



ExoplanetSat:

A Nanosatellite Space Telescope for Detecting Transiting Exoplanets

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- Science
- Concept of operations
- Long term vision
- Spacecraft design
 - Ongoing trades
 - Payload
 - Attitude determination and control
- Hardware test results
- Future Work

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Exoplanet Science & Motivation

- **High-level goal:** Search the brightest Sun-like stars for transiting Earth-size planets
 - Constellation of satellites
 - Bright star search enables follow up characterization studies (vs. Kepler)
- Prototype goal: 3U CubeSat capable of 10 ppm phototometry (7σ detection of Earth-sized planets) for bright (0 ≤ V ≤ 6) Sun-like stars



Why CubeSat form factor for transit searches of bright stars?





Concept of Operation







Long-Term Vision



 Fleet of small satellites (3U CubeSats, 6U CubeSats, EPSA-class) in low-Earth orbit, collectively monitoring hundreds of Sun-like stars



Phase 1:

- Single prototype
- Tech demonstration (arsecond-level pointing)
- Observe alpha centauri (brightest Sun-like star)
- Search for transits of known super Earth exoplanets

Phase 2:

- Add 3U models + 6U models with 120 mm apertures
- Observe 20 brightest stars for Earth-sized transits
- 10-15 spacecraft needed

Phase 3:

- Full planet detection survey
- Seek 95% confidence of 3+
 planet detections
- Observe bright stars to V = 8
- Observe 250 stars
- Expanded fleet



Spacecraft Design









- Mass
 - Currently at approximately 5.5 kg
- Volume
 - Off-the-shelf vs. custom lens
 - Evaluating board layout (PC-104 cards vs. custom PCBs)



- Detector architecture
 - Number and placement of CMOS imagers for star tracking
 - Science detector selection



Payload



- Variation within CCD pixel requires arcsecond-level optical pointing
- Combined star tracker (CMOS imagers) and science telescope (CCD)
 - CCD: Defocused, ≥1 s integration time to collect many photons
 - CMOS: In focus, ≤100 ms integration time to provide frequent updates to estimator



Attitude Determination & Control DRAPER (



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ADCS Testing



- Hardware in-the-loop test
 - Successful proof-of-concept demonstration of fine pointing stage: 2.3 arcseconds (3σ)
 - Inject simulated residual pointing errors from reaction wheels using star field emulator
 - Correct for pointing errors on spacecraft emulator with lens, detector, piezoelectric stage





Future Path



- ADCS hardware-in-the-loop test bed
 - Spherical air bearing
 - Two-stage control functional demo (piezo stage + reaction wheels in the loop)
- Payload
 - Intrapixel sensitivity measurements
 - Mature science data processing pipeline
- Avionics development
 - FPGA + Microcontroller architecture
- "Bus" subsystems currently at varying levels of maturity
 - Power Comm
 - Structure Thermal
- Environmental testing at Draper, MIT, NASA GSFC
- Goal: launch in 2012-13 time frame
 - Selected under NASA CubeSat Launch Initiative in January, 2011

MIT 3DOF spherical air bearing test stand





Conclusion



- ExoplanetSat will combine the low-cost CubeSat platform with two-stage attitude control to detect Earthsized planets around the brightest stars
 - The 3U prototype is under development with a potential launch date through the NASA CubeSat Launch Initiative
- Key engineering breakthrough: very high precision pointing (arcsecond-level) in a CubeSat
- ExoplanetSat initiates the graduated growth of a modular, extensible constellation, with the final phase being many satellites surveying bright stars for other Earths





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