

Lights Out: Evolution of an Automated Ground Segment for Operation of the Aerospace CubeSat Constellation

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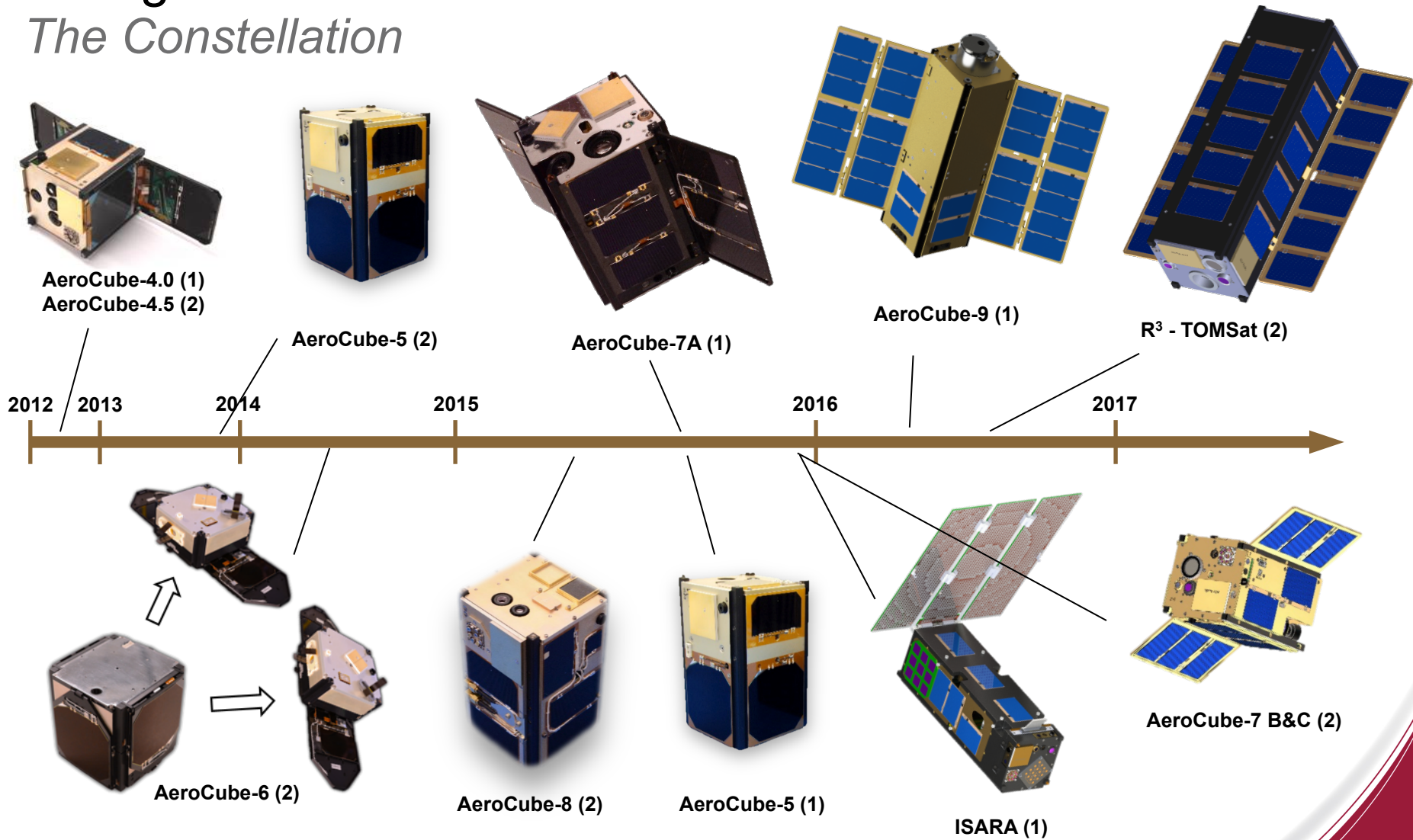
Presentation Outline

- Background
 - *The Constellation and Ground Station Network*
 - *Historical Setup*
 - *Goals/Requirements*
- Initial Evolution
- Automation
- System Architecture
- Automation Examples



