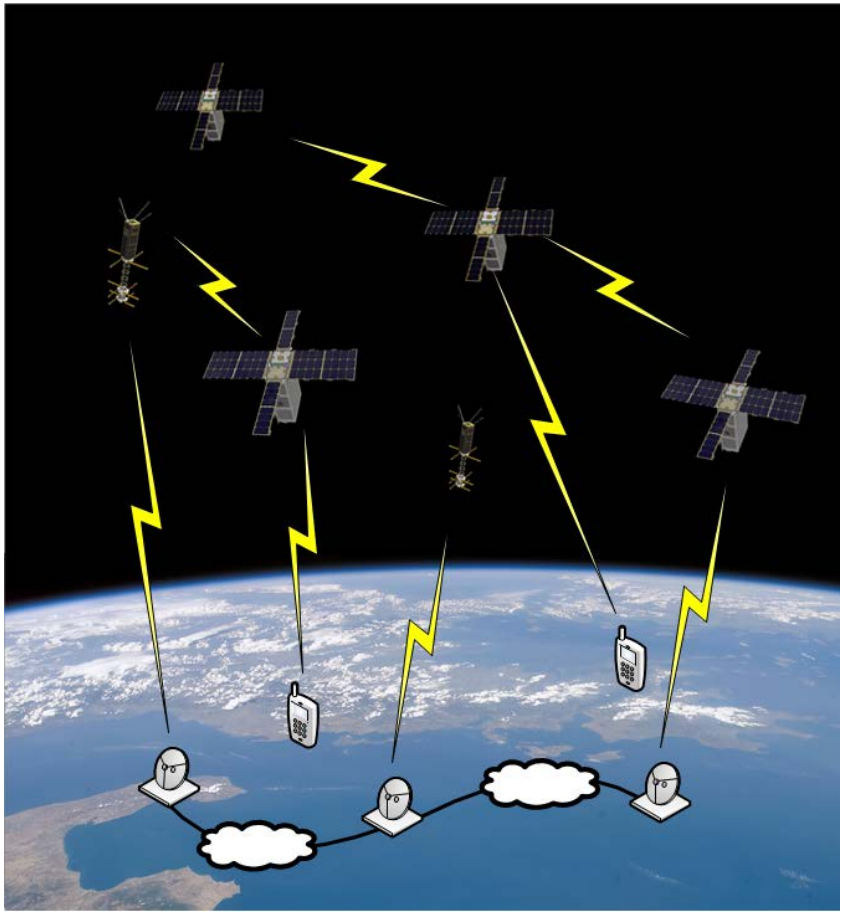
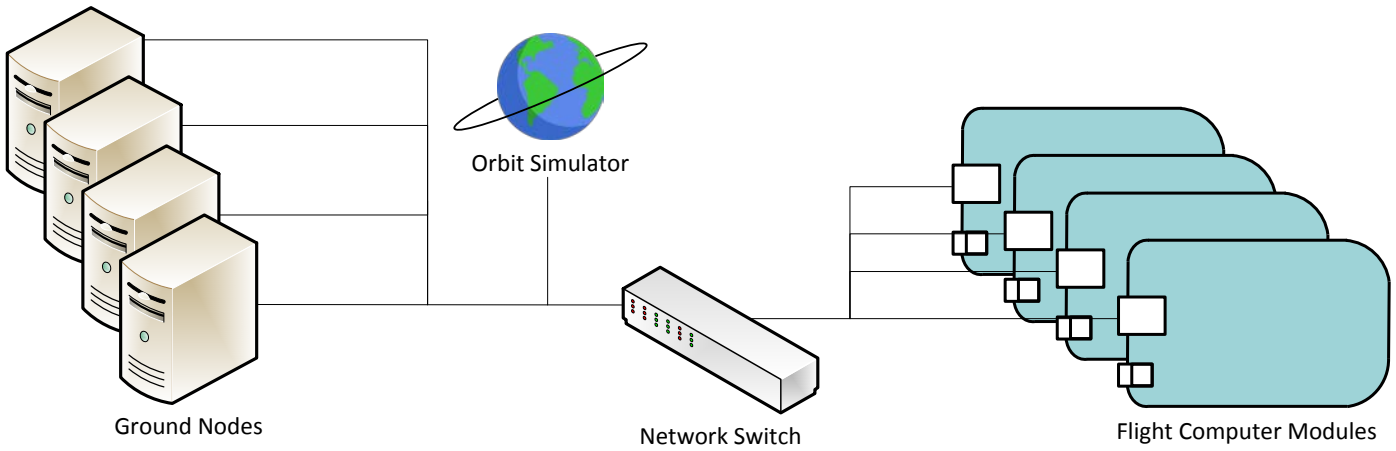
Need: Mission-level Hardware testbed



