

# DustCube

2016 CubeSat Developers' Workshop  
Cal Poly

(04/21/2016)



UniversidadeVigo



Engineering for Remote Sensing

**A 3U Cubesat to Characterize the natural dust environment and microscopic ejecta due to DART high speed impact on the Binary asteroid 65803 Didymos.**

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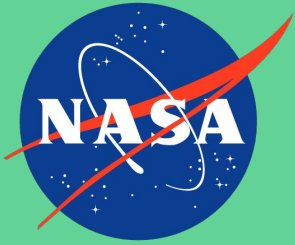
Gergely Dolgos

gergely.dolgos@micos.ch

**University of Vigo**

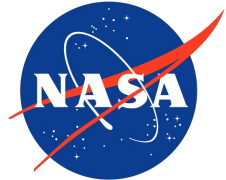
**University of Bologna**

**Micos Engineering**

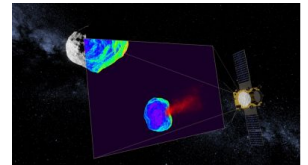
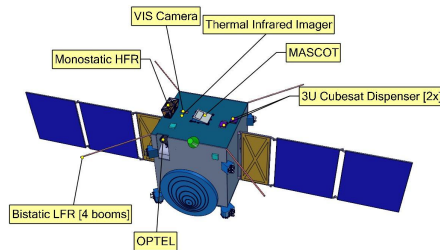
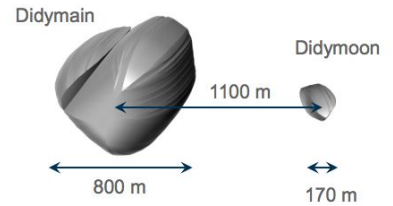
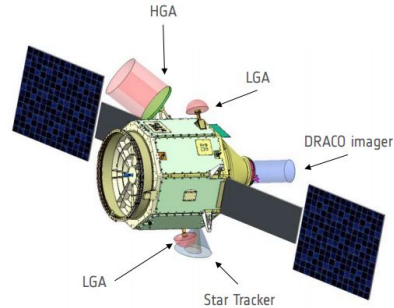


# AIDA Mission

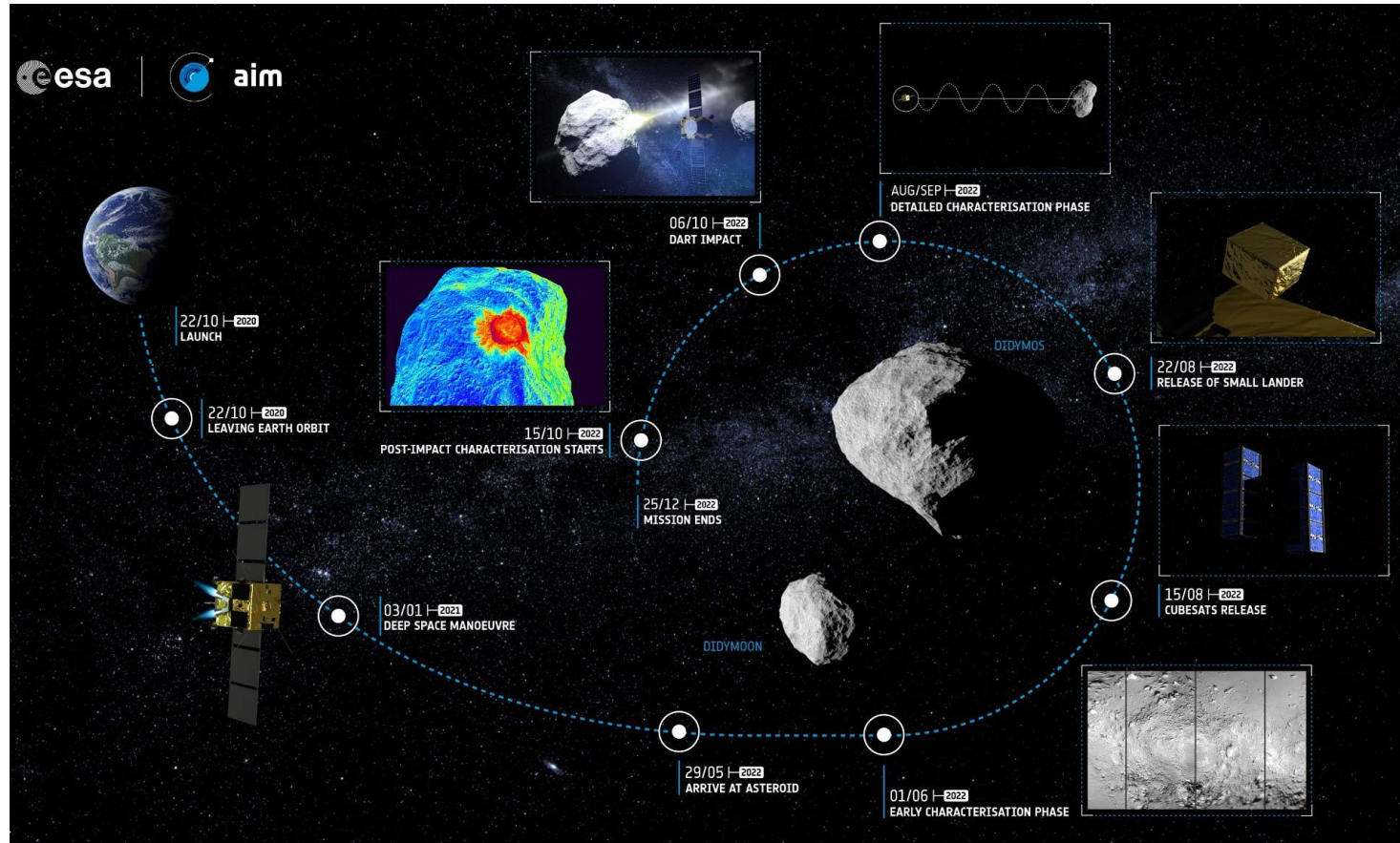
# AIDA Mission (Asteroid Impact and deflection assessment)