Background

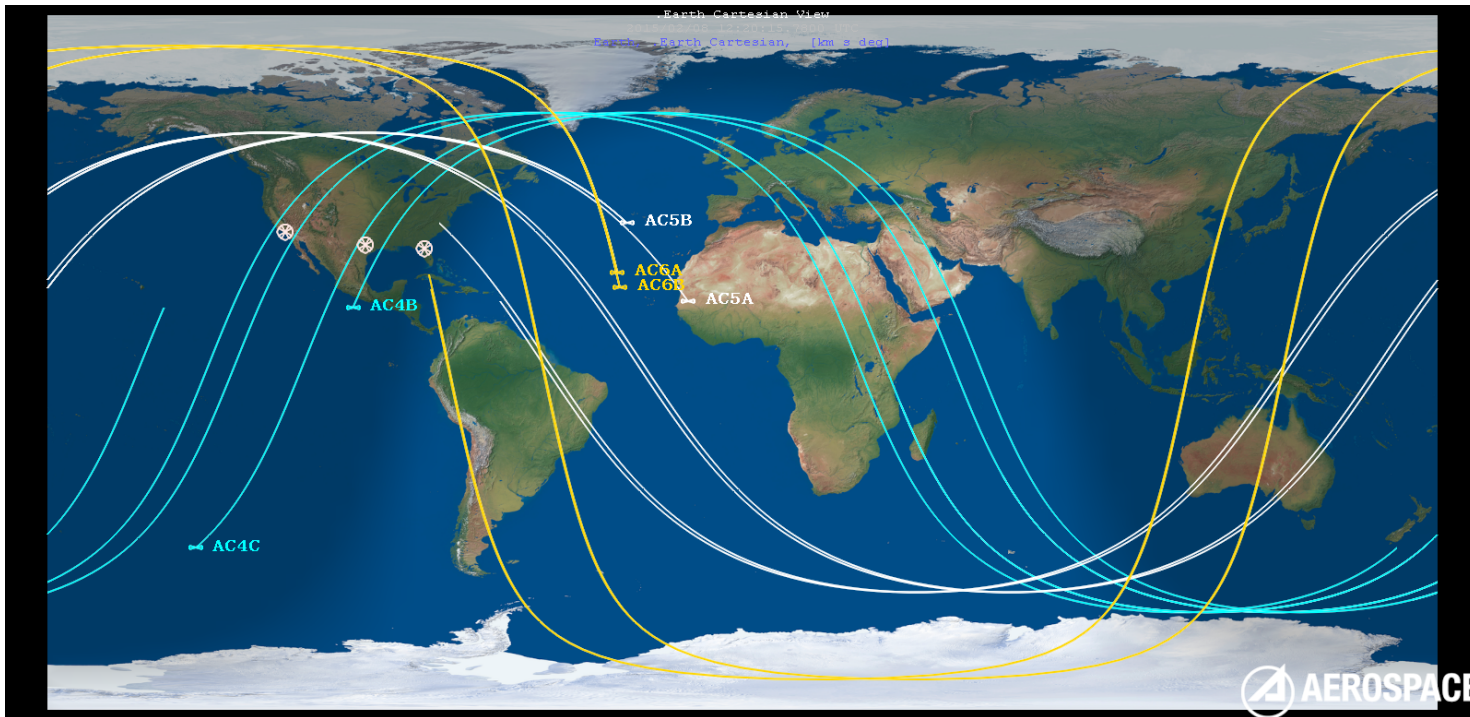
The Constellation



Background

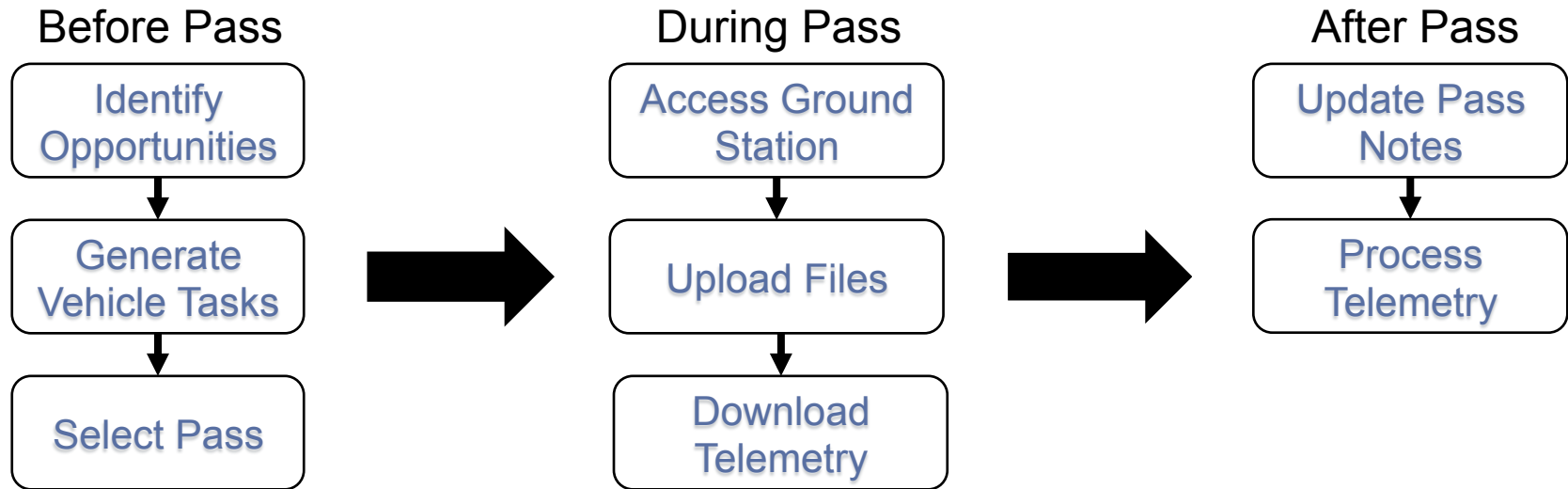
The Ground Network

- Ground Stations
 - *Texas*
 - *Florida*
 - *California*
- Features
 - *Vehicle Independent*



Background

Mission Flow



Background

Historic Operations - Tools

- Tools
 - *Mission Planning Software*
 - Generates vehicle tasking
 - *Ground Station Control Software*
 - Uploads tasking
 - Allows direct vehicle commanding
 - *Pass Management*
 - Pass data manually logged
 - *Telemetry Handling*
 - Parser Scripts
 - *Time Tagged Files*
 - Data compiled in Excel as needed
- Problems
 - *Labor Intensive*
 - Numerous repetitive tasks
 - Idle vehicles
 - *Still need to collect health telemetry*
 - *Coordination is Difficult*
 - *Data Overload*
 - Telemetry is not readily accessible
 - Hard to find and identify specific events
 - *Multiple Code Bases*
 - ***Constellation is Growing!!!***



System Evolution

The Goal

- Driving Goal
 - ***Reduce The Required Labor to Maintain the Constellation***
- How
 - *Automate Ground Stations*
 - *Simplify Coordination*
 - *Automate Telemetry Collection and Aggregation*
 - *Automate Basic Fault Detection*
- Requirements
 - *Do not interfere with user planned missions*
 - *Interact with existing software*



