

# CUBESAT PROPULSION MODULE WITH CLOSED-LOOP THRUST CONTROL



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# Outline

- Background & Introduction
  - *MEMS & first generation micropropulsion*
  - *Advanced propulsion requirements*
- Second generation MEMS micropropulsion
  - *Closed loop thrust control*
- Some other propulsion developments
- Swedish lessons

# MEMS – MicroElectroMechanical Systems

- MEMS enables small sizes
  - $\mu\text{m}$  feature sizes
- MEMS enables batch fabrication
- MEMS enables on-chip integration
  - Nozzles, sensors, actuators...

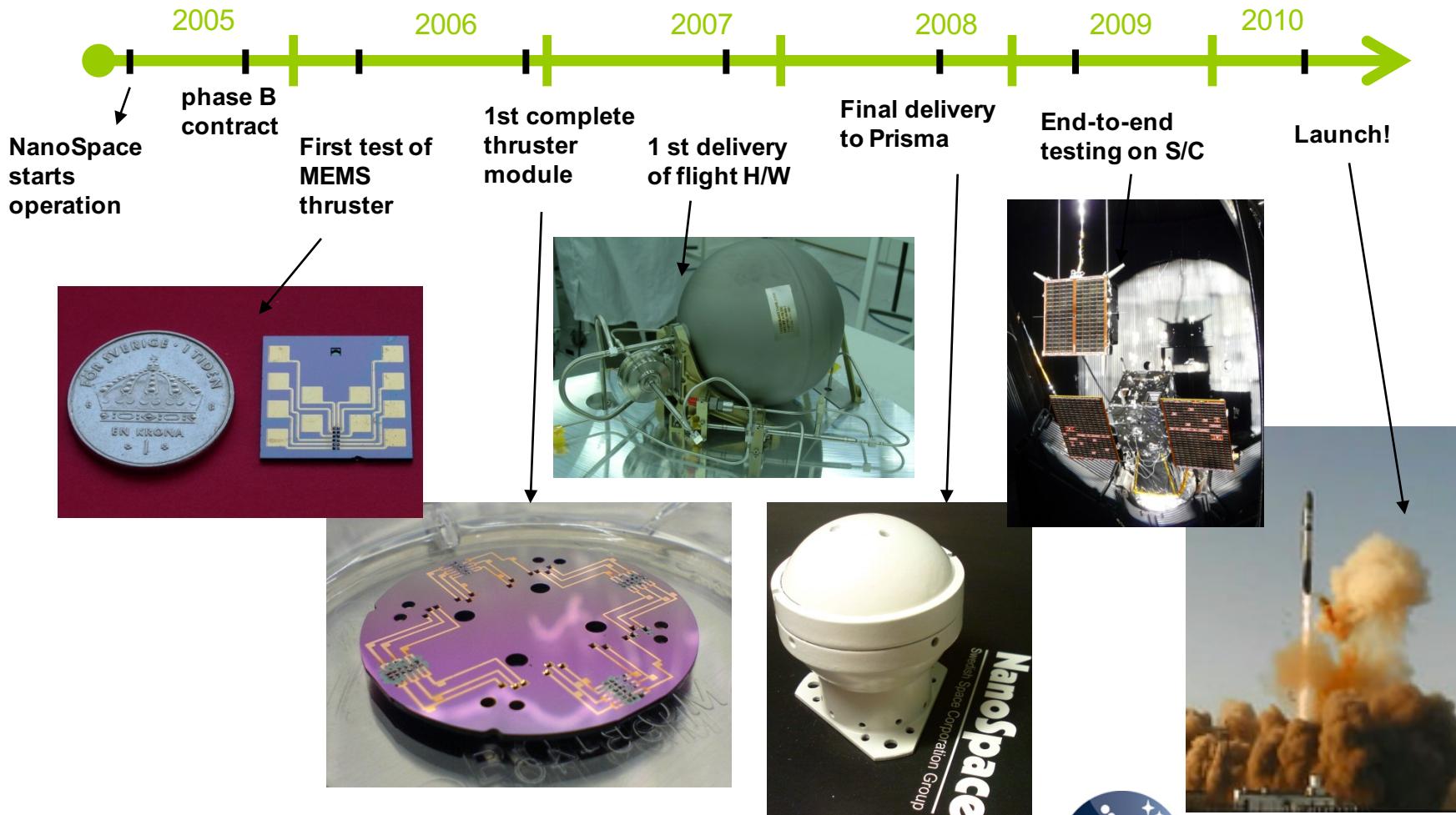
***Integration and small size***  
=> ***small internal volumes***  
=> ***short response time and***  
***small impulse bits***



Our "MEMS kitchen"