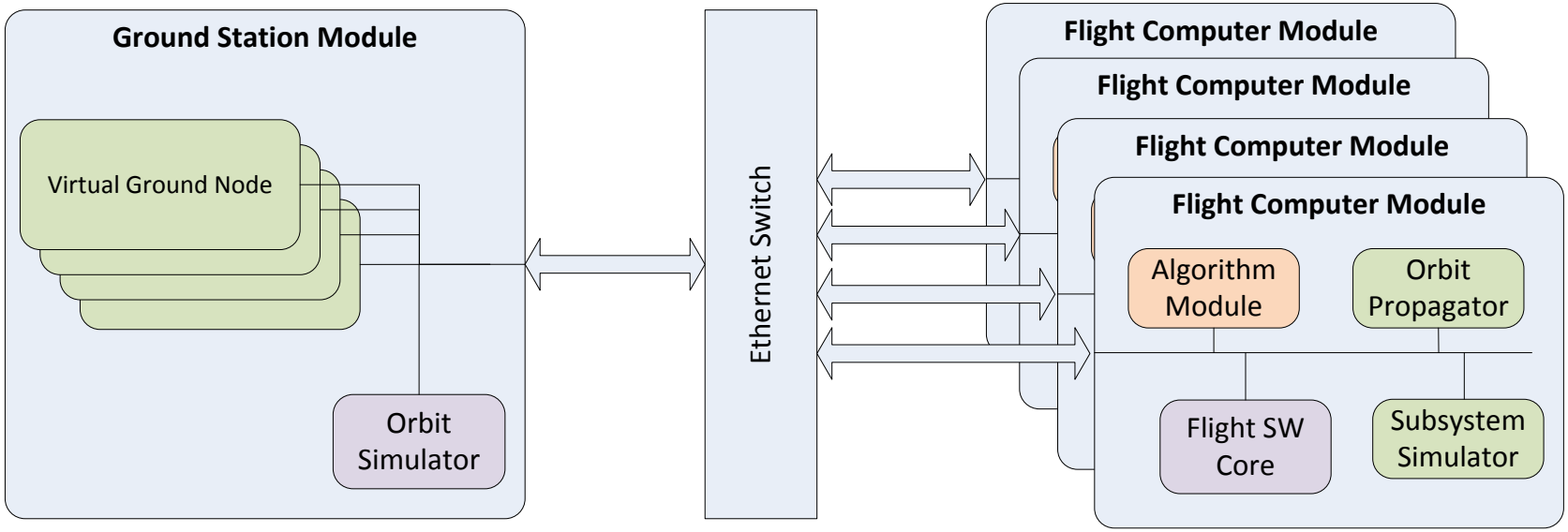
- Software-in-the-loop (SITL) modeling and simulation has limitations
- No low-cost Hardware-in-the-loop (HITL) M&S tool to test/simulate mission scenarios
- Flatsats / ground testbeds can only simulate individual nanosatellites

Proposed Solution

- Create a low-cost, mission-level simulation environment using Commercial-Off-The-Shelf (COTS) hardware
  - Hardware-In-The-Loop (HITL) nanosatellite constellation testbed
  - Open source, industry standards and existing flight software
  - Graphical User Interface (GUI) for input parameters and analysis output
- Demonstrate autonomous algorithms using the testbed