System Evolution

First Steps

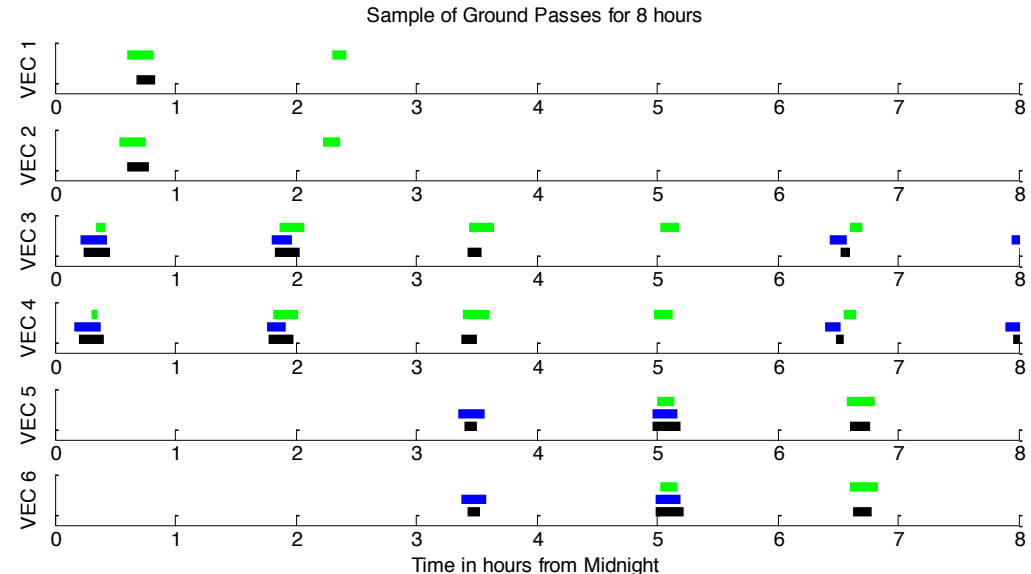
- Step 1 – Scripted Ground Stations (2012)
 - *Socket Based Program*
 - Server - Powers client per schedule and sends command file
 - Client - Executes command files and returns telemetry to server
- Step 2 – Pass Management (March 2014)
 - *Database driven website*
 - Provides automatic handling for simultaneous users
 - Database acts as central repository for other programs
- Step 3 – Telemetry Handling (July 2014)
 - *Automated telemetry binary data parsing*
 - *Aggregate in database*



System Evolution

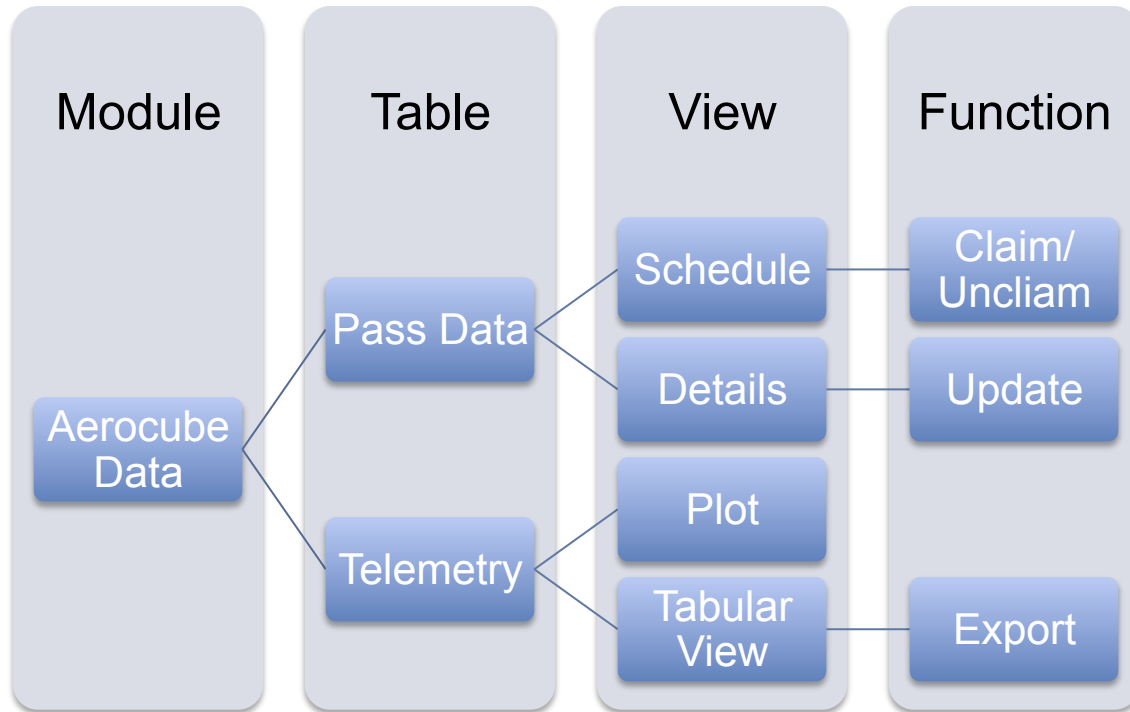
Notes on Pass Management

- Import Predictions to Database
- Identify Conflicts
 - *Considerations*
 - Ground Station Restrictions
 - Vehicle Restrictions
 - Timing!!
- Store Conflict Data
- Management Interface
 - *Claiming pass locks out conflicting passes*
 - *Allows super users to bypass conflict management*



System Evolution

Website Architecture



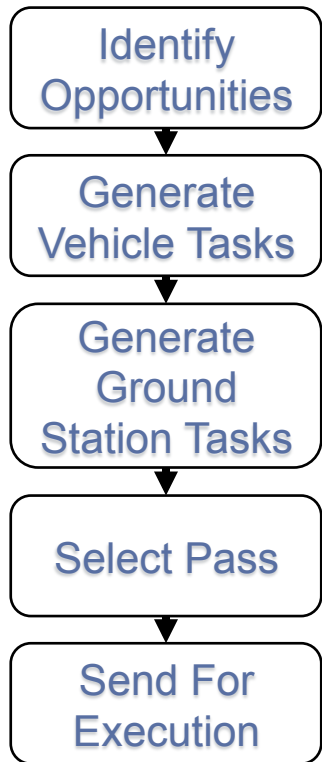
- Website Advantages
 - Platform Independent
 - Simple Access Control
 - Elegant Visualization Tools
- Django Platform
 - Python Backend
 - HTML, CSS, Javascript Frontend
 - Advantages
 - Python Based
 - Template System
 - Module Based



