



PEARL CubeSat Bus Building Toward Operational Missions

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Building Toward Operational Missions

▶ Proven Value

- CubeSats have proven they can perform valuable scientific missions

▶ New Interest

- Significant interest has been generated within the scientific community, with both funding agencies and principal investigators

▶ New Platform to Meet New Interest

- SDL has evaluated the needs of the science community and is developing a CubeSat platform for the higher-end science mission

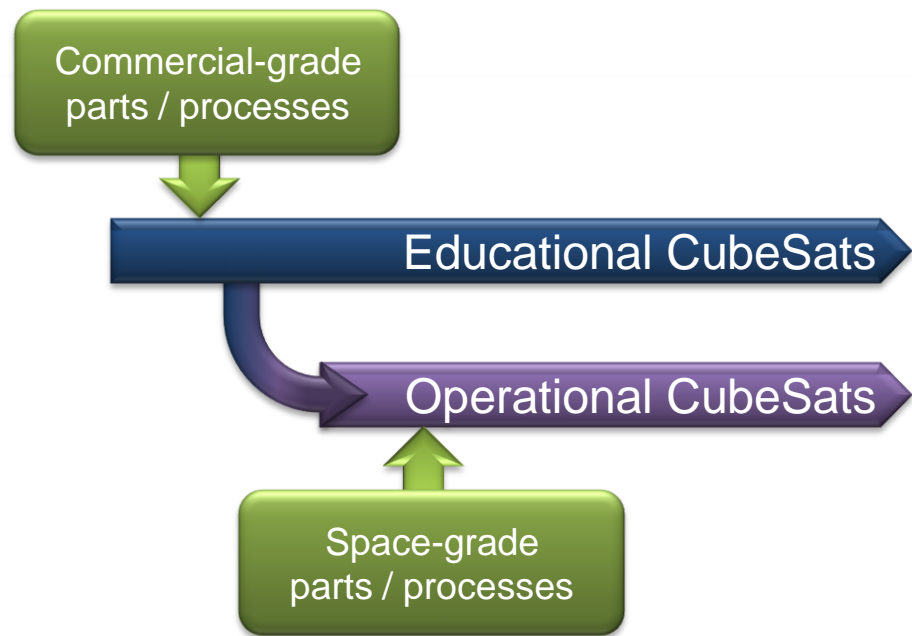
Higher Capabilities – Different Mindset

► Operational missions tend to push the capability envelope

- More power
- More processing capability
- Higher data throughput
- Better pointing control
- Higher reliability
- Longer mission lifetime

► Operational missions tend to require a different mindset

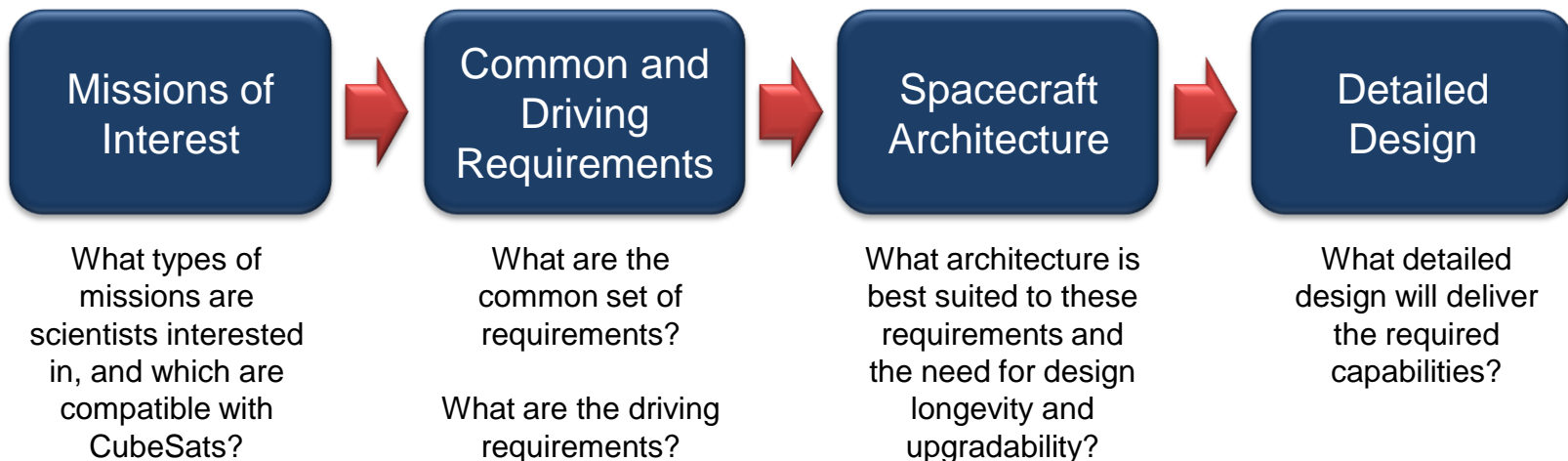
- Requirements-based design
- Quality standards/certifications
- Traceability
- Risk averse
- Higher profile, higher cost, higher payoff