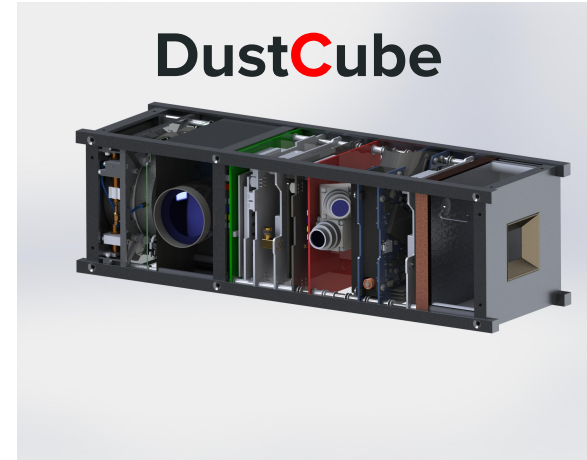
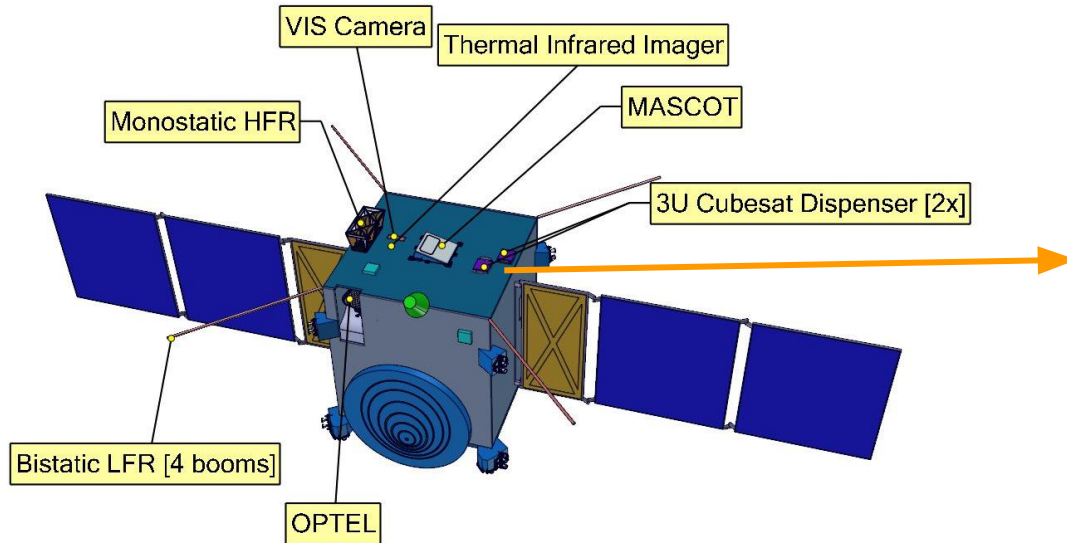
**dart** (Double Asteroid Redirection Test)



# AIM CONOPS (Concept of Operations)



# AIM (Asteroid Impact Mission)



**DustCube**  
**TEAM**

# DustCube Project Consortium

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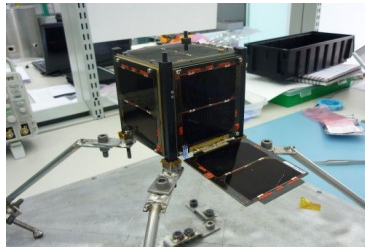
Engineering for Remote Sensing

- Orbit Dynamics
- Attitude Control Systems
- Navigation Control Systems

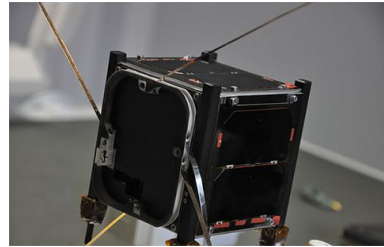
- Project Management
- System Engineering
- SC Platform
- SC Operations

- Optical Payload Design
- Scientific analysis
- Environmental Testing
- Scientific data processing

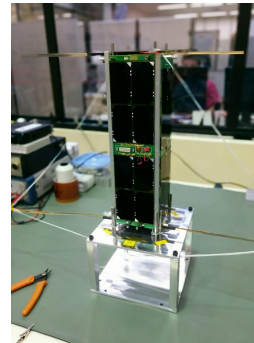
- UVIGO CubeSats Experience in 8 years: 3 CubeSats launched and operated until 2016



**Xatcobeo: 1U**  
 (Operated for 2.5 years,  
 Launched on (13/02/2012)  
**Re-Entered** on 01/09/2014)  
 Launched with **ESA Vega**



**HUMSAT-D: 1U**  
 (Operated for 1.2 years,  
**OPS Finalized** on 02/2015)  
 Launched with **Dnepr/GAUSS**  
 11/2013



**SERPENS: 3U**  
 (Mission finalized on  
**April 1, 2016 Re-Entered**)  
 Launched with JAXA,  
 through the ISS  
 19/08/2015



- On-going developments:



**FemtoXat** 1/3 U (Modular Cubesat)



**HumSat2.0 Payload:**  
 Second Generation SDR payload  
 for HUMSAT. (**End of 2016**)



**SatNet:** Open Source Ground  
 station network  
 (Final testing. **Operative on**  
**03/2016**)

- ESA ESEO Satellite - Ground Station Node
- Pontevedra **Smart City Sensors Network** deployment.
- Development of **Highly adaptable EGSE tools** for SC Testing
- Developments of **CubeSats Telemetry analysis tools**