Nanosat Communications Constellation Testbed Architecture

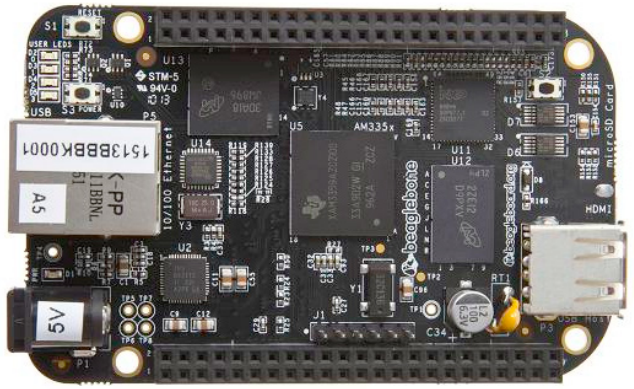


- **Virtual Ground Node** – Simulates ground stations in different geographic areas and hosts GUI and module for automation and optimization algorithms
- **Orbit Simulator** – Provides orbit information for a given mission
- **Flight SW Core** – Provide services for sending commands / receiving telemetry
- **Orbit Propagator** – propagate position and velocity of a satellite
- **Subsystem Simulator** – Simulates battery, solar panel, attitude control, gps receiver
- **Algorithm Module** – User-defined automation and optimization algorithms

Nanosat Communications Constellation Testbed Design

Hardware Implementation

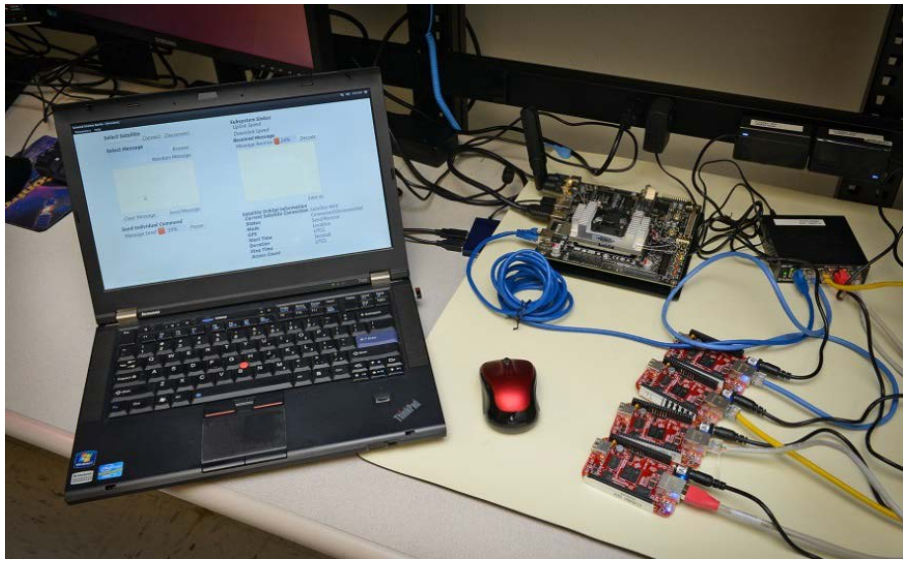
- 1 x Workstation
- 4 x BeagleBone Black (BBB)
- 1 x Ethernet switch (8-port)