Requirements/Capabilities Traceability

► Design based on requirements and mission needs:

- Design CubeSat platform with capabilities traceable to scientific mission needs
- Architecture must be flexible and adaptable to support multiple mission types
- Architecture must be upgradable to incorporate new capabilities as they are developed



Missions & Mission Needs

▶ **Technology Demonstration Mission**

- Just needs to be in space

▶ **Simple Science Mission** (simple mission, not simple science)

- Pointing control requirements are low
- Processing requirements are low
- Data requirements are low

▶ **Sophisticated Science Mission**

- Higher pointing control requirements
- Higher processing requirements
- Higher data requirements

Next Step for CubeSats

▶ **Operational Mission**

- High reliability (higher quality parts, traceability, QA, etc.)
- Longer design life (higher quality parts, more radiation tolerance)

Approach Summary

Follow CubeSat standard, but not “commercial” philosophy

- ▶ The CubeSat standard and philosophy were designed for educational use
 - Very effective
 - Very well adapted for the educational missions they were designed for

Challenges*:

- Moving from academic to industry model
 - Industry/Government Customers
 - Higher Performance/Cost Satellites
 - Increased Quality Required
 - Potential Cost Increases

* Jordi Puig-Suari, CubeSat Developers Workshop 2009

- ▶ The SDL approach:
 - Follow the CubeSat standard (it's still very effective)
 - Incorporate the reliability, parts quality, performance, and design rigor required of high-profile, operational missions

Design Approach

► Meet Increased Process and Capability Requirements

- Reliability
 - Space and military grade parts
 - NASA certified parts program
 - Certified assembly and testing processes
 - Traceability
- Performance
 - Increased pointing knowledge and control
 - Increased processing capability
 - High throughput data bus
- Environmental tolerance (especially radiation)
- Design rigor
 - Configuration control
 - Risk tracking
 - Detailed analysis, worst-case analysis, failure modes analysis
 - Design reviews
 - Design verification



Environmental Tolerance

- ▶ **End-goal is to migrate to all space-grade components**
 - Higher reliability in space environment
 - Increased radiation tolerance
 - Longer mission life
- ▶ **Architecture and form factor allow for migration**
 - Increased size of the card allows for the larger components
 - PCI architecture has space flight heritage and larger selection of space parts to choose from
- ▶ **Incrementally improve parts quality in each card design**
 - Begin with CPU card

