

POLYSAT

A University CubeSat Story



California Polytechnic State University, USA

PARIN PATEL

BRYAN KLOFAS

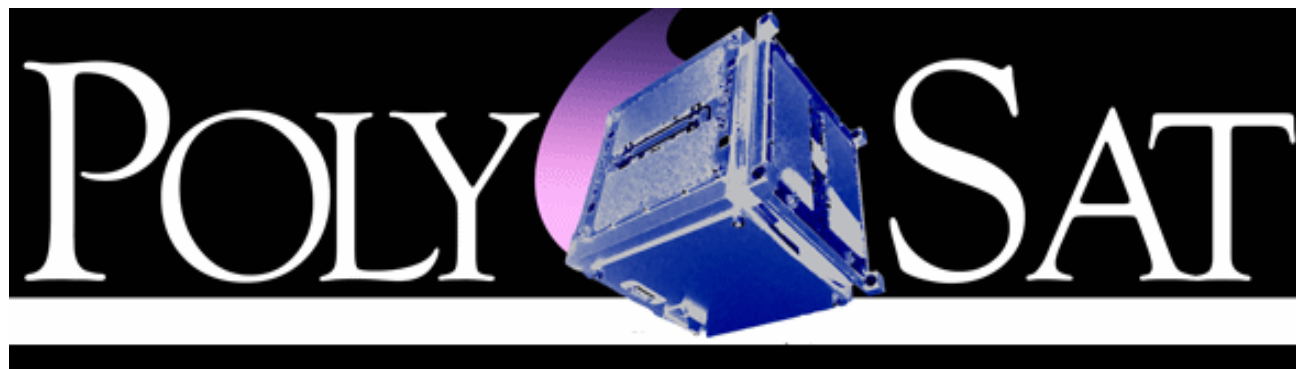
CubeSat Developer's Workshop

The Boeing Company, Huntington Beach California

April 20th 2007



- Started in 1999 by a Multidisciplinary Team of Engineering Students
- Objective: Engineering Education
- Objective: Provide a reliable bus system to allow for flight qualification of a wide variety of small sensors and attitude control devices.





- Magnetorquer developed by Cal Poly
- Third party Sun Sensor


- DNEPR 1 launch failure: July 26th 2006
 - No in orbit operations

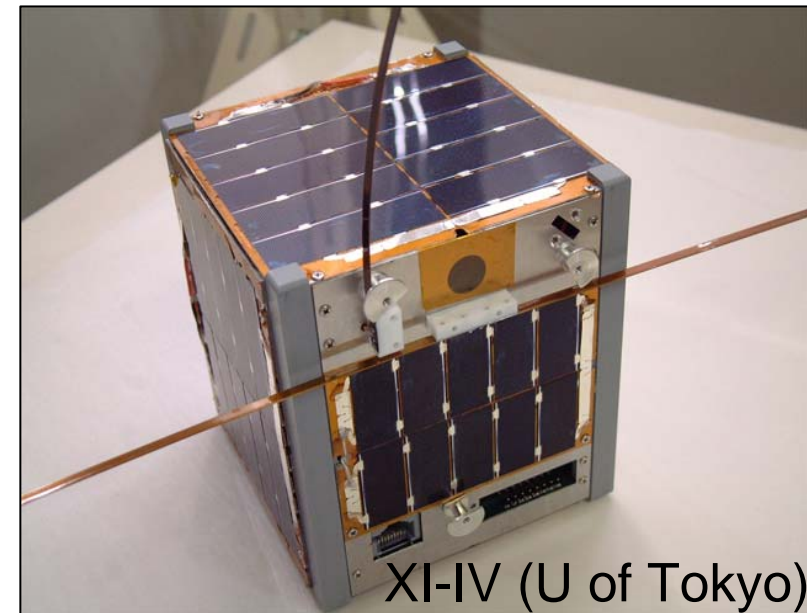
- Valuable lessons learned
 - CubeSat development: challenges & logistics
 - Non-Reoccurring Costs: Multiple Flight Units



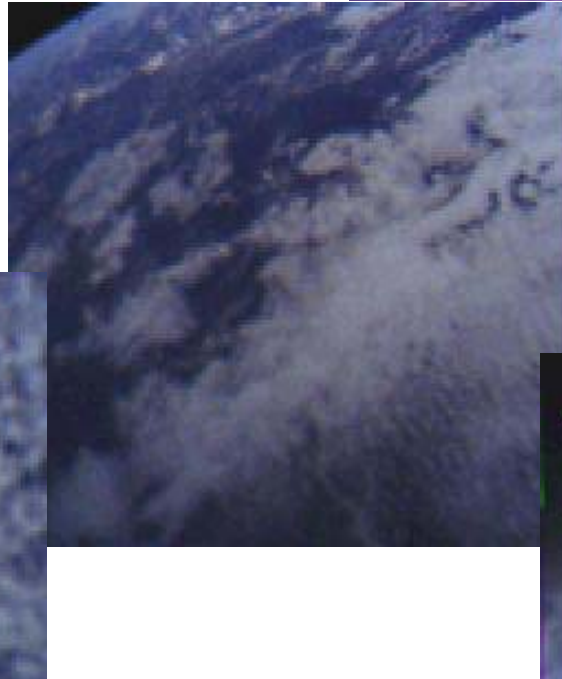