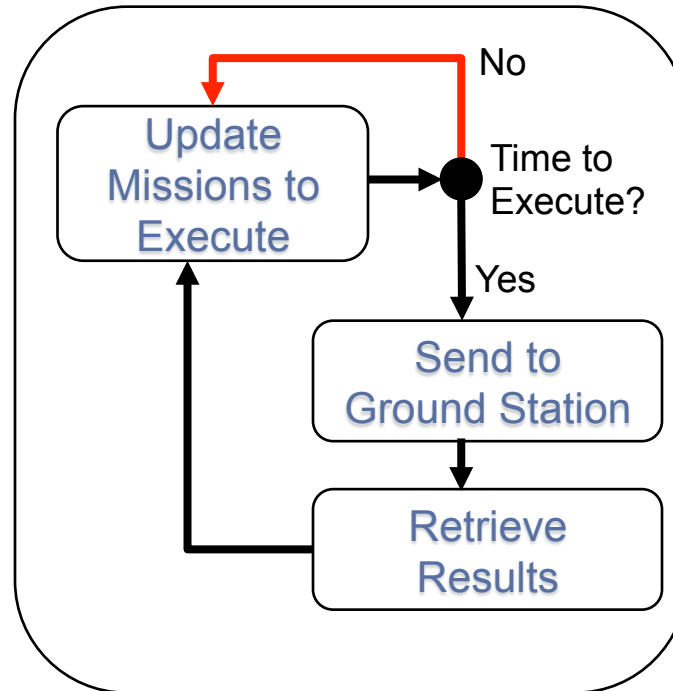
System Evolution

New Mission Flow

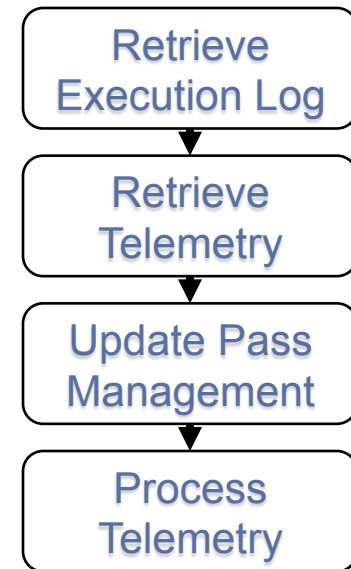
End User Before Pass



Ground Station Server



End User After Pass



System Evolution

Introducing Automation

- Step 4 – Basic Automation (August-October 2014)
 - *Collect Basic Health Telemetry Automatically*
 - Generate simple vehicle and ground station tasking
 - Generate vehicle priorities
 - *Ground Pass Tracking*
 - Parse results from ground pass server and import to the database
 - *Vehicle State Tracking*
- Step 5 – Contextual Notifications (January 2015)
 - *Email Alerts*
 - Automation Failures
 - Vehicle Health Alerts
- Step 6 – Advanced Automation (May 2015)
 - *Complex Telemetry Collection*
 - *Vehicle Specific Automation*



Constellation Automation

Deciding What to Do

Determine Priority

- Considerations
 - User Set Priority
 - Vehicle Restriction
 - Is Telemetry Available
 - When Will Telemetry Buffers Rollover
 - When Does the Current Taking Expire
- Requires a Blending Algorithm!!

Allocate Passes

- Considerations
 - Conflicts
 - Can Tasks be Combined
 - Timing!!
- Assign Passes based on Priority

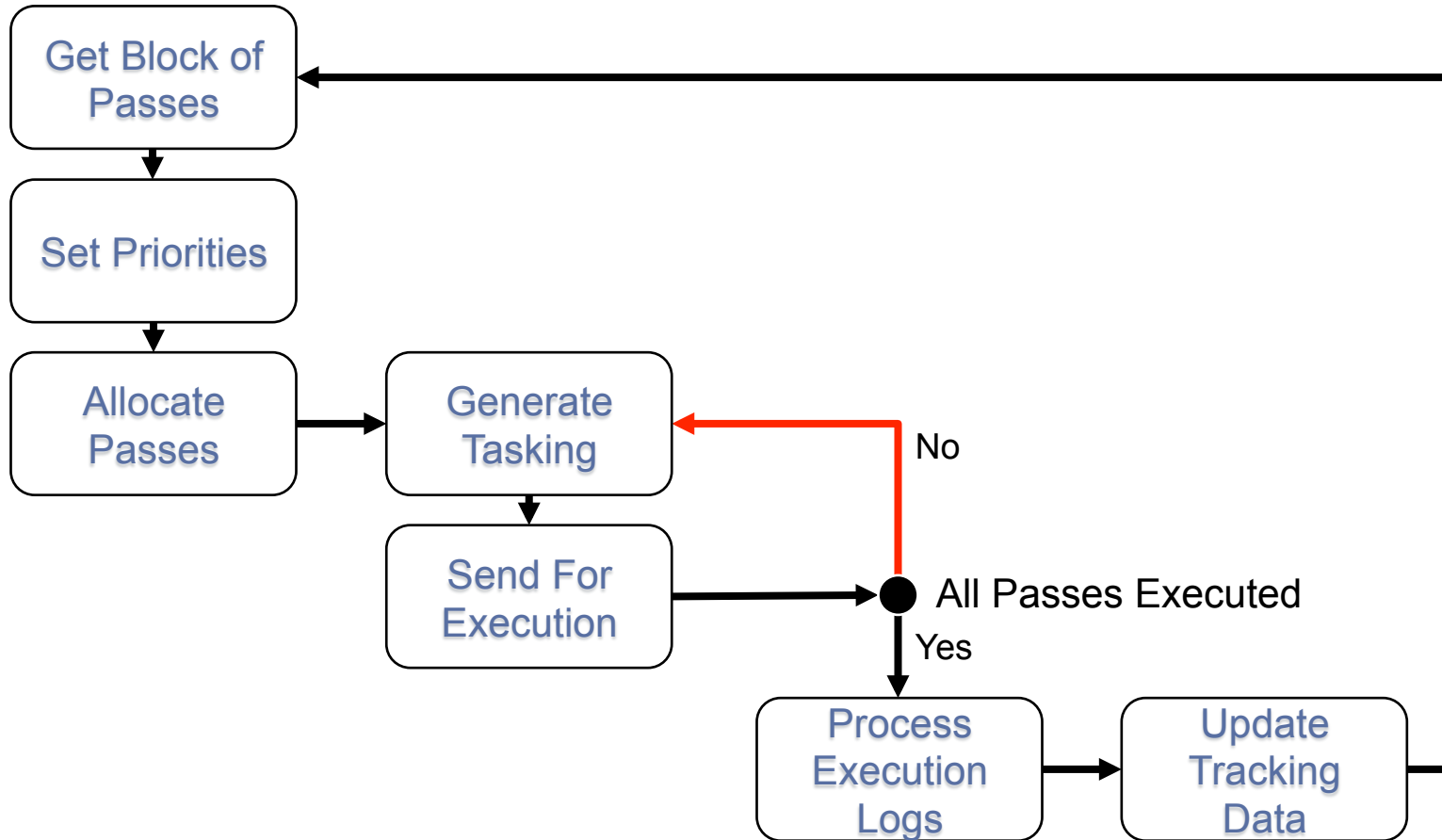
Generate Missions

- Generate in Execution Order
- Generate Just Prior to Execution
 - Allow End Users First Choice of Passes
- Look for Completed Missions while waiting for next Mission Generation