PEARL* Architecture

► Modular Chassis Sections

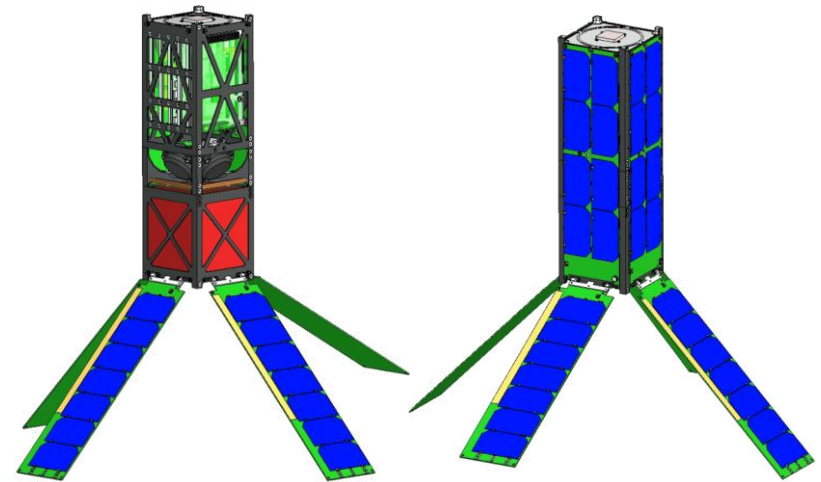
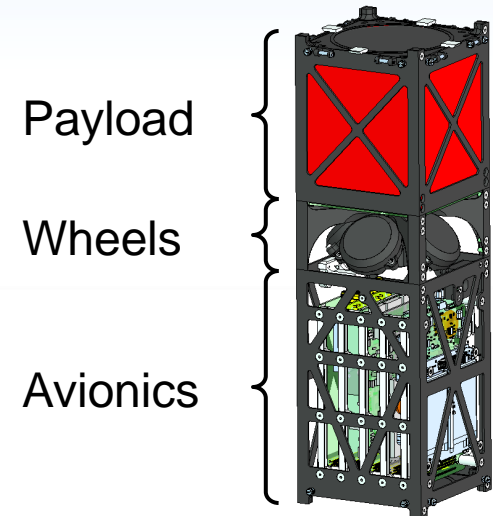
- Payload Chassis: 1.0 U
- Reaction Wheels: 0.5 U
- Avionics Chassis: 1.5 U

► Monolithic Aluminum Structure

- Utilize efficient on-site advanced machining practices
- Maximized strength-to-weight ratio

► Solar panel arrays

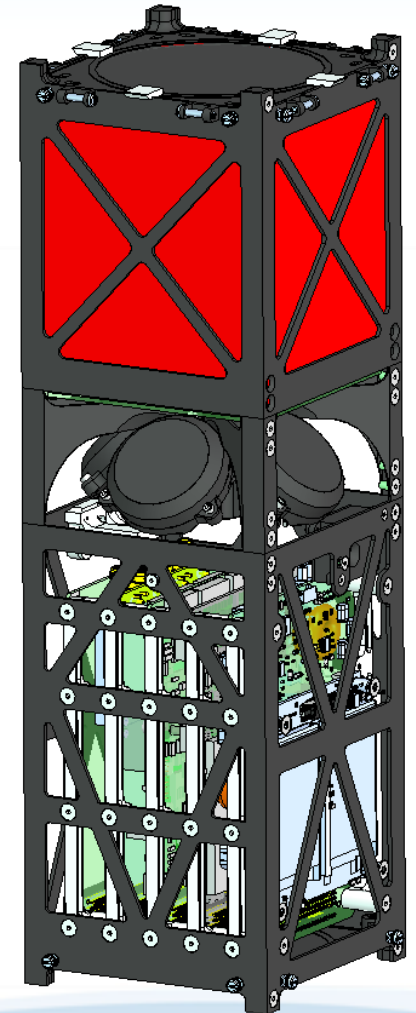
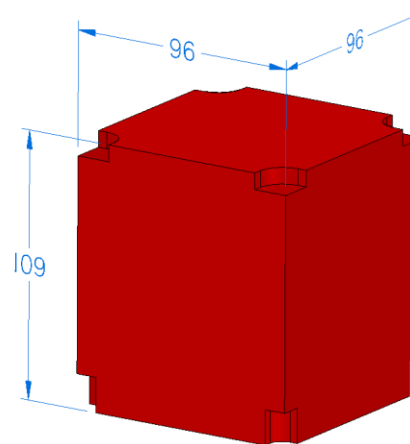
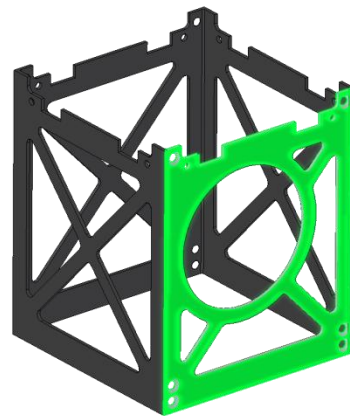
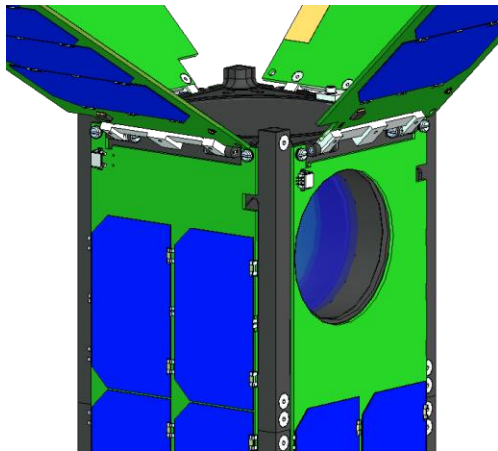
- 4x stationary
- 4x deployable with adjustable deployment angle