# First generation MEMS micropulsion

- developed for the *Prisma* satellites

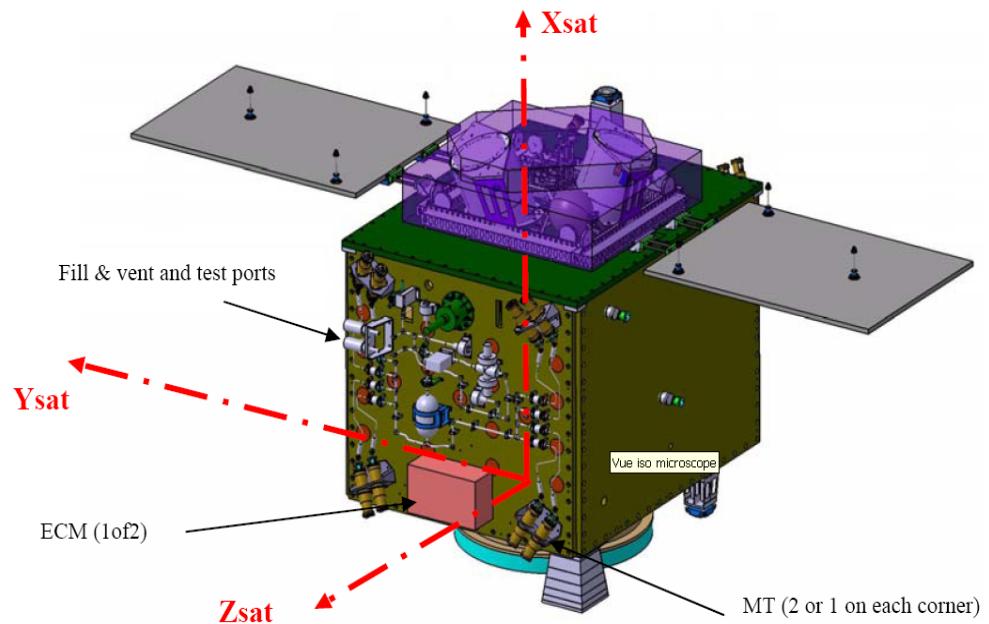


# Advanced missions – Demanding requirements

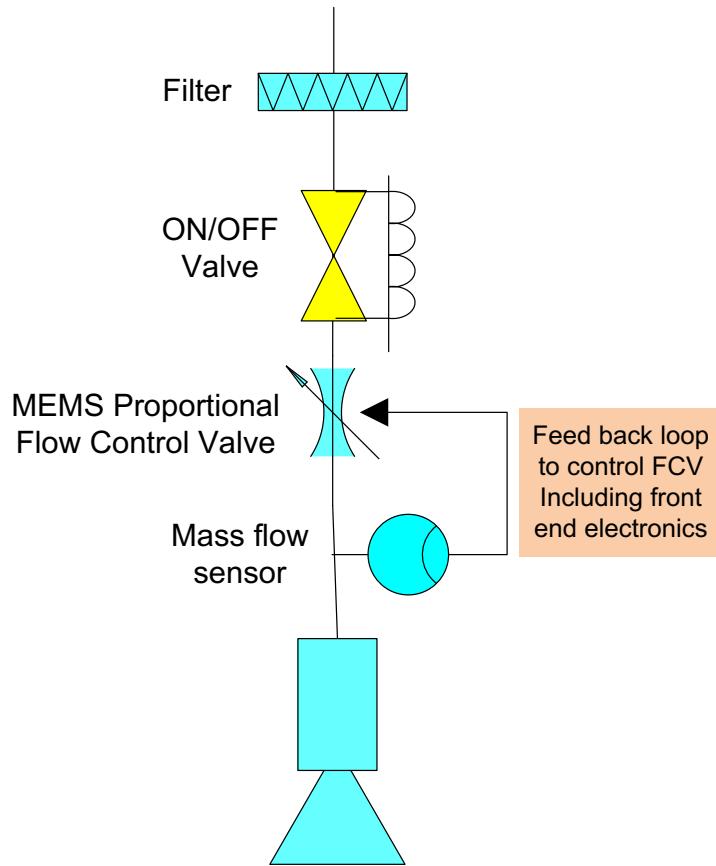
## Example: MICROSCOPE – drag free flight

16 thrusters with closed loop thrust control

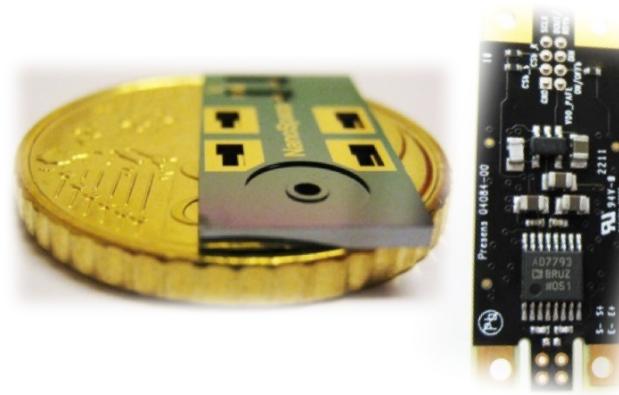
- 16 thrusters with closed
- 1 – 300  $\mu\text{N}$  thrust range
- 0,2  $\mu\text{N}$  resolution
- 250 ms response time
- 260 million cycles



# Second generation – Closed-Loop Thrust Control



Integrated mass flow sensor provides control signal to the proportional flow control valve  
⇒ Closed loop thrust control



Thruster chip and front end electronics

Figure: Schematic view of a complete closed loop control thruster.  
ON/OFF valve in conventional technology, the rest in MEMS.