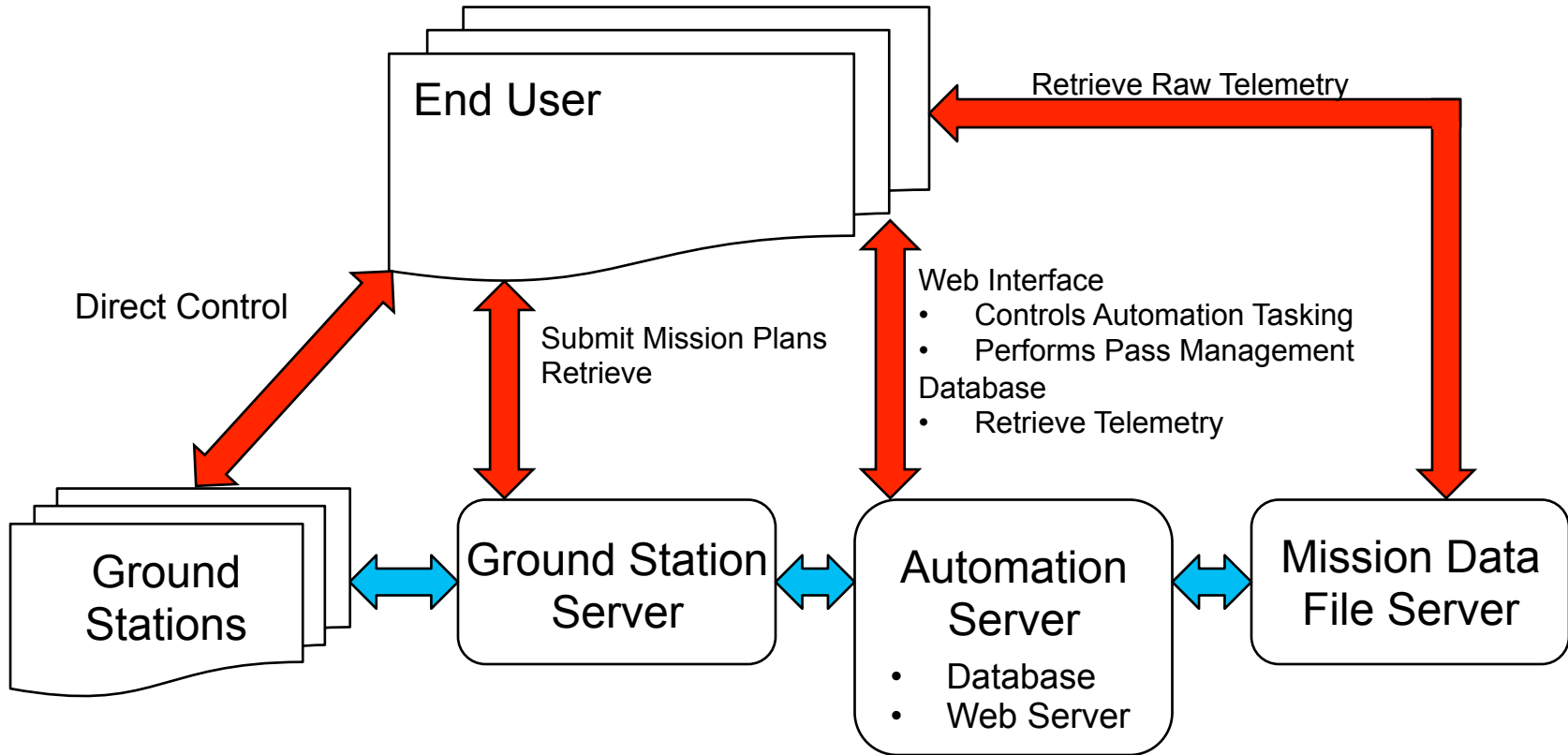
Constellation Automation

Automation Flow



Constellation Automation

Basic Architecture



Constellation Automation

Detailed Architecture

Software Key

-MATLAB

-C++

-VB6

-Python

-HTML

Data Key

-XML

-Files

-Database

-Socket

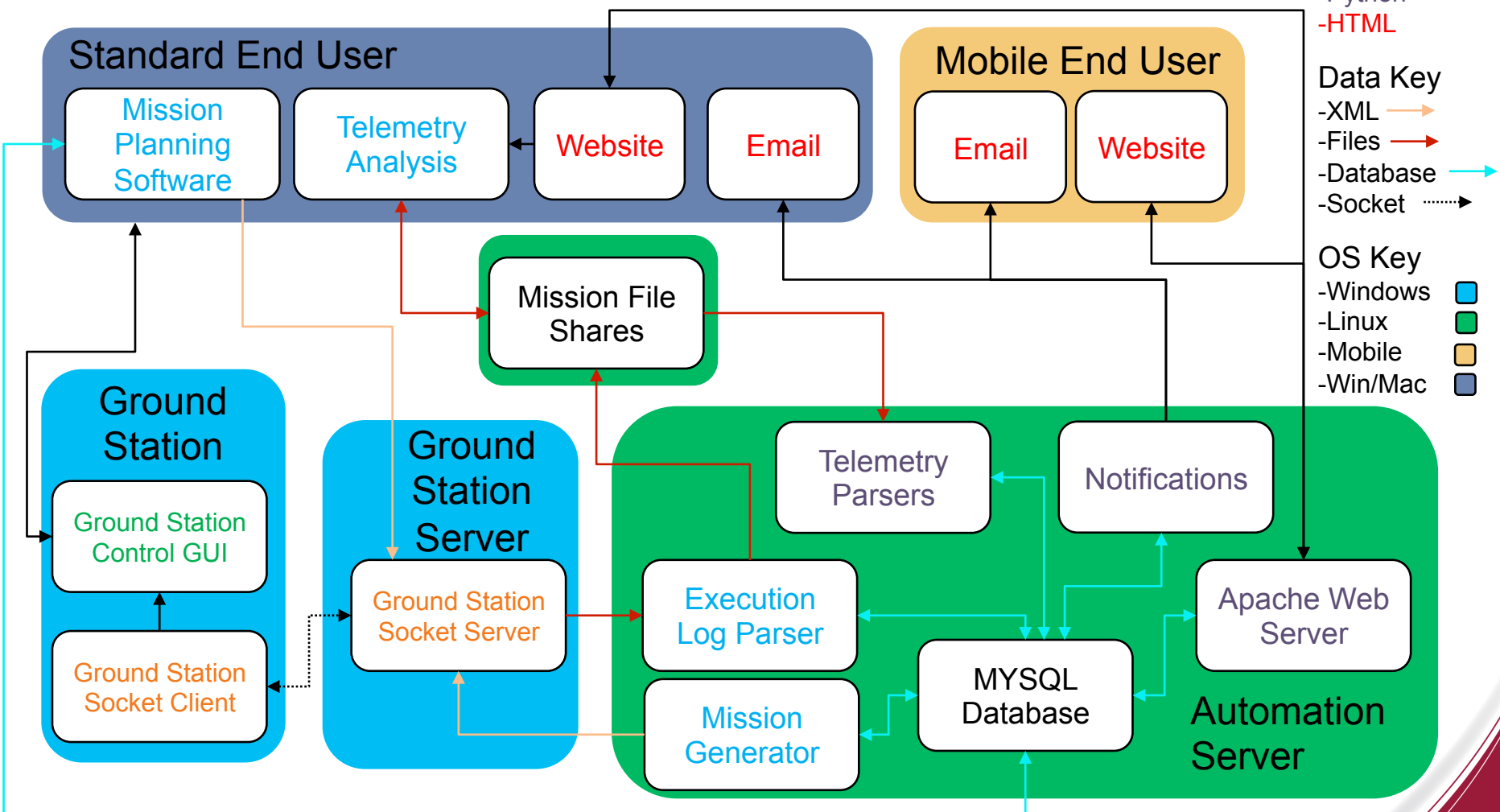
OS Key

-Windows

-Linux

-Mobile

-Win/Mac



Automation Use Cases

Complex Joint Experiment Planning with CubeSats

- What does it take to execute a complex joint experiment?
 - ***Accurate ephemeris prediction***
 - *Precise attitude control*
 - *Coordinated data exchange between planning groups*
 - *Accurate on-board clock & ability to execute time based stored commands*
- Ephemeris Prediction Options:
 - JSpOC TLEs are released on a (mostly) daily basis
 - Position errors can be too large for some experiments
 - Error is 1–3 km at epoch