* PEARL development is sponsored in part by the Air Force Research Laboratory (AFRL)

Payload Support

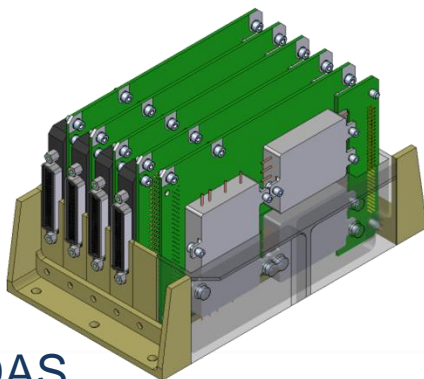
- ▶ 1U available for payload + 1 PCI card in avionics
- ▶ Up to 1Kg of payload mass
- ▶ Up to 2W continuous for Nadir Pointing mission
- ▶ Chassis modifications possible to support viewing
- ▶ Mounting bosses on top and bottom corners
- ▶ Chassis sides can support additional mounting points



Avionics Layout

► Vertical vs. Horizontal Card Stack

- Data throughput and processing requirements meant the data bus architecture had to change
- Chose to leverage off of existing space-designed avionics targeted for Plug-and-Play distributed small satellite applications (MODAS)
- Same card standard can be used in both applications
- Significant harness improvement – connectors for all cards are located in a harness set-aside volume at top of avionics stack



