



# Developing the Miniature Tether Electrodynamics Experiment

**Completion of Key Milestones and Future Work** 

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**MiTEE Spacecraft:** CubeSat with picosat scale end-body on 10 meter miniature electrodynamic tether (EDT) designed to characterize and demonstrate miniature EDT technology.

#### **Mission Goals:**

- Provide a hands-on multidisciplinary educational experience rooted in faculty driven research
- Understand the impact of hands-on multidisciplinary participation in faculty research on STEM education for undergraduate and graduate students
- Understand the functionality of miniature electrodynamic tethered systems









#### **Science and Engineering Objectives**

Characterize voltage-current transfer functions for EDT system under a variety of ionospheric plasma conditions

• Measure tether current as a function of anode/CubeSat voltage for a range of cathode emission levels

#### Characterize miniature tethered system dynamics

• Cubesat and End-body attitude and position as a function of time and tether operational modes (thrusting/non-thrusting)

#### Demonstrate use of the tether as a high gain groundpointing traveling wave antenna

• Compare primary antenna and tether-based signal strength as a function of overpass attitude and distance

















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### **Electrodynamic Tether as Traveling Wave Antenna**



Tether Axis -14 -26 -38 Peak Gain 7 dB Gain •Nadir Angle Polar Gain Plot (dB) 3D Gain Model (dB)

High gain annular radiation concentric with tether axis

Peak gain occurs toward the end of the tether opposite the driving circuitry (nadir pointing)

For demonstration purposes, tether signal strength and transmission integrity will be compared to primary antenna. Attitude and distance will play key roles in this analysis.





## 2014-2015 Major Design Decisions: Primary Antenna



Selected four-way synchronously driven monopole antenna array for primary communications





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### 2014-2015 Major Design Decisions: Cathode



WINCS thermionic cathode

- Barium-oxide coated tungsten filament
- Designed to output more than 7 mA
- Manufactured by E-Beam Inc
- Flying aboard then UM CADRE CubeSat later this year







### 2014-2015 Major Design Decisions: Deployment



Motorized spool and roller design for slow controlled deployment

- Spring-loaded pinch rollers
- Small piezo-electric motor
- Structure can be 3D printed







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### 2014-2015 Major Design Decisions: Processing



Moved to distributed (hub and spoke) processing architecture to simplify parallel development and operation of subsystems. Additional benefits:

- Greater redundancy
- Lower over-all power consumption







### 2014-2015 Major Design Decisions: Form Factor



Converted from 1U to 3U for increased mass, power, and volume capacity









#### **CubeSat Launch Initiative (CSLI)**



- Selected for 6<sup>th</sup> round of NASA's CubeSat Launch Initiative
- Ranked 4<sup>th</sup> among selected missions
- Launch opportunities in 2016-2018



Courtesy of NASA/Google Maps





### **Future Development and Major Milestones**



#### Future Development

- Improved tether dynamics modeling
  - Software modeling (ADAMS) of tether system with all relevant drag, thrust and gravity gradient forces well characterized
- Evolving designs for end-body position characterization
  - Lidar based distance determination coupled with on-board attitude determination with CubeSat link
- Tether core and insulative coatings research
  - Research into "semi-rigid" tether materials is ongoing as well as analysis of potential insulative coating materials
- Indium-Tin-Oxide solar cell coatings
  - Solar cell surfaces are required to be conductive and grounded for maximum ion ram current collection
- Antenna/Tether coupling analysis
  - Preliminary study suggests strong coupling with primary antenna array



#### Milestones

- Preliminary Design Review (Ongoing) • September 2015
- Critical Design Review
  - March 2016
- Flight Hardware Assembly, Integration and Testing
  - o Flight Readiness Review
    - O1 2017
  - Hardware Delivery
    - O2 2017



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