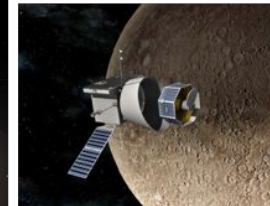
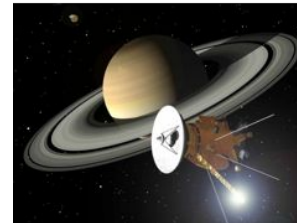
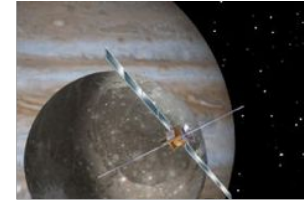
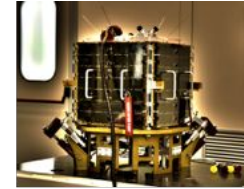


# DustCube Project Consortium (2 / 3)



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- **ALMASat (ALma MAter Satellite)**  
Demonstrator, successfully launched on February 13<sup>th</sup>, 2012
- **ESEO satellite**  
GPS Receiver and OD, as part of the payload package (in collaboration with SITAEL)  
Ground Stations design.
- **Target research areas:**  
Micropropulsion systems  
Cold-gas, flown on ALMASat-1 in 2012  
Monopropellant warm-gas, under development  
GPS Receivers and Autonomous Navigation Systems  
Ground Segment/Station Technologies and Mission Control Centers  
AODCS simulation tools
- **RadioScience Experiments**
  - Juno (NASA),
  - Cassini-huygens (NASA/ESA/ASI)
  - Juice (ESA)
  - Bepi-Colombo (ESA)



# Micos Engineering GmbH

## Company competences and SysNova team

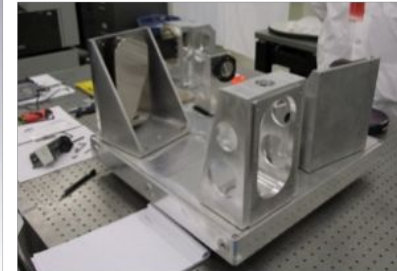
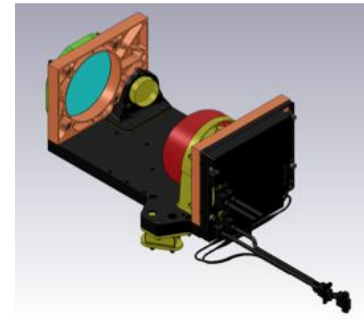
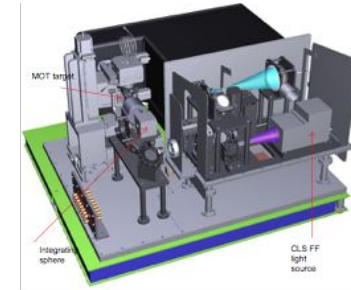
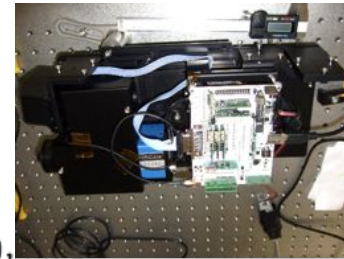


Engineering for Remote Sensing

- Operational since April 2011 ([www.micos.ch](http://www.micos.ch))
- Hosted by Empa (Swiss Materials Science Federal laboratory) incubator
- Focus on system engineering for opto-mechanical systems
- Independently owned (100% by 5 shareholders)
- 20 employees (16 engineers/physicists, 6 PhDs)
- Clean room (15m<sup>2</sup> ISO7, 45m<sup>2</sup> ISO6, 9m<sup>2</sup> ISO5), ESD lab, TVAC procured
- E.g. instrumentation for Sentinels (S4: AIT-OGSE, S5: Calibration Subsystem), COM-Blackbodies, Proba-3: High Accuracy Metrology Optical Head Unit, and technology developments such as Optical Encoders

### Micos Competencies:

- System Engineering
- Optical Engineering
- Mechanical Engineering
- Algorithms, Processing and SW
- AIT
- PA/QA



# DustCube S/C

It is a **CubeSat for deep space exploration** which main technical and scientific objectives are:

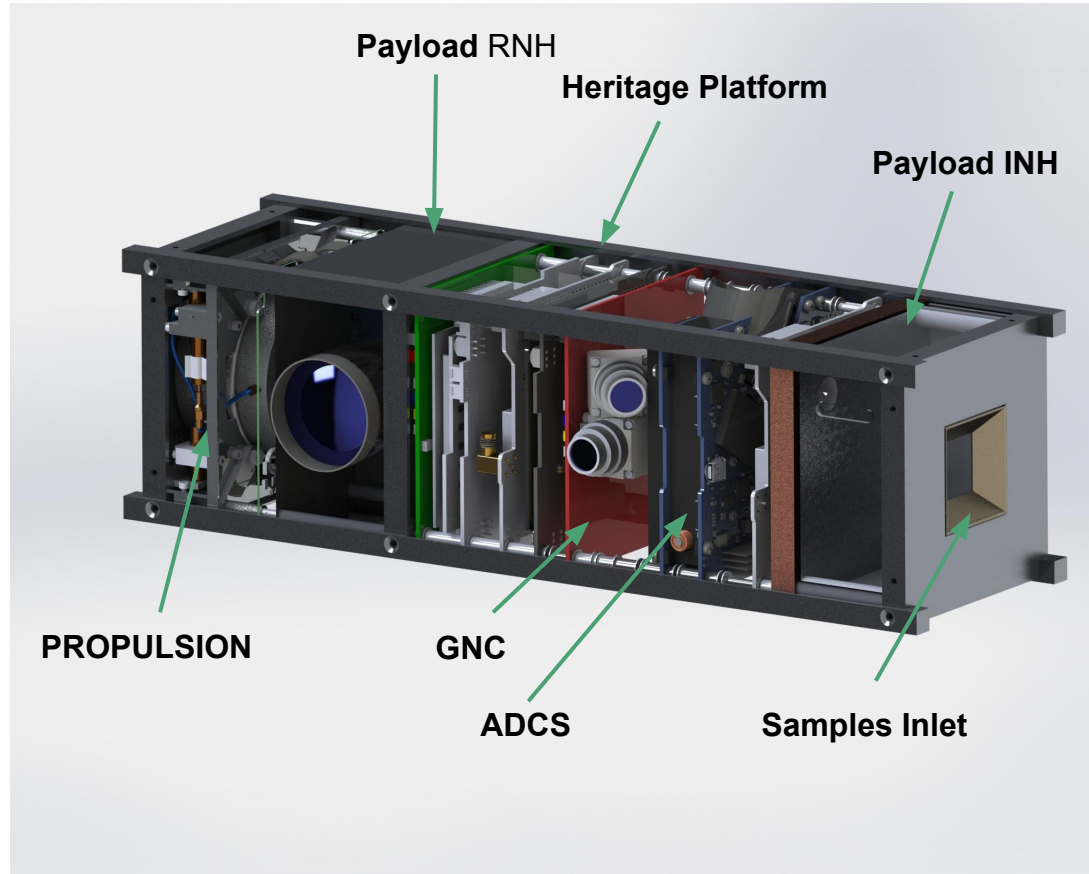
## Technical:

- **Test an Intersatellite-link** ( network of 2 cubesats + lander + AIM mother S/C) in deep space.
- **Deploy a cubesat on an asteroid vicinity.**
- **Test laser altimetry** on a miniaturized system onboard a Cubesat.

## Scientific:

- **Characterize (shape, size, speed, refractive index,etc) the asteroid particles environment:**
  - Natural environment Dust
    - **Vicinity, L4/L5**
  - Characterization of the **asteroid ejecta plume** due to DART **Impact**
    - Plume cloud physical properties (composition, size, shape, distribution)
    - Plume evolution after impact
    - Surface regolith characterization
- **Imaging** of the Didymoon
  - **Before** Impact
  - **During** Impact
  - **After** Impact

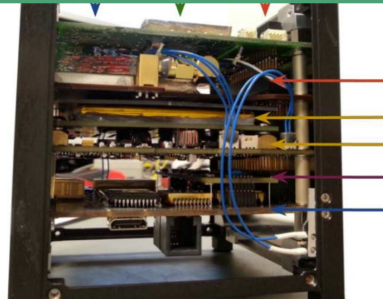
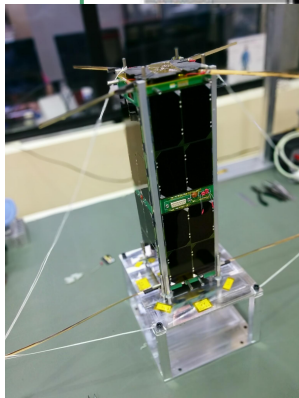
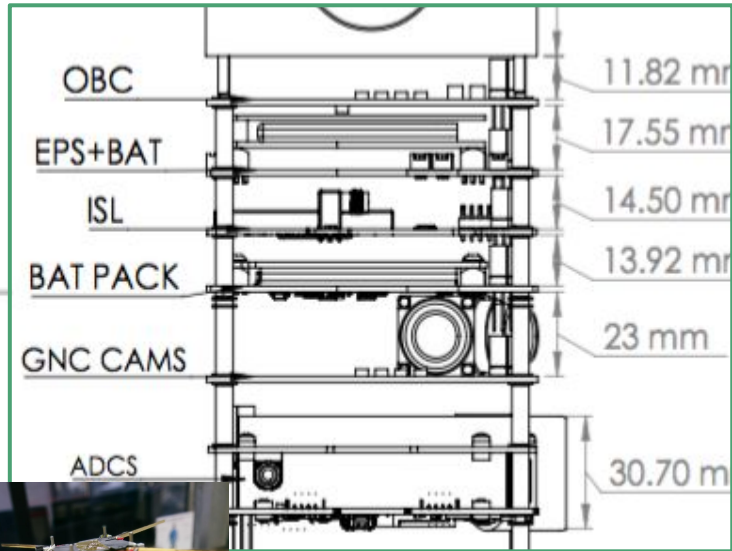
# S/C Configuration



## 1 x 3U CubeSat

- Optical Navigation
  - (TIR Cameras)
- Cold Gas Propulsion
  - Multiple Thrusters configuration
- ADCS (3-axis pointing)
  - Reaction wheels
  - Star-trackers
  - Sun-sensors
- Payloads
  - INH (In-Situ Nephelometer)
  - RNH (Remote Nephelometer)
- Two deployable solar panels
  - Estimated power generation of 15W