# Key capabilities – Like any other

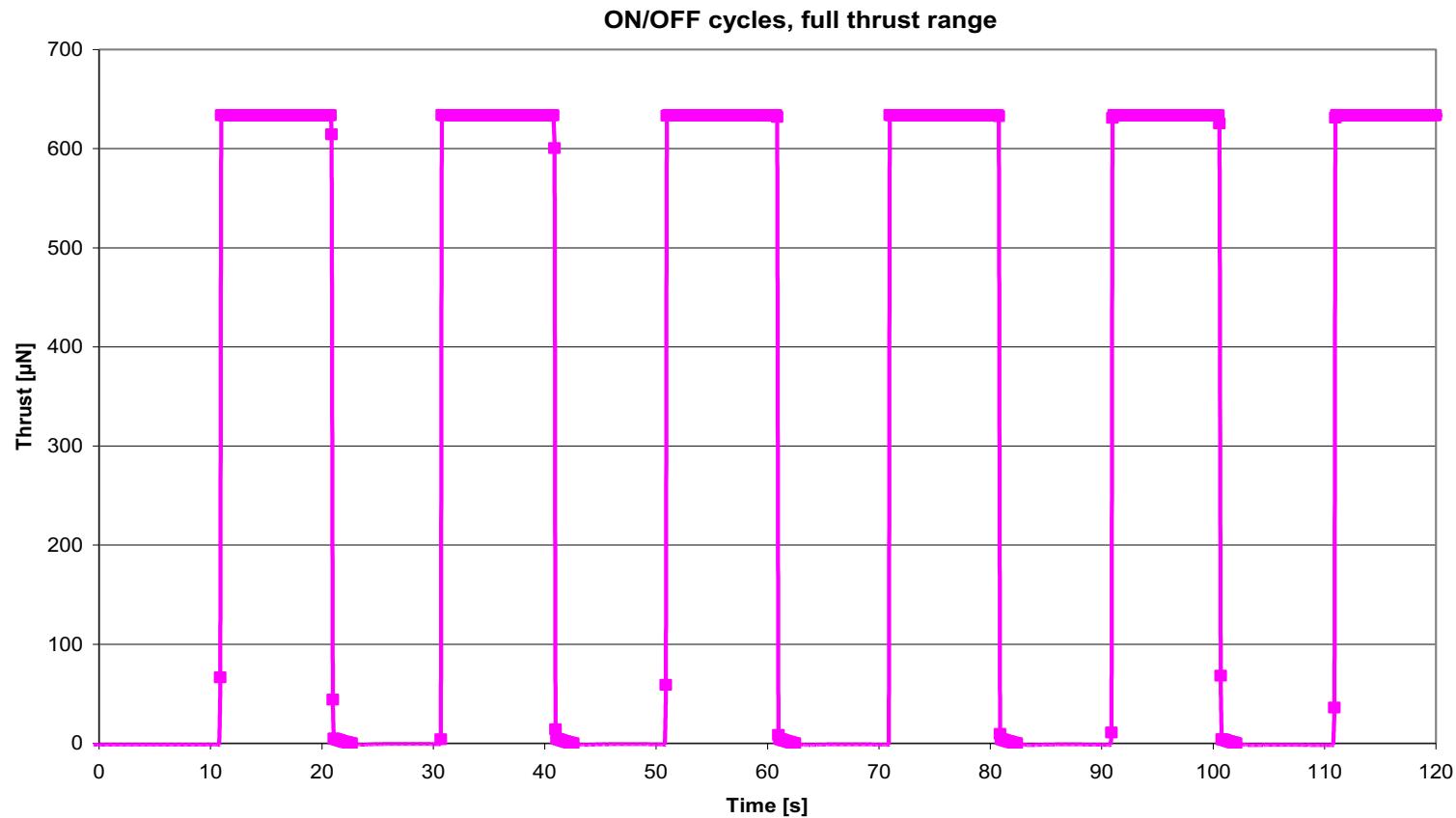


Figure: Test result of MEMS thruster operating in ON/OFF mode (open loop, using solenoid valve only) to show thrust range.

Full thrust can be set in the range **50 micro-Newton to 10 milli-Newton**

# Key capabilities – Unlike any other

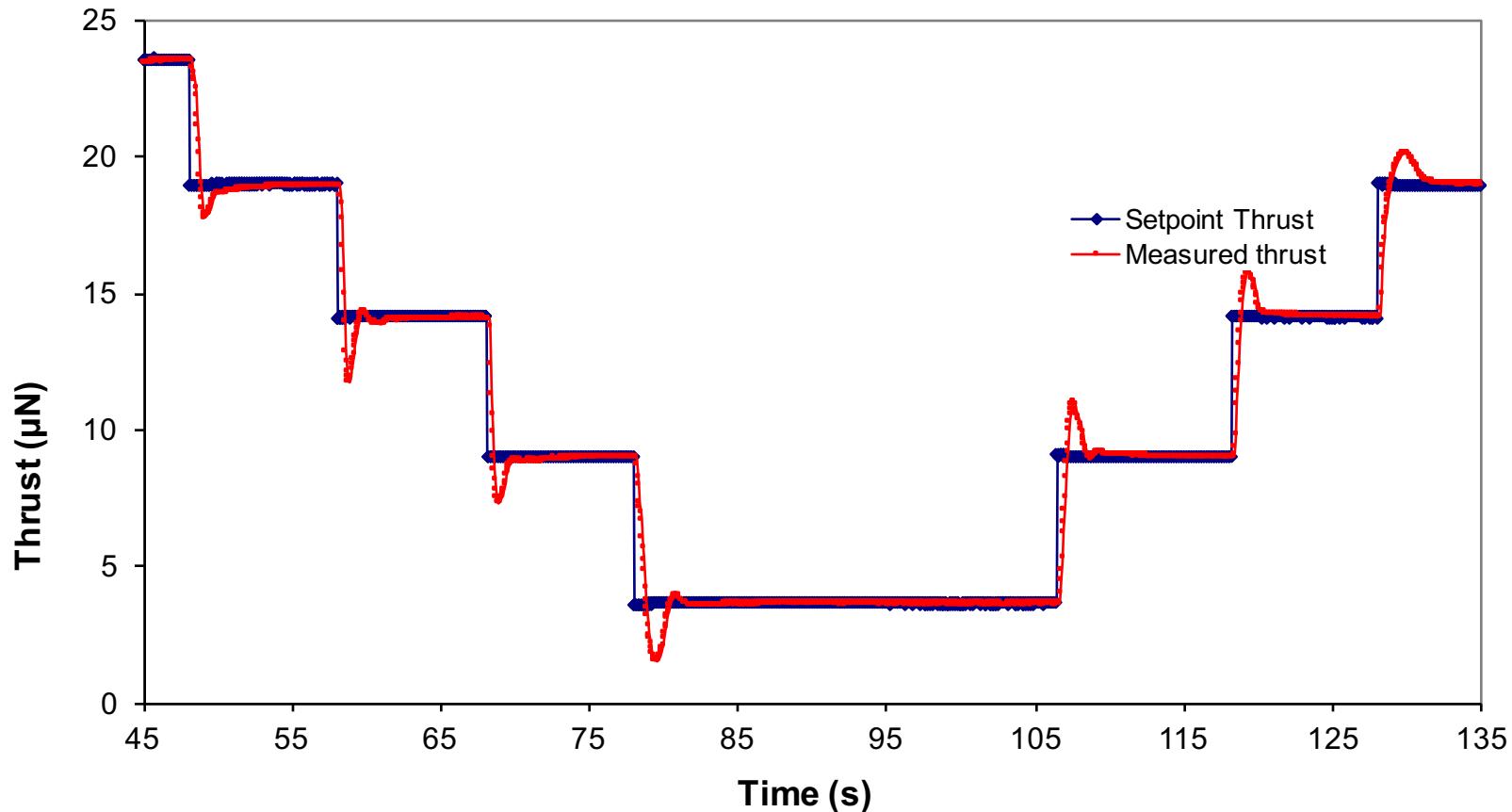


Figure: Test result of a MEMS valve operating in closed loop control mode showing the thrust response to commanded steps of  $5 \mu\text{N}$ .