 - Error grows at ~10 km per day, making advanced planning difficult
 - GPS Derived Ephemeris
 - Requires on-board GPS receiver
 - Requires potentially large ground network to downlink timely GPS data
 - Requires complex orbit determination software



Automation Use Cases

Complex Joint Experiment Planning with CubeSats

Ephemeris Prediction Position Error as a Function of Planning Lead Time

Lead Time	In-Track Position Error	Cross-Track Position Error	Radial Position Error
T-14days	~100 km	~100 m	~2 km
T-3days	2.0 km	12 m	40 m
T-2days	0.4 km	<10 m	<10 m
T-1days	0.3 km	<10 m	<10 m
T-0.5days	0.1 km	<10 m	<10 m

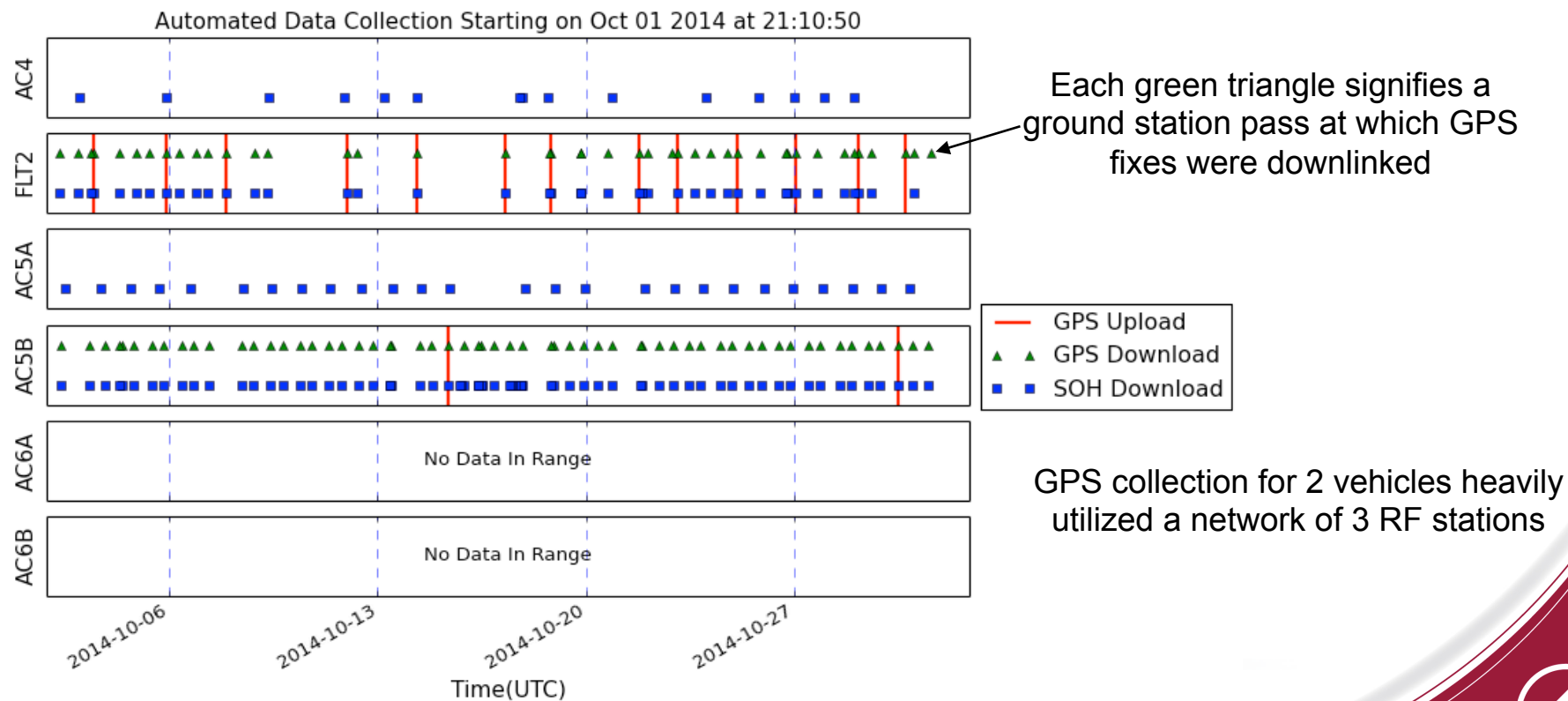
- Note that lead times less than 12 hours could produce better accuracy, however, short lead times are not practical
 - *Limited to ground station access times for GPS data downlink*
 - *Complex experiments require time for planning, data exchange & command uplink*