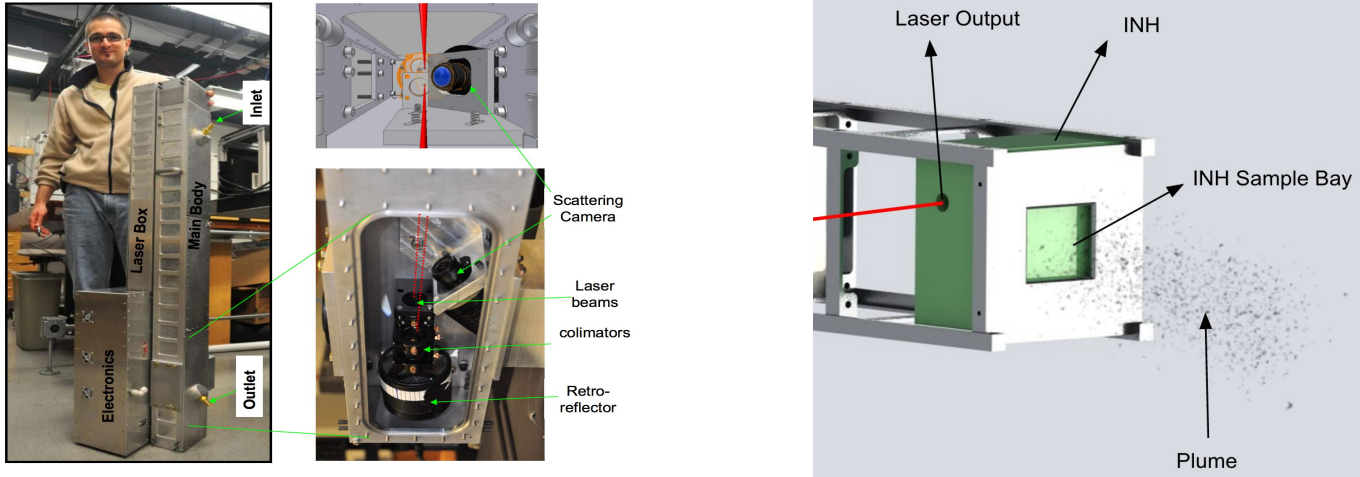
# Proposed flight-proven Platform for DustCube



- **System Reliability:**
  - **> 4 Years** in Orbit, more than **100.000 EXECUTED COMMANDS**
  - Inhouse subsystems development + COTS
  - Critical components = RAD-HARD
  - **Inhouse OBSW:** On Board SW
    - **FDIR** implementation (Failure detection, isolation and recovery)
    - High level of autonomy
    - High modularity for new payloads
  - **40 different Telemetries**
  - **84 Telecommands** direct and scheduler programming
  - Exhaustive system engineering effort and AIT:
    - TLYF (Test Like you Fly)
    - E2E
    - EMC Testing
    - **ECCS** Tailored Methodology for CubeSats developments
  - **LOW COST!** (Lowering the cost, without compromising reliability)
- **GSSW** (Ground Segment Software) based on ESA **PUS** (Packet Utilization Standard)

# (INH) In-situ Nephelometer

- INH: In situ NepHelometer is a miniature design of the PI-Neph (NASA airborne missions)

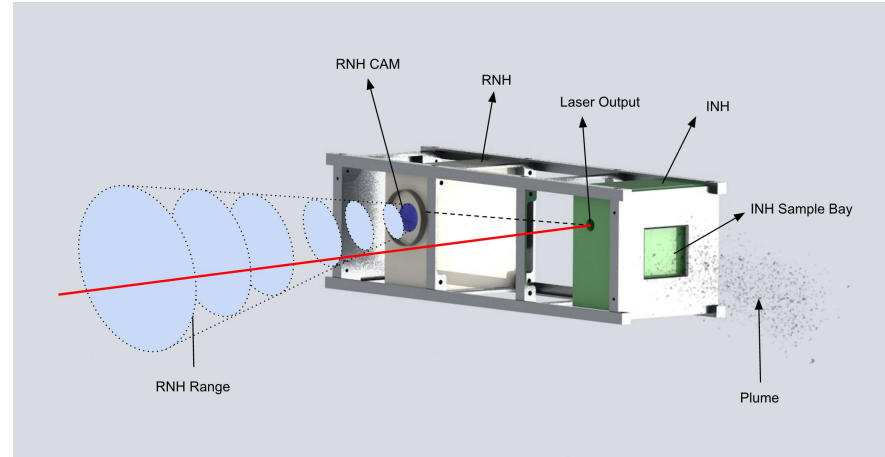
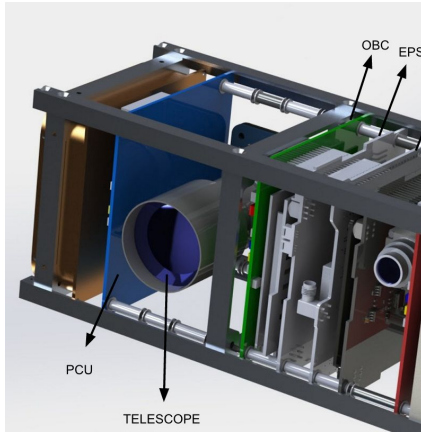


Polarized Imaging Nephelometer Development and Applications on Aircraft, Dissertation, Dolgos, G., 298 pages, 2014

- The particles are deposited in the INH Sample Bay
  - Trapped on a charged surface
- The laser beam passes in front of the camera twice while, the camera takes samples of the impact of the laser with the particles,
  - On the first pass, the forward **scattered light** reaches the camera on a family of scattering angles
  - On the second pass the **backscattered light** reaches the camera in the complementary scattering angle range.
- The laser beam reaches the output of the SC to execute remote measurements of particles.
- Ongoing instrument miniaturization for a 1U CubeSat volume equivalent, based on Micos heritage, is being performed.