*https://beagleboard.org

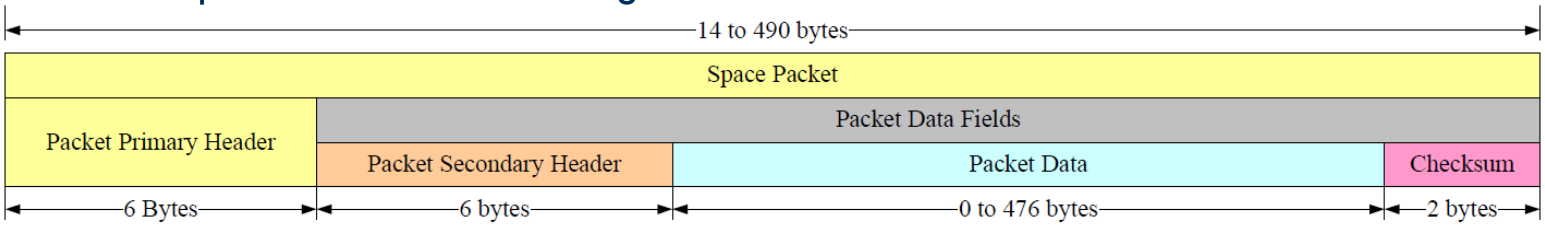
Software Implementation

- Flight Software developed for DoD 6U nanosat bus
- VMware with Ubuntu
- Python IDE

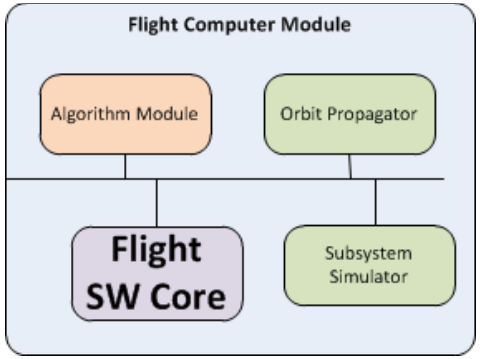


Flight SW Core Description

- Testbed uses actual flight software
- Uses Consultative Committee for Space Data Systems (CCSDS) compliant message structure called “Space Packet” for all telemetry, commands, interface control requests and acknowledgements

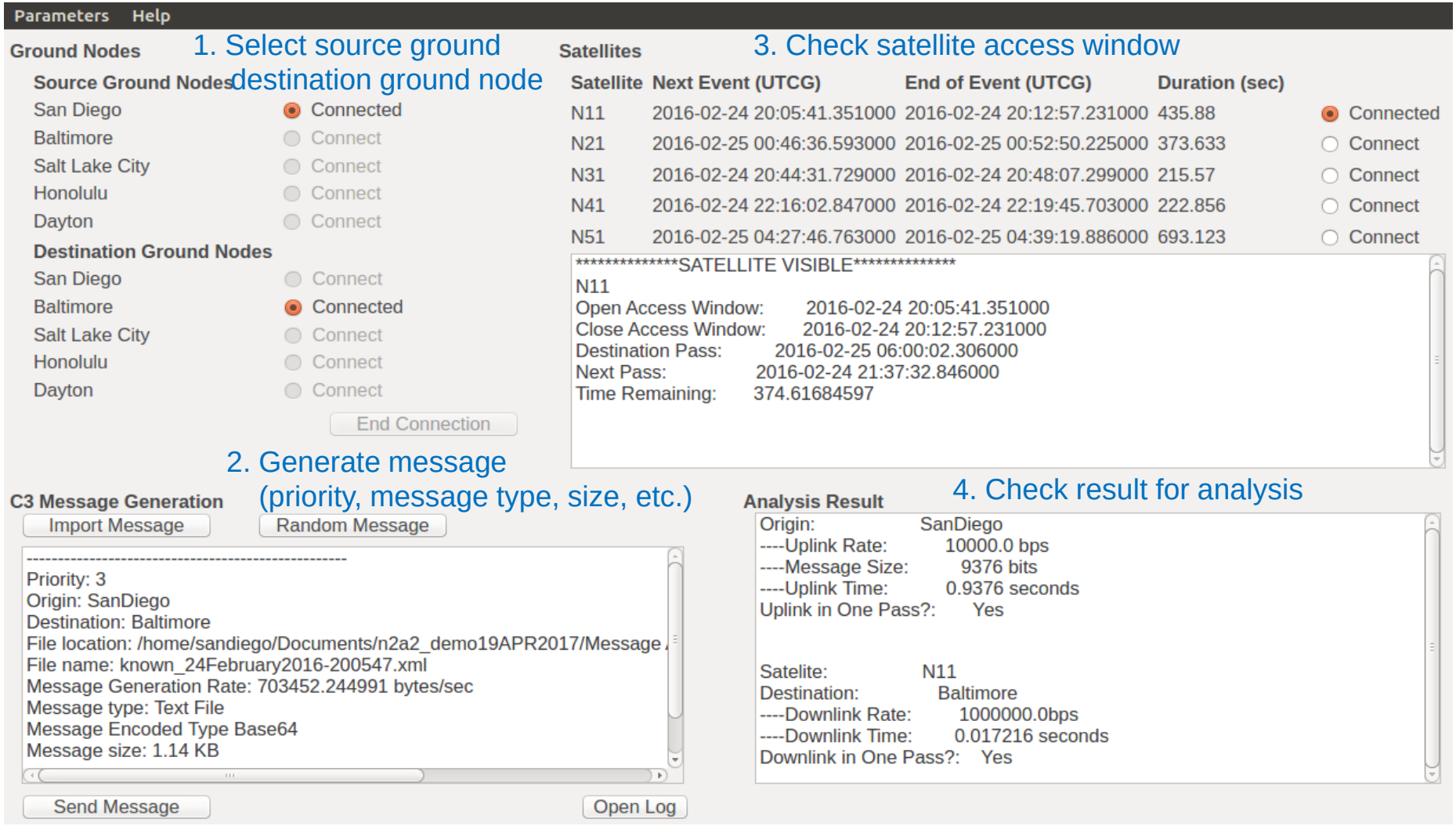


- IP-based/Ethernet interface between components including ground stations
- 9 Services* available between bus and payload including
  - Payload Command Forwarding
  - Payload Telemetry
  - Bus Command
  - Bus Telemetry Packet
  - Bus Telemetry Stream
  - Payload Data Storage
  - Payload Data Downlink
  - Payload Data Load
  - Time Service

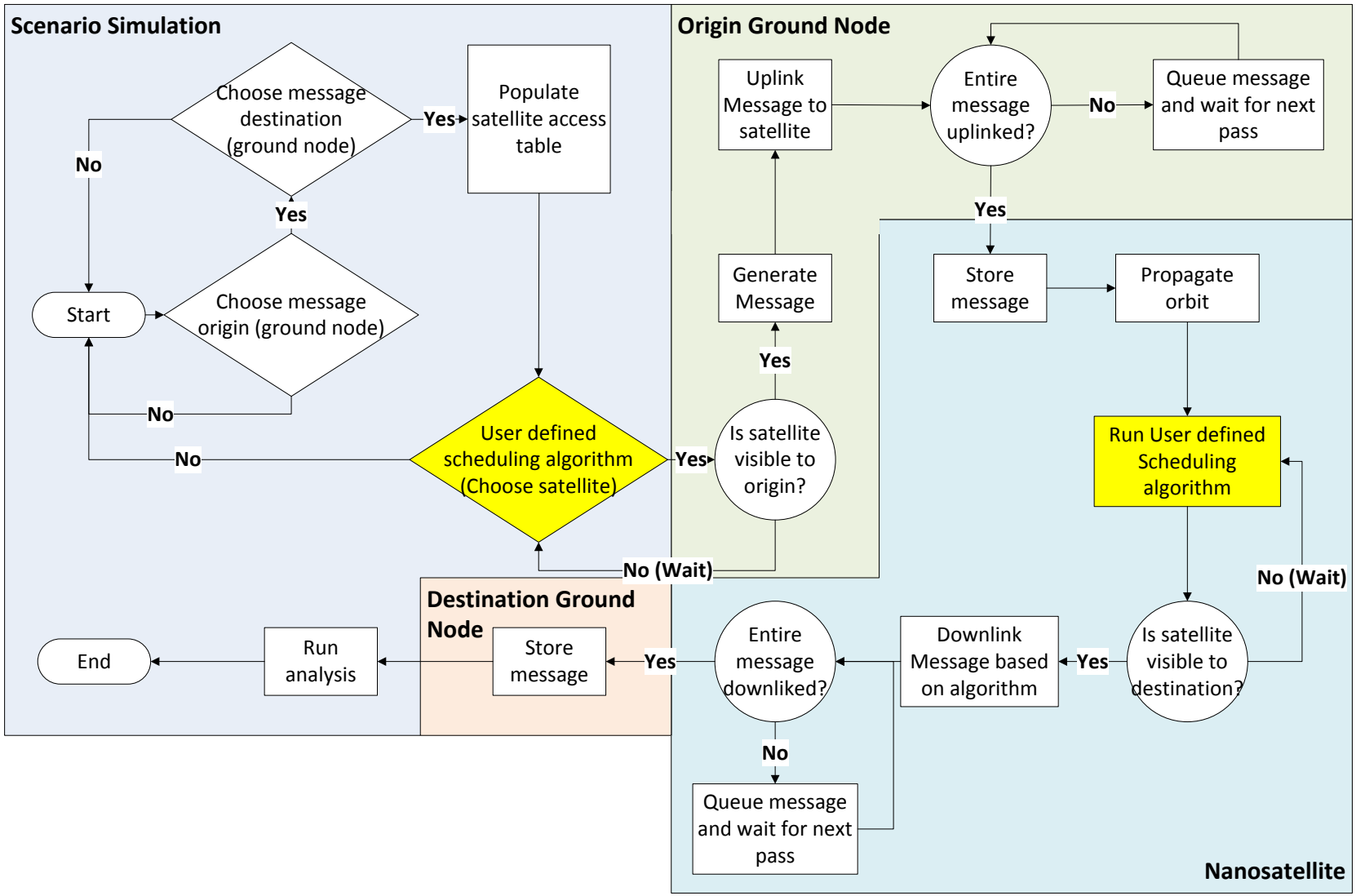


* SN-BPLICD-001 Rev 1.0 by Naval Research Laboratory

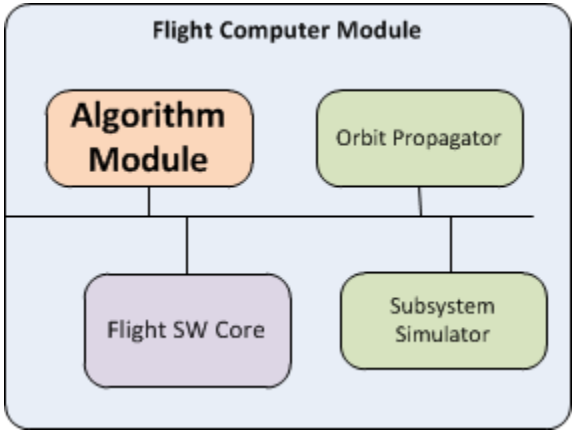
Scenario Simulation: Graphical User Interface Design Example



Nanosat Communications Constellation Testbed Message flow



Interface to Algorithm Module



- Software wrapper allows rapid implementation of user-defined scheduling algorithms
  - Provides receive and send capability between ground nodes and nanosatellites
  - Telemetry data is available for algorithm to use during decision making
- Algorithm Module provides pathway to implement optimization in the flight computer
  - Communication scheduling
  - Other event scheduling

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Summary and Ongoing Work

Summary

- Developed mission-level nanosatellite communications constellation testbed framework using COTS components
- Defined virtual ground node and flight computer module interfaces
- Developed a GUI design to help modeling and simulation
- Developed message delivery simulation test cases for evaluation

Ongoing Work

- Model a nanosat subsystem simulation module (battery, solar panel and etc.)
- Implement energy-cognizant nanosat message delivery scheduling system
- Implement MC3 ground station network model and simulation
- Demonstrate autonomous message delivery scheduling systems for a store-and-forward nanosat communication constellation using the testbed

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THANK YOU