Automation Use Cases

Complex Joint Experiment Planning with CubeSats

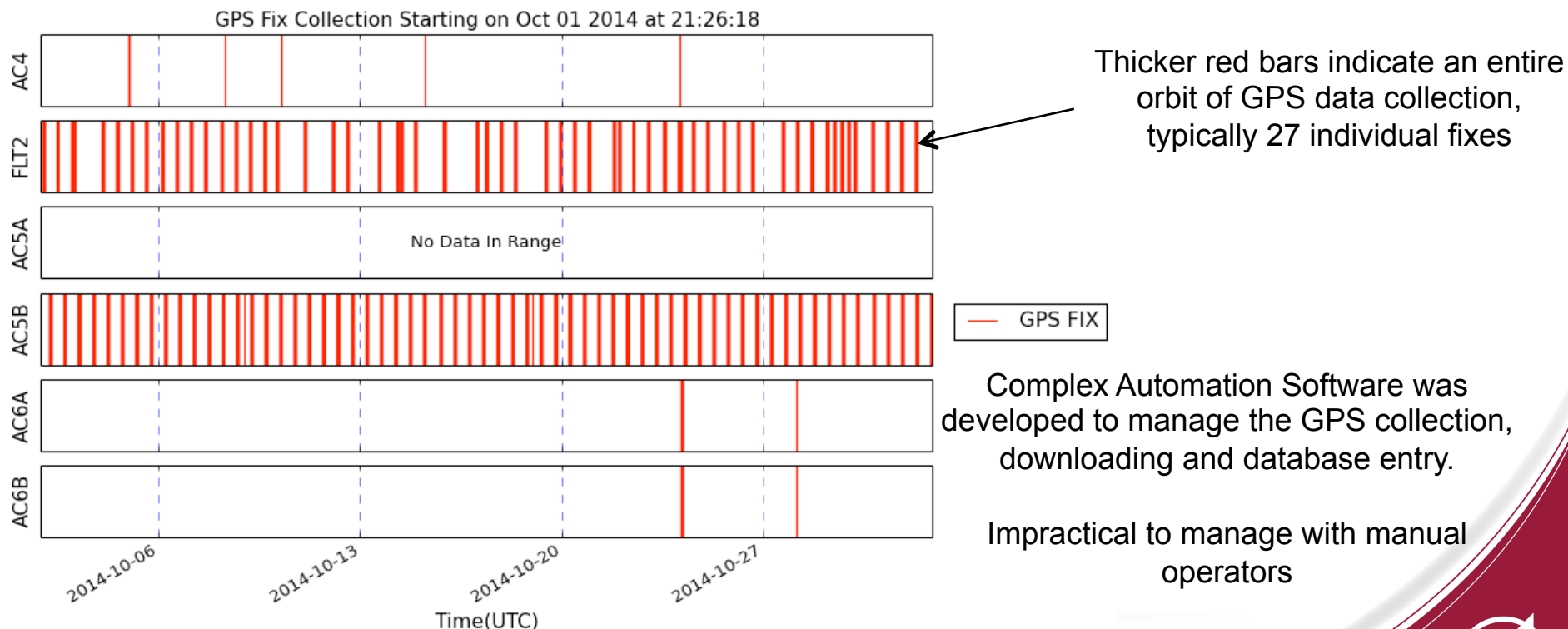
- Regular GPS fix scheduling & downloading is a burden on the ground network
 - *Requires multiple contacts per day to ensure “fresh” GPS data is available for planning*