# RNH Design (Remote Nephelometer)

- RNH: Instrument enhancement for remote sensing
  - Scattering data from remote particles

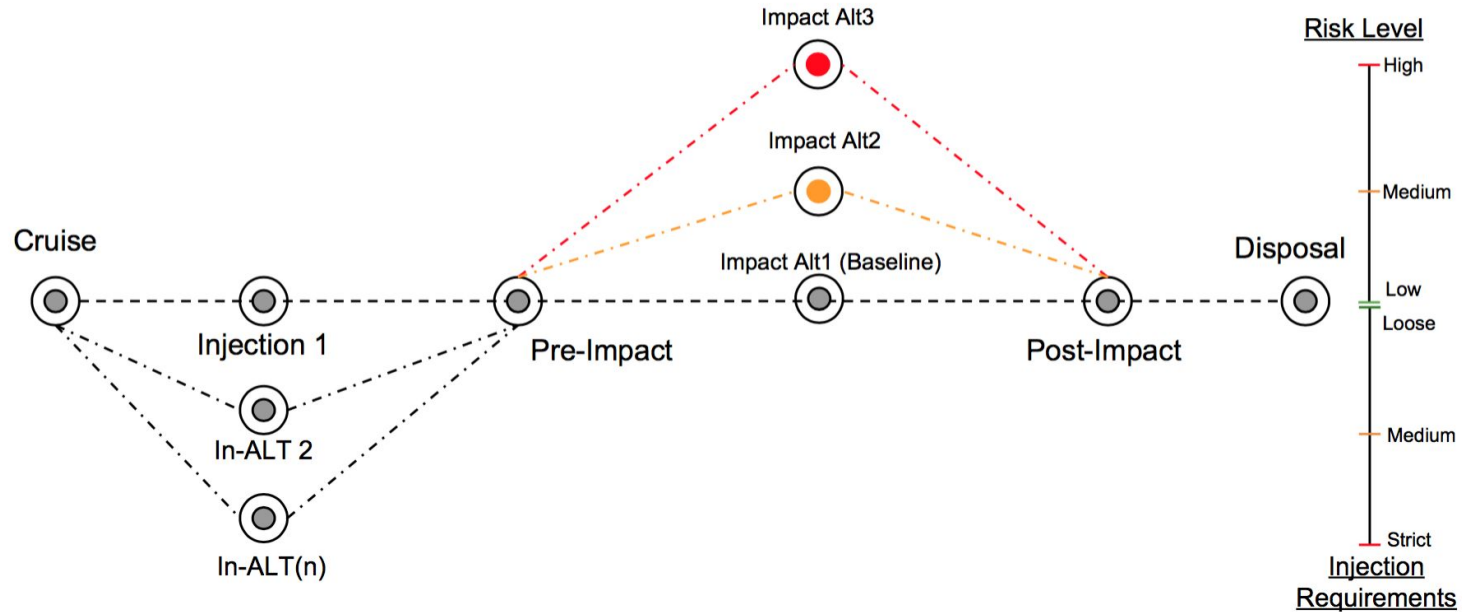


- Technology validation of an altimetry laser (TOF) system used for both surface recognition and navigation.

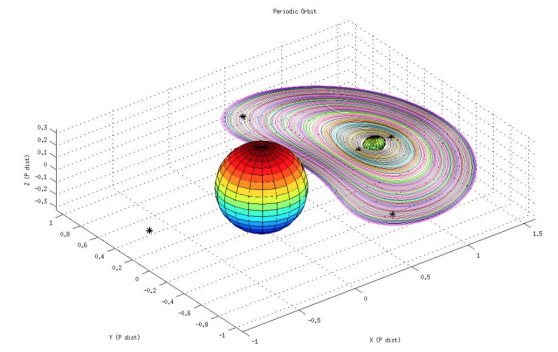
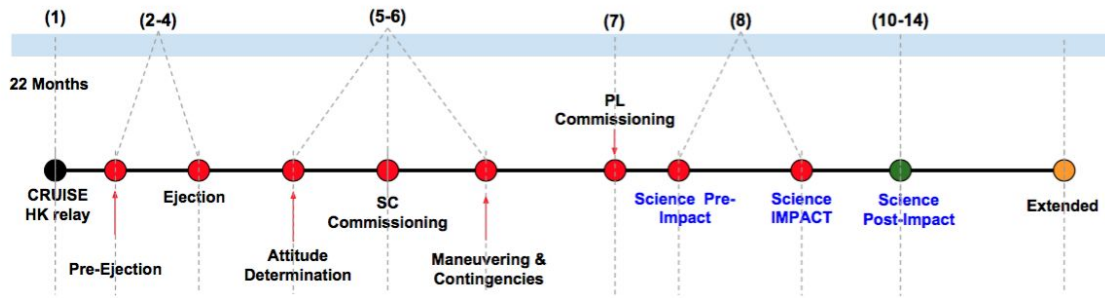
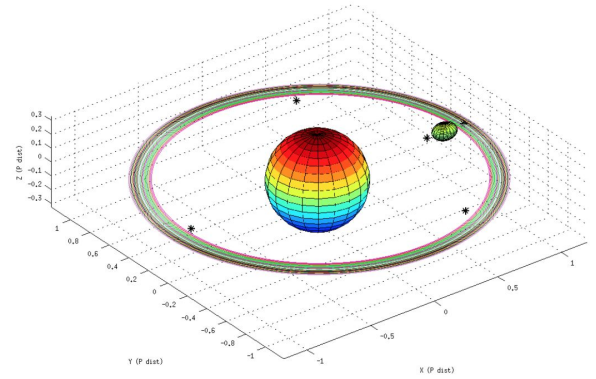
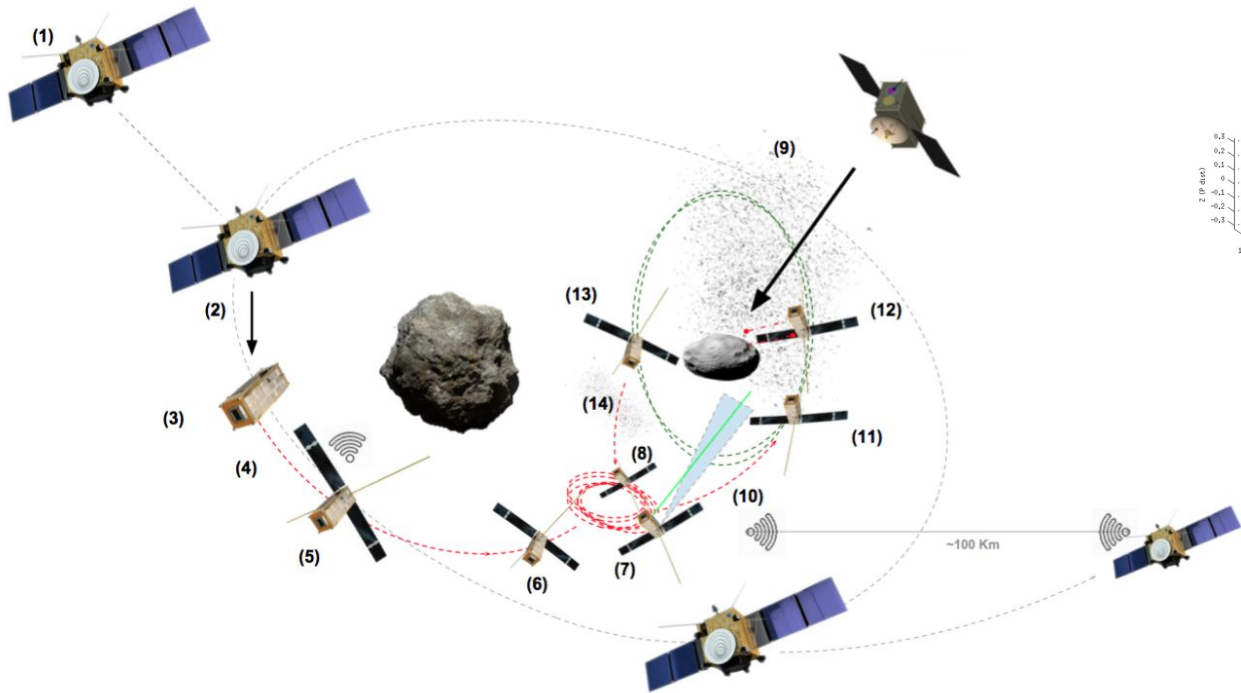
**DustCube**  
**CONOPS**