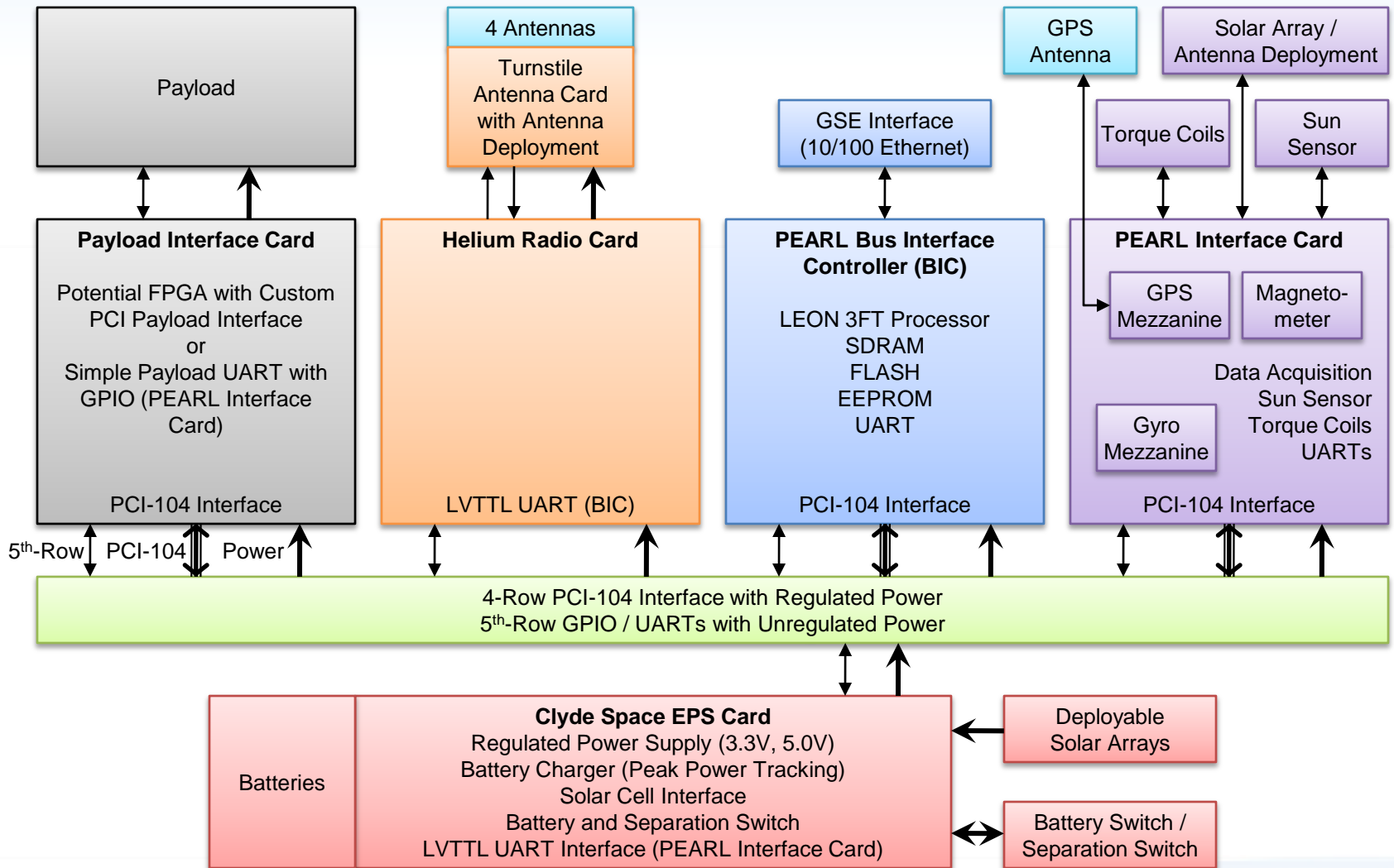
MODAS



PEARL

- 5 cards plus batteries
- 1 card reserved for payload
- Modified PCI-104 form factor
 - CPU
 - EPS
 - Transceiver
 - ADCS Interface
 - Payload

PEARL System Block Diagram



Bus Architecture & Processor

► PEARL uses an industry standard PCI bus architecture

- 33 MHz, 32-bit,
- LEON 3FT general purpose CPU
- Serial Ports: UART, SpaceWire, Ethernet
- IEEE-754 Floating Point Processor
- Electrically compliance: PCI-104
- CPU Radiation Tolerance: 300Krad
- Memory (EDAC Protected + radiation test data)
 - SDRAM: 128M bytes
 - EEPROM: 512K bytes
 - Flash: 512M bytes
- Upgrade path to 100Krad(Si) tolerance for the entire card



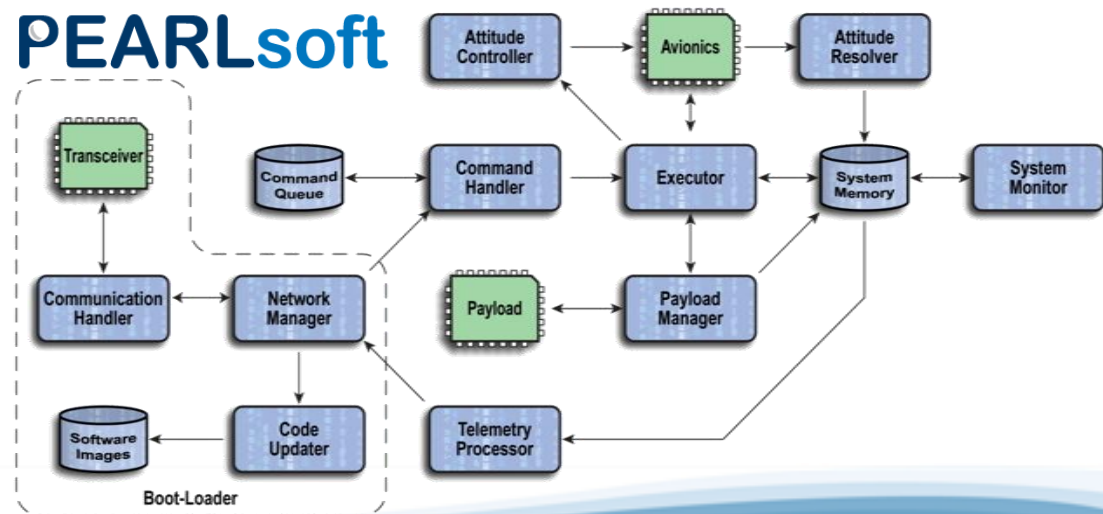
PEARLsoft Flight Software

► Real-time flight software

- Adapted from software currently flying on NASA AIM-SOFIE mission
- Supported by VxWorks 6.5
- ISO-9001 Development process with configuration control