# Unique performance

Low thrust regime response: 0.1 $\mu$ N steps

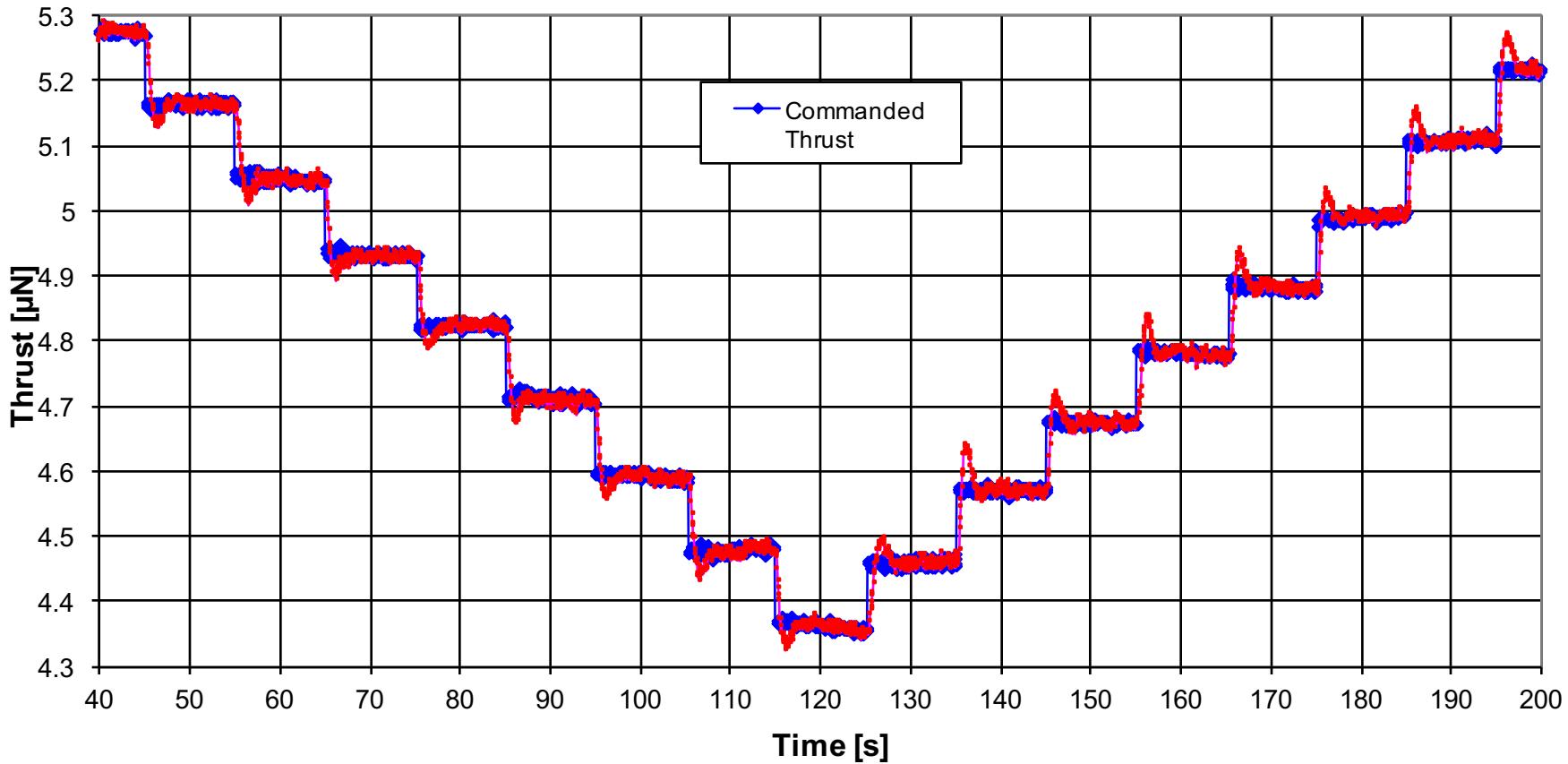
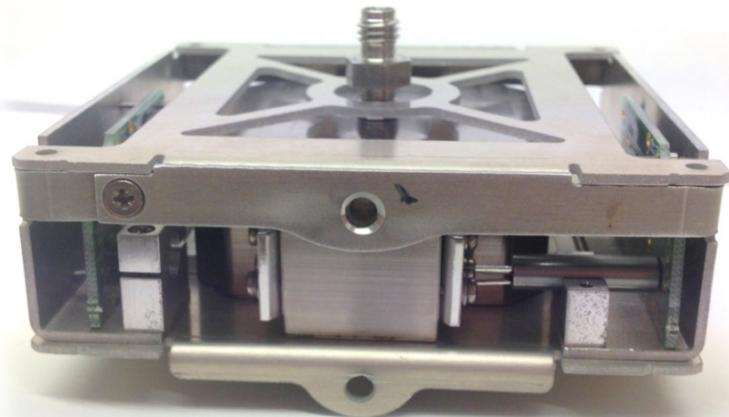


Figure: Test result of a MEMS valve operating in closed loop control mode responding to the commanded steps of 0,1  $\mu$ N.