# Concept of operations



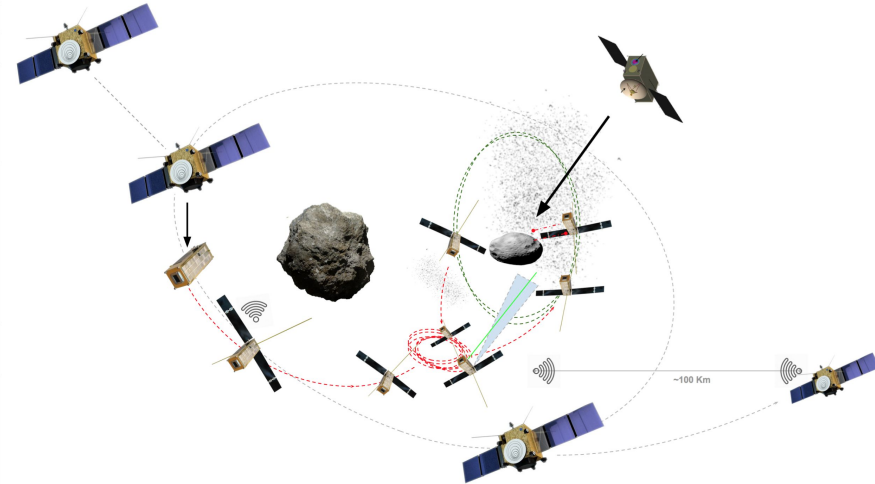
- Set of alternatives for INJECTION Phase, based on injection complexity (Backed-up with numerical models)
- Set of alternatives for IMPACT Phase, based on probability to be impacted by ejected plume, and navigation complexity (Backed-up with Orbital and Environmental analysis )



**DustC**ube  
**SCIENCE**

# SCIENCE CONOPS and Objectives

COPINS Phase	Orbit Position	Duration	Payload Activities
COPINS Deployment	Platform activities @Km	6 days	Commissioning
	Orbit Manouevring (Parking orbit)	1 day	Didymos system imaging
Pre-Impact	SCIENCE @L4/L5	21 days	<ul style="list-style-type: none"> <li>- Natural dust environment characterization                             <ul style="list-style-type: none"> <li>- Particles counting</li> <li>- Particles deposition</li> </ul> </li> <li>- Didymoon surface Imaging</li> </ul>
DART Impact	SCIENCE @L4/L5	1 day	<ul style="list-style-type: none"> <li>- Impact Imaging</li> <li>- Plume concentration evolution</li> <li>- Particles characterization                             <ul style="list-style-type: none"> <li>- PSD (Particles Size distribution)</li> <li>- Particles speeds</li> <li>- Shape</li> <li>- Refractive Index</li> </ul> </li> </ul>
	SCIENCE @Rendezvous	(TBD) hrs	<ul style="list-style-type: none"> <li>- Didymoon surface Imaging</li> <li>- Laser altimetry validation (TOF)</li> </ul>
	SCIENCE @DRO Low altitutde	24 days	<ul style="list-style-type: none"> <li>- Particles charcaterization                             <ul style="list-style-type: none"> <li>- Sphericity</li> <li>- BRDF</li> <li>- PSD (Particles size distribution)</li> </ul> </li> <li>- Surface Imaging</li> </ul>
Post-Impact	SCIENCE @L4/L5	~20 days	Extended Science objectives