► Multi-threaded architecture to provide design modularity

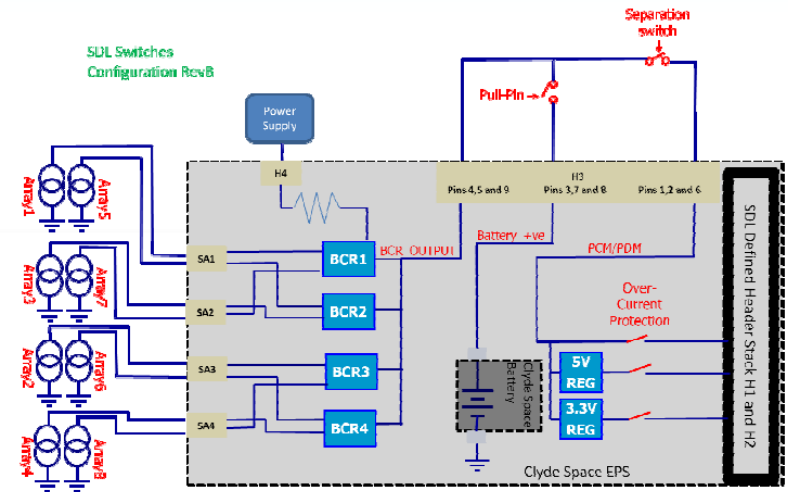
- High level of reuse
- Adaptable for broad range of mission requirements
- The following separate threads enable easy modification:
 - Communications
 - Attitude Control
 - Payload Management



EPS & Communications

► Electrical Power System

- Extended PCI-104 form factor
- Clyde Space Peak Power Tracking system
- Max Power: 36W
- Input voltage: 10 – 25 Volts
- Efficiency: > 90%
- 4 Lithium Polymer: 8.2 Volts, 2.5 A-hr
- Solar Array: 4 body mounted, 4 deployable



► Transceiver

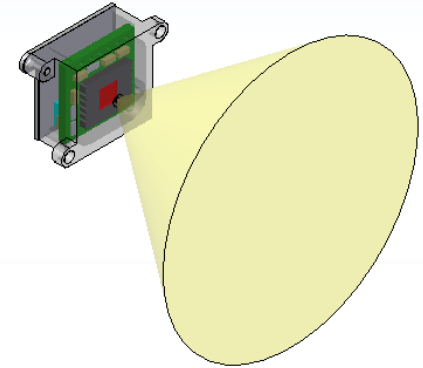
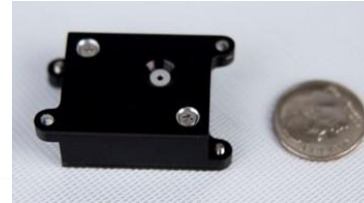
- Extended PCI-104 form factor
- Astronautical Development He-100
- Uplink/downlink: UHF, 9600 baud (higher rates available)
- Output Power: 100 mW to 3W
- UHF antennas embedded in solar array panels



Attitude Control

► Higher accuracy sensors

- Miniature Sun Sensor
 - 72° full-angle field of view
 - Targeted accuracy to 0.01°
 - Very low power
- Star Camera / Star Tracker



► Kalman-filter based attitude and attitude rate determination

- Used to estimate error sources
- Provides attitude control solution for entire orbit (including eclipse)
- Variable number of states to match available processing and desired accuracy
- Steady-state Kalman filter option for significantly reduced computational complexity

► Reaction wheel assembly

- Compact ½U size
- 4-wheel pyramid layout
- Space-compatible lubricants and control electronics

Summary

- ▶ **More sophisticated operational missions are possible**
 - Higher performance
 - Higher reliability
 - Longer life
- ▶ **SDL's PEARL spacecraft is designed to support these missions**
 - LEON 3FT processor with Vx Works and PEARLsoft
 - PCI-104 data bus
 - Attitude control improvements
 - Transitioning to space-grade parts
 - Quality controls and traceability
 - Operational design philosophy