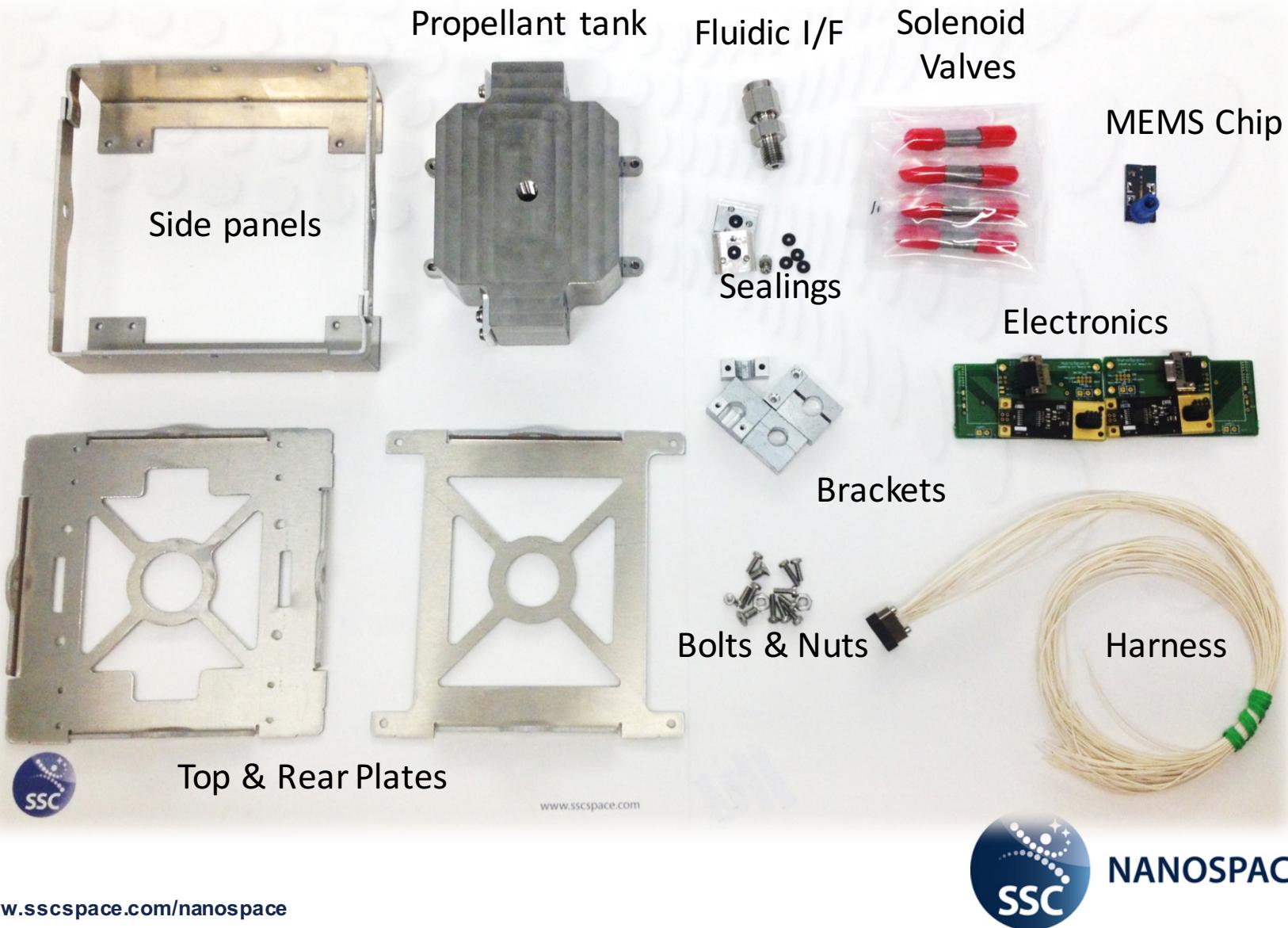
# The CubeSat propulsion module

General specification:

- Four 1mN thrusters with closed loop thrust control
- Thrust resolution:  $<10\mu\text{N}$
- Propellant: Butane
- Total impulse: 40Ns
- Size: 10\*10\*3cm
- Mass: 250g
- Operating pressure: 2-5 bar
- Power consumption: 2 W  
(average, operating)
- Mechanical interface: CubeSat payload I/F (Pumpkin)
- Electrical interface: 52 pins analog (0-12V) and digital (SPI)