Automation Use Cases

Complex Joint Experiment Planning with CubeSats

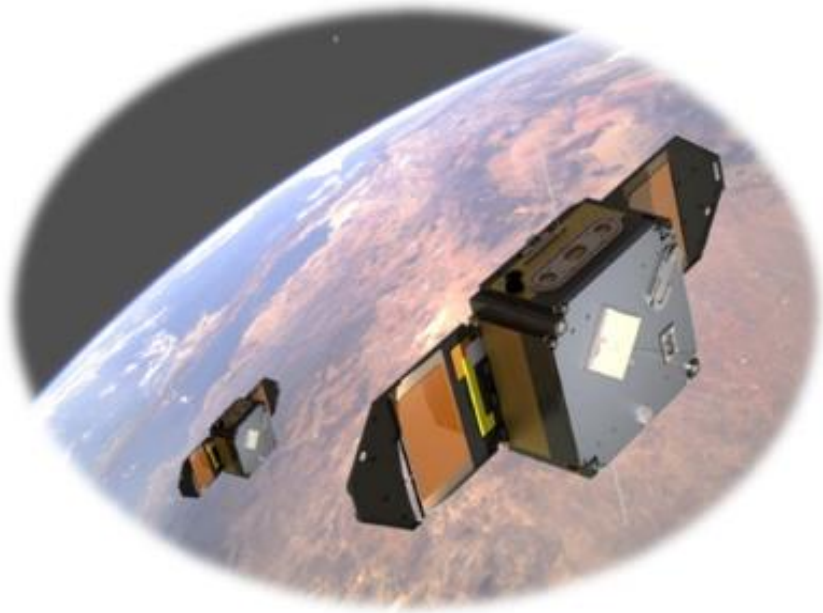
- GPS data needs to be well distributed throughout the orbit and collected for multiple orbits per day
 - *Each vehicle can collect ~1700 fixes per month to support advanced planning*
 - *Fixes need to be parsed & entered into a database*



Automation Use Cases

Science Missions

- Two Spin Stabilized 0.5U CubeSats
- Primary Mission
 - *Correlate observations and study small-scale radiation belt structure*
- Unique Requirements
 - *Always on*
 - Gathering dosimeter telemetry
 - Maintaining spin stabilization
 - *Proximity Operations*
 - Need to adjust vehicle separation using differential drag
 - *Regular Contact Intervals*
 - Downlink dosimeter telemetry
 - Downlink pointing telemetry
 - Uplink payload commanding
 - Uplink pointing commands for differential drag



Automation Use Cases

Science Missions

- Regular Cadence to the Mission Operations
 - *Requires 1-1.5 hours to plan daily*

Interval	Task
12 hours	Download Dosimeter Telemetry
1 day	Download Pointing and Health Data
1.5 day	Upload Pointing Commands
2 weeks	Collect GPS Data
2 weeks	Clear Pointing Telemetry Buffer
1 month	Clear Health Telemetry Buffer

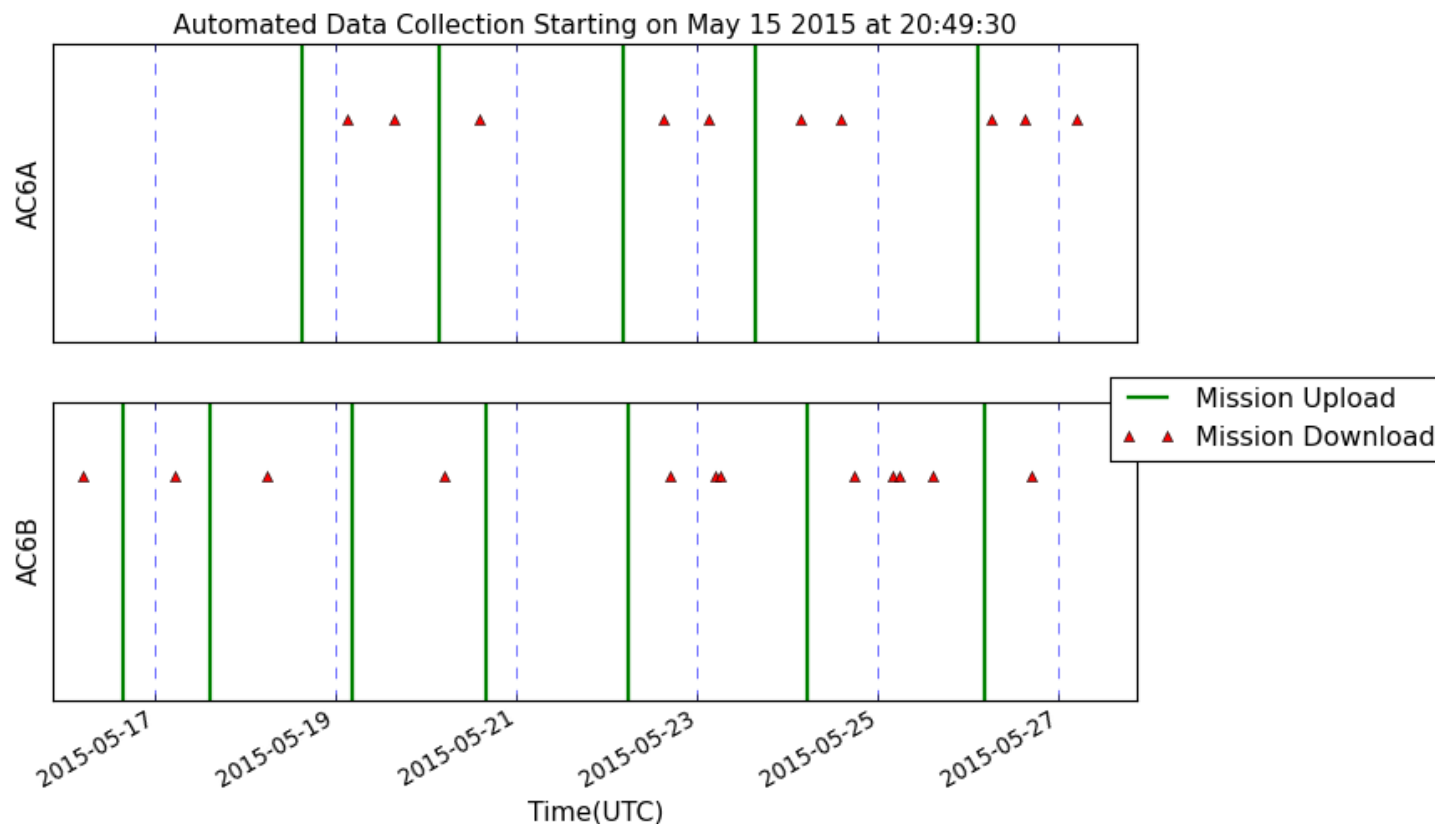
Highly Automatable



Automation Use Cases

Science Missions

- Automation Turned on May 15th



Conclusion

- It's possible to blend existing tools into an Automation System
- Taking an incremental approach is a practical method for developing an Automation System
- ***It now take fewer man hours to run 8 satellites than it previously took to run 1***

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Questions?

