

#### ITÜ NXG – Scaling Up for Low-Cost Science

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#### Payload/s might require something bigger (in terms of volume, power etc.)





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### What Carries On?

With Little Modification
OBDH, Power, Comms
With Some Modification
ADCS
Experience





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# Launch Standardized Adapters Time-frame might be >2 years





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### Example Missions

| Mission   | Timeline  | No of S/C   | Mission  | Orbit   | Constellation<br>/ Formation | Constellation/Formation<br>Size  | Relative Positioning<br>Accuracy  |
|-----------|-----------|---|--|---|------------------------------|--|---|
| EO 1      | 2000      | 2 (1 is the target to<br>be followed - already<br>in orbit) | FF Testing by following a known s/c  | Follows Landsat 7 -<br>700km  | Formation                    | 450km (60 seconds<br>between s/c)  | 20m   |
| Cluster   | 2000      | 4   | Mapping the Magnetosphere  | 19000 - 119000 km   | Constellation                | 200-18000 km   | ?   |
| GRACE     | 2002      | 2   | Mapping the Gravity Field of Earth   | 500km polar   | Constellation                | 220km  | 0.01mm (GPS and<br>mirowave ranging)  |
| ST5       | 2006      | 3   | Mapping the Magnetosphere  | 300x4500km Sun-<br>Synchronous  | Constellation                | 40-200km   | 5m in Leo, 100m RMS in<br>GEO   |
| PRISMA    | 2008      | 2   | FF & Rendezvous Demo (uses GPS<br>for FF, VBS + GPS for rendezvous,<br>tests RF metrology) | 700 km  | Formation                    | 5km -> 0m  | 5m(initial)/GPS   |
| TanDEM-X  | 2009      | 2 (Will fly in<br>formation with<br>TerraSAR - X)           | Bi-Static and ATI SAR  | 514 km polar  | Formation                    | 200 - 2000m  | 2-4 mm  |
| MMS       | 2013      | 4   | Studying the Magnetosphere   | 4 phases, varies<br>between 1.2 R <sub>E</sub> -12 R <sub>E</sub> ,<br>10R <sub>E</sub> - 40 R <sub>E</sub> | Tetrahedron<br>Formation     | Phase 1,2 - 1000 -<br>2000km, Phase 3,4 - on<br>the same orbit (string of<br>pearls) a few R <sub>e</sub> 's | 100m(using GPS and xlink<br>ranging(probably RF)) -<br>also uses GS doppler in<br>phase 1 |
| DARWIN    | 2015      | 4   | Deep Space Optical/Infrared<br>Interferometry  | L2  | Formation                    | 1200m  | Sub millimeter(Laser metrology)   |
| LISA      | 2018      | 3   | Gravitational Wave Detection   | 1 AU, 20 deg phase<br>behind Earth  | Formation                    | Triangle, 5 000 000km  | TBD   |
| PROBA 3   | TBD       | 2   | Validate GPS + RF metrology, test<br>coarse & fine optical metrology                       | 600-36000km (GTO)   | Formation                    | 200-400m   | cm range (0.1mm in optica<br>metrology test)  |
| XEUS      | TBD       | 2   | X-Ray Spectroscopy   | L2  | Formation                    | 35m  | 0.1mm (laser metrology)   |
| TechSat21 | Cancelled | 3   | SAR demo   | 550km   | Formation                    | 500m   | 10cm(DGPS)(1 cm before<br>data collection by various<br>techniques)                       |



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#### Formation Keeping Accuracy vs. **Formation Size** Magnetospheric Studies 100 m MMS Cluster II Formation Keeping Accuracy 50 m ST5 EO 1 Technology Demonstrators - (SAR, relative navigation) 10 m TanDEM-X Deep-Space Observation PRISMA < 1mm PROBA 3 GRACE XEUS DARWIN LISA 1 m 100 m 1 km 1000 km > 10000 km Relative Distance Istanbul Technical University - Faculty of Aeronautics and Astronautics



### Technology Drivers

- Relative navigation and attitude sensing
- Relative motion dynamic modeling
- Fleet level control and coordination
- Inter-s/c comm. for interoperation and time synch
- On-board intelligence and faulttolerance





#### Example Requirements for high-resolution InSAR

- Meter level height resolution cm
   level Baseline accuracy
- o 0.01° attitude control
- 2.5 x 10<sup>-12</sup> s clock stability
- o 10<sup>12</sup> flops on-board for 1m resolution





### What will the mission do?

 Demonstrate and space mature technologies necessary for tightly controlled FF

Examine flexible s/c structures





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#### Mission Modes

| Modes                            | Experiments   | Precision                               |  |
|----------------------------------|---|---|--|
| A: Launch Configuration          | Orbit Checkout & System Verification                          |   |  |
| B: Flexible Monolithic Structure | Coordinated Attitude Control of Flexible Structures           | <0.1° control                           |  |
|                                  | High Precision Relative Positioning & Attitude Metrology Test | 10 µm relative distance knowledge       |  |
|                                  | Cross - Navigation Verification                               | 5 - 0.05 mm relative distance knowledge |  |
| C: Free Formation Flight         | Precision Formation Planning and Control                      | < 10 cm relative distance control       |  |













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#### Mission Modes - 2







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## System Overview - 2

| System Overview              |                            |                                |        |               |  |  |  |
|------------------------------|----------------------------|--------------------------------|--------|---------------|--|--|--|
| Spacecraft                   |                            | ADCS                           |        |               |  |  |  |
| Power<br>Mass                | 8.5 W on average<br>9.5kg  | <u>Sensors</u><br>Magnetometer |        |               |  |  |  |
| Volume                       | 20*20*20cm <sup>3</sup>    | IMU                            |        |               |  |  |  |
| OBDH                         |                            | GPS                            |        |               |  |  |  |
| Storage                      | 1Gbit                      | Star Tracker                   |        |               |  |  |  |
|                              |                            | Actuators                      |        |               |  |  |  |
| Comm                         |                            | 3 reaction wheels              |        |               |  |  |  |
| Cross-Link                   | Wireless Ethernet          | <u>Thrusters</u>               |        |               |  |  |  |
|                              |                            |                                | ΔV     | Thrust Levels |  |  |  |
| Up/Downlink                  | S Band Transceiver         | 12 μPPT                        | 60 m/s | 20µN          |  |  |  |
| -                            |                            | 7 cold gas thrusters           | 30 m/s | 50mN          |  |  |  |
| Power                        |                            |                                |        |               |  |  |  |
| GaAs Cells<br>Li-Ion battery | 0.1 m <sup>2</sup><br>10Ah |                                |        |               |  |  |  |



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http://usl.itu.edu.tr

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# Initial Analyses – Disturbance Rejection via LQR





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# ITÜ pSAT I Brief Update



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### • • Example Pictures





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#### Antenna Opening







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#### • • After Thermal & TV Tests







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### Ground Station





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### Remaining Work

Shake & TV tests of complete satellite
Finish operational software

RF Tests

 Ground station test during a real launch!





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### Thanks for your time!

#### We'd like to acknowledge our sponsor; Scientific and Technological Research Council of Turkey







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