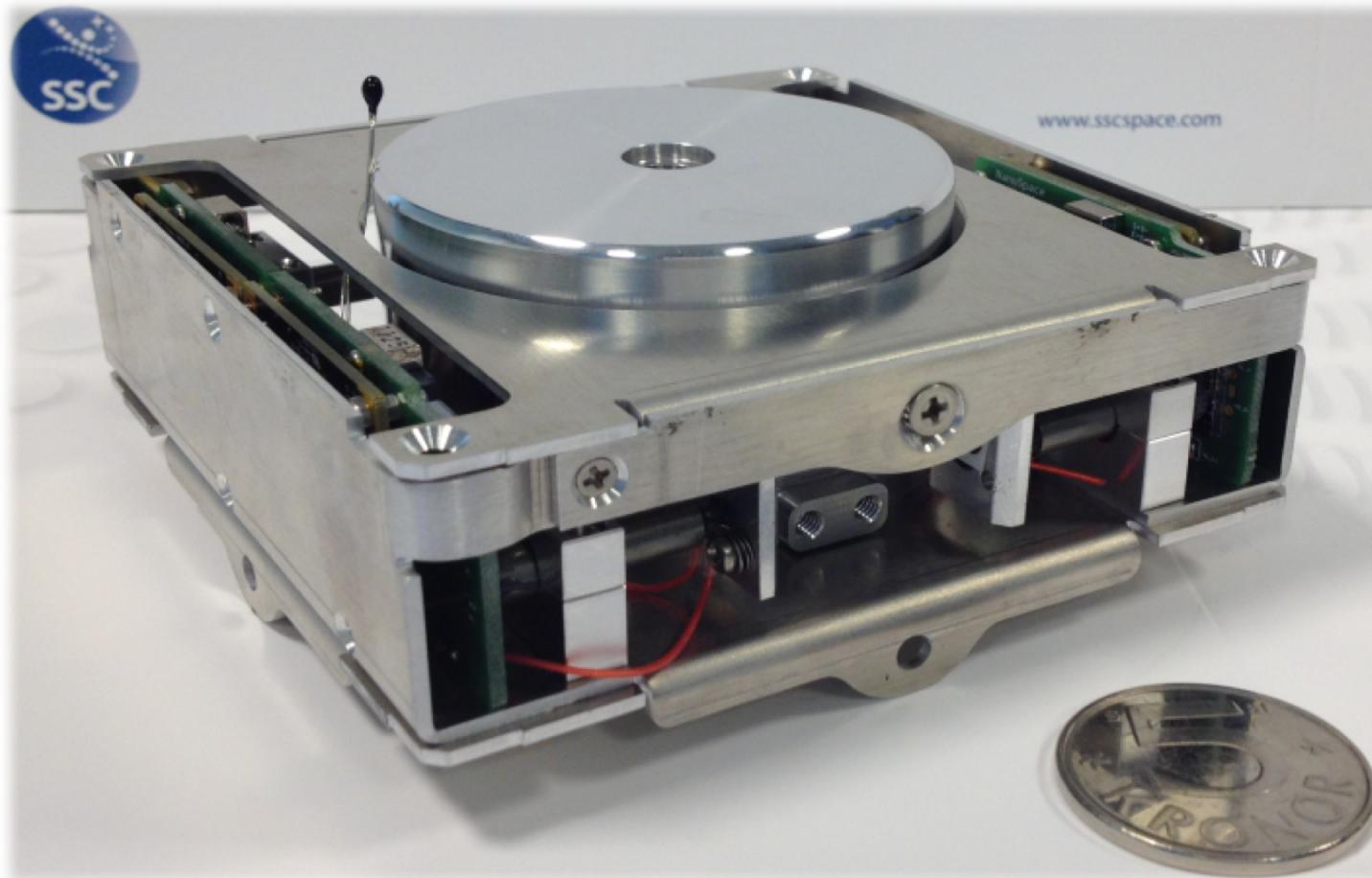


# The propulsion module –in bits and pieces



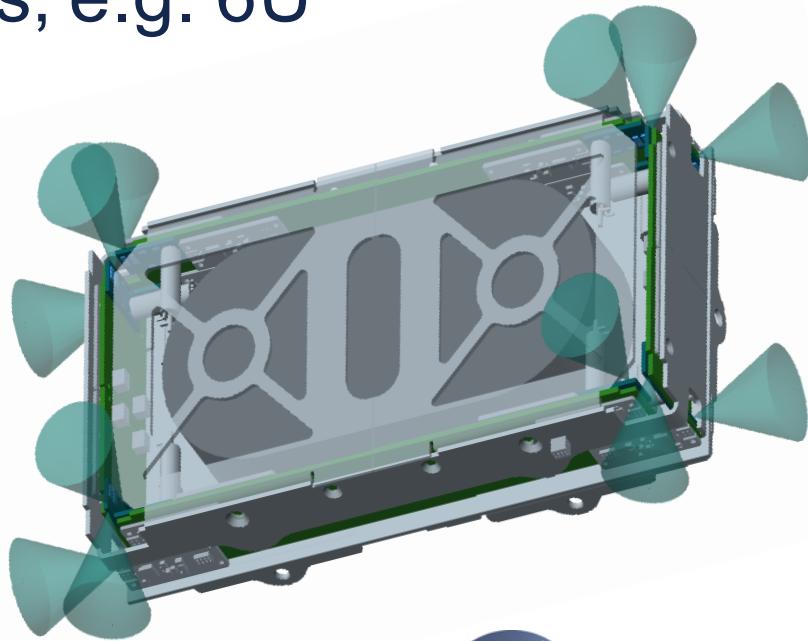
# The “tuna can” design

-following the new CubeSat standard



# Design, specification and performance changes possible

- Thrust levels
- Number of thrusters and thrust directions
- Other CubeSat designs, e.g. 6U
- Tank size
- ...

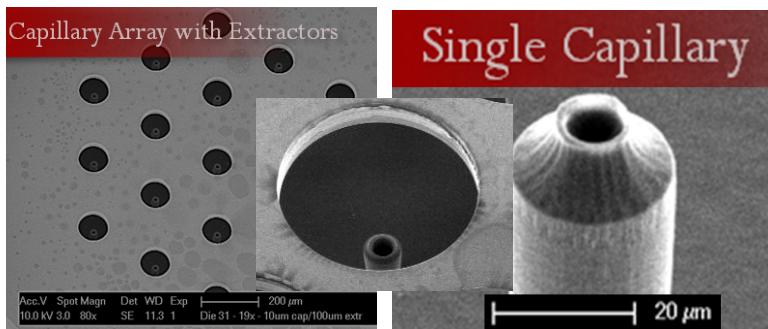
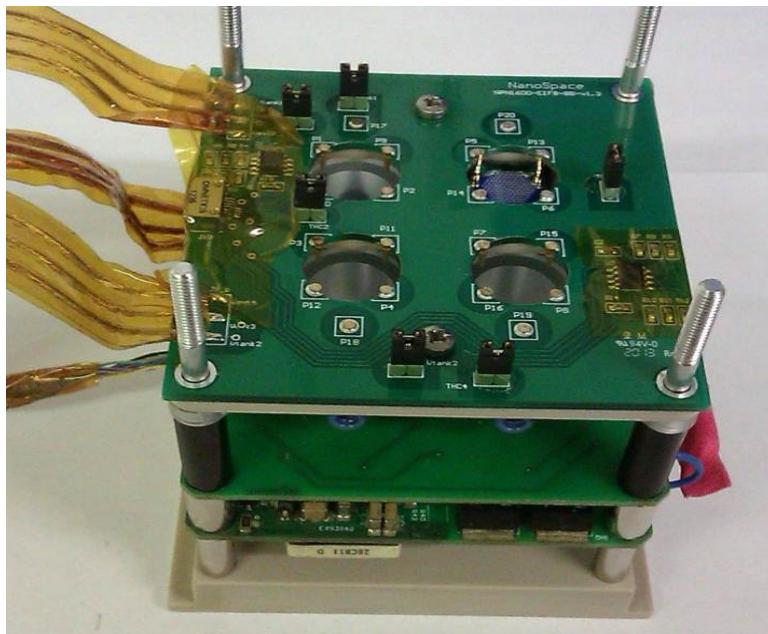


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# MicroThrust: MEMS-based colloid thrusters for CubeSats



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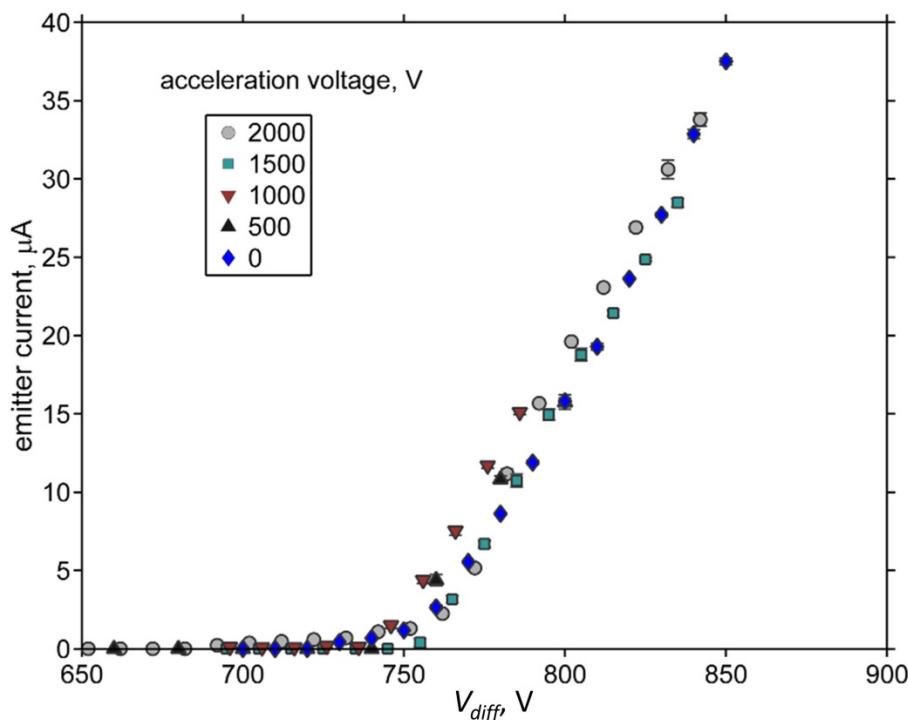
## Specification

Operating media	EMI-BF <sub>4</sub>
Thrust/Power	50 $\mu\text{N}/\text{W}$
Isp	3000 sec
$\Delta v$ (1U)	5 km/s
Lifetime	13 000 hours

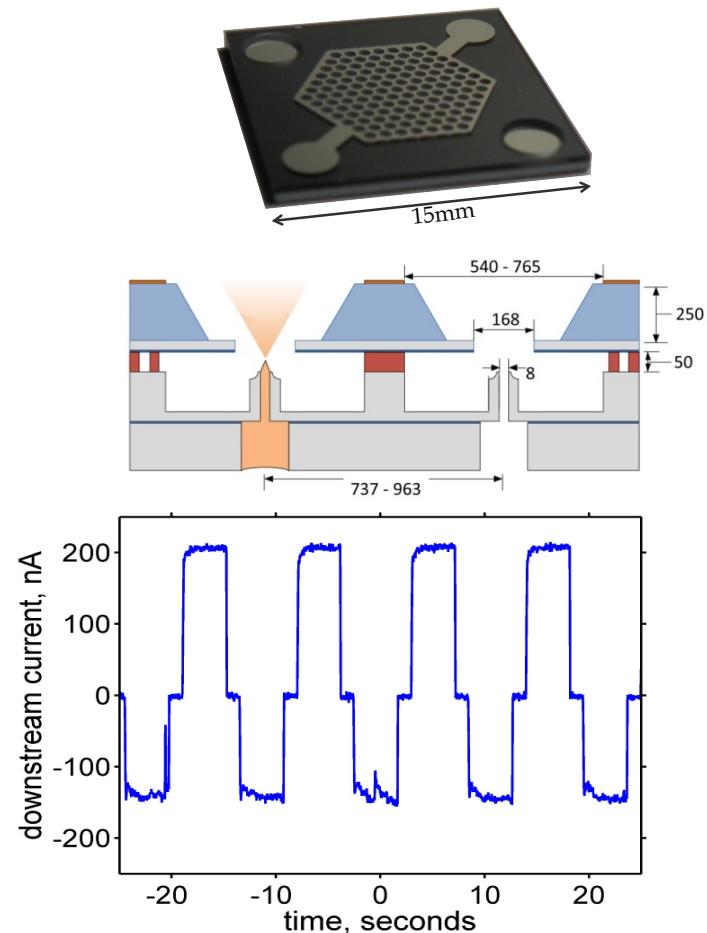


# MicroThrust – Recent Results

- Current-voltage measurements
- Time of flight
- Plume angle measurements



*Variation of emitter current with voltage difference between emitter and extractor, at different acceleration voltages*

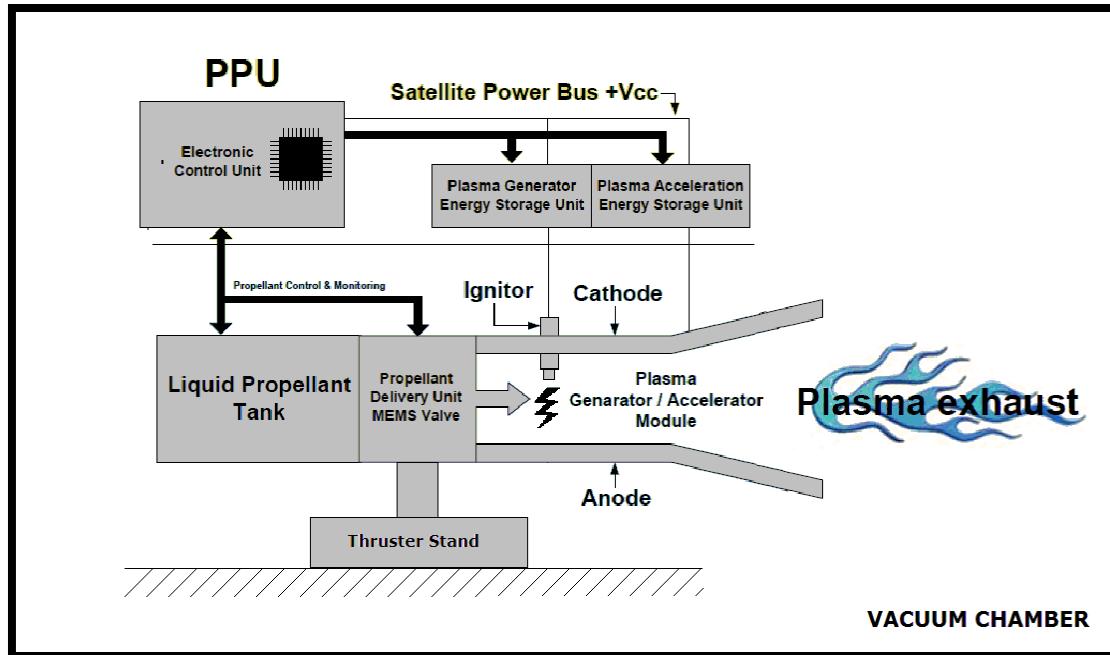


*Bipolar mode operation with 127 emitter array*

# FP7-SPACE-2011-283279: Liquid Micro Pulsed Plasma Thruster



JMP INGENIEROS SL JMP Spain  
NAJERA AEROSPACE SL NASP Spain  
Mecartex SA MECARTEX Switzerland  
IPPLM Poland  
NANOSPACE AB NANOSPACE Sweden  
KOPOOS, France

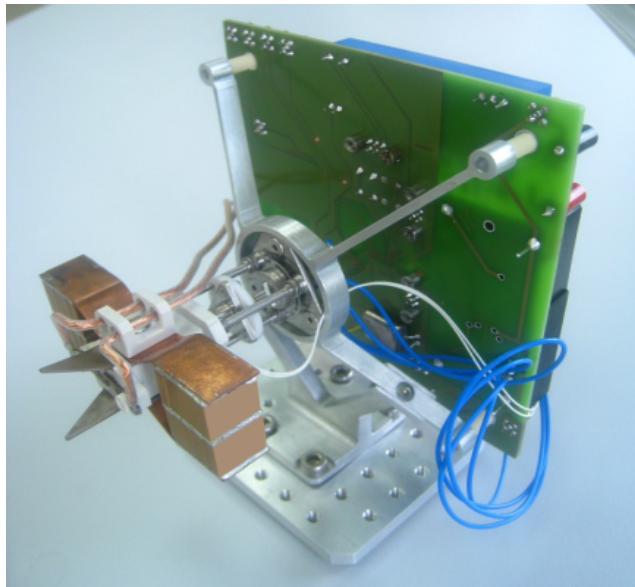


L- $\mu$ PPT system diagram. Propulsion system and its components.

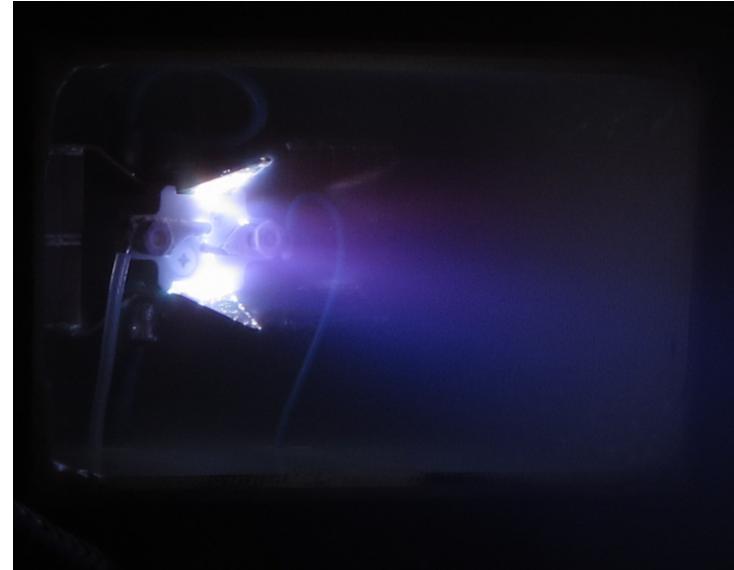
# Liquid micro-Pulsed Plasma Thruster

Funding from European Community's Seventh Framework Programme (FP7/2007-2013) under grant agreement n°283279, the L- $\mu$ PPT project.

- Propellant not limited by geometry: **total impulse much less constrained than Teflon PPTs**
- Steady propellant feed geometry: **no long term drift in terms of impulse bit**
- Propellant balancing capability in multi-thruster configuration: **better utilization of propellant mass**

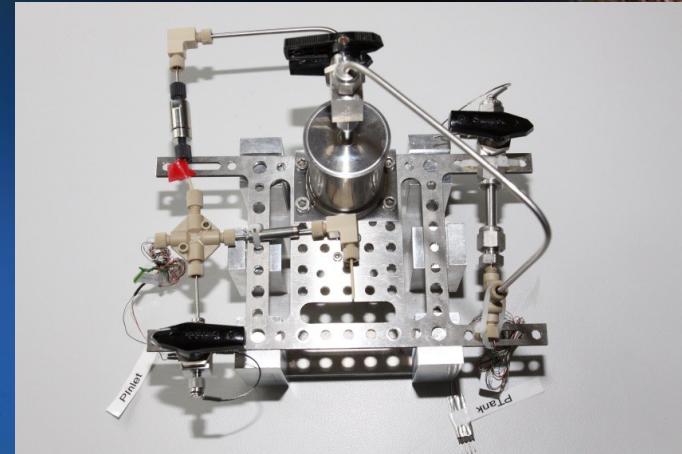
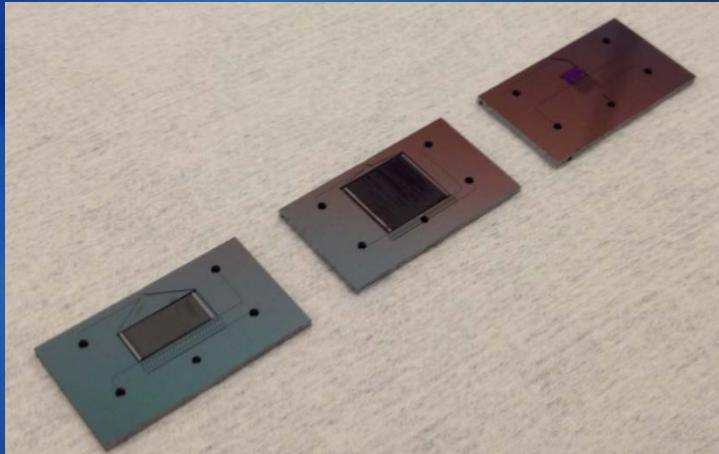
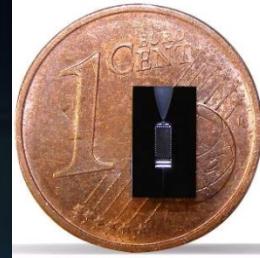


1st european L $\mu$ PPT prototype  
(CubeSat-sized)



Thruster operating 900 V.  
Long exposure photographs over a single discharge.

# PRECISE



PRECISE focuses on the research and development of a MEMS-based monopropellant micro Chemical Propulsion System ( $\mu$ CPS) for highly accurate attitude control of satellites.



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UNIVERSITY OF  
SURREY

University of Twente  
The Netherlands

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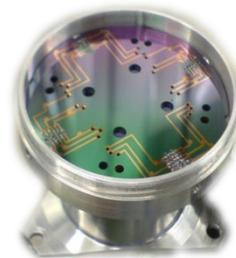
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# SMÖRGÅSBORD ['smørgɔ:s, bu:d]

## MEMS Micropropulsion Components

- First generation MEMS micropropulsion:

- *Miniaturised, accurate and open-loop*



- Next generation MEMS micropropulsion:

- ***Closed-loop control***



Xenon flow control module



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CubeSat propulsion module



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# Swedish lesson #2:



*Manager (informal: boss)*

*Chef [sje:f]*

*Welcome!*



*SSC booth with USN, ECAPS & NanoSpace*

*Thank you!*