# DustCube Conclusions

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- International Consortium (Research institutions + Industry)
- Very valuable science return for the community (INH + RNH)
- Validation of technology for future missions with CubeSats (Laser altimetry)
- Reliable Technology (flight proven platform)
  - FDIR
  - Autonomy
  - 3 Launched and Operated CubeSats Missions
- Experience on autonomous navigation system, space optical payloads and autonomous OBSW
- Tailored ECSS Methodology on CubeSats developments
  - i.e PUS (Packet Utilization standard)



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Engineering for Remote Sensing

# DustCube Project

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**SERPENS S/C**

**Fresh Data**

**(Backup slides)**

# Fresh data from SERPENS Cubesat (Proposed Platform)

- Snap shot of SERPENS TM Viewer during S/C pass over Vigo (Thursday 18/02/2016)

28083  
Executed  
Commands on  
scheduler  
(since 09/2015)

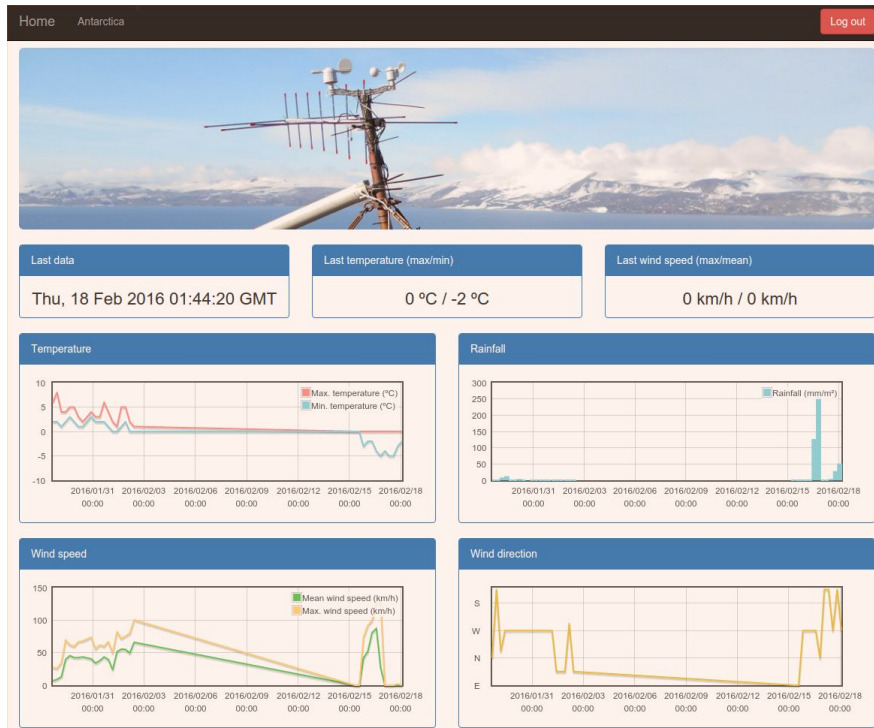
The screenshot displays the SERPENS Ground Segment Software interface. It features a top navigation bar with 'SERPENS Ground Segment Software' and a logo. Below this are several control panels: 'Time Interval' with checkboxes for 'Out of Limits', 'Out of Limits & Old', and 'Old', and a 'Limit (s)' field set to 300; 'Protocol' with 'TM Mode' and 'Reset Protocol' buttons; 'TC & TM' with 'TC Manager', 'TM Viewer', and 'Hex. Converter' buttons; 'Pass Control' with 'PASS MODE (AUTO)', 'Start pass', and 'End Pass' buttons. A central data table is divided into columns: TTC, OBC, Solar Panel X, EPS, OBSW, and Humpl. The '28083 SDU' entry is highlighted in red in the OBC column. To the right, the 'Station Manager' panel includes 'TX polarization control' (Mode: fixedLHCP), 'Reception log' (Last RX packet: Thu Feb 18 12:03:41 GM), and two TNC status sections (TNC 1 and TNC 2) both showing 'AVAILABLE'. At the bottom, the 'Time Management' panel shows the current time as 'Thu Feb 18 12:03:42 GMT 2016' and various offset and epoch settings.

TTC	OBC	Solar Panel X	EPS
P_TTC_RX	17 pkt	P_OBC_HUMPL_SV	0
P_TTC_RXERR	3 pkt	P_OBC_HUMPL_3V3	0
P_TTC_BITCORR		P_EPS_+X_T	511
P_TTC_BYTECORR		P_EPS_-X_T	511
P_TTC_TX	131 pkt	P_EPS_+X_T	460
P_TTC_RSSI	-106 dBm	P_EPS_-X_T	511
P_TTC_RFERR	-144 Hz	Solar Panel Y1	
P_TTC_TX_I	812 mA	P_EPS_Y1_V	
P_TTC_BOOTCOUNT	17167 Rebo...	P_EPS_+Y1_I	
P_TTC_T_PA	9 °C	P_EPS_-Y1_I	
P_TTC_T_PCB	5 °C	P_EPS_-Y1_T	
		Solar Panel Y2	
		P_EPS_Y2_V	
		P_EPS_+Y2_I	
		P_EPS_-Y2_I	
		Temp. Z	
		P_EPS_+Z_T	
		P_EPS_-Z_T	

- Downloaded Data in the communication pass:
  - Environmental data collected from HUMSAT sensors deployed in **ANTARCTICA + Chile + Spain**.
  - Payload measurements of Global VHF radio interference on the Amateur band to globally map the jamming sources.



# Fresh data from SERPENS (Antarctica data and sensors)



Figs. Data gathered from Antarctica sensors



Figure. Humsat sensor



Figure. Antarctica spanish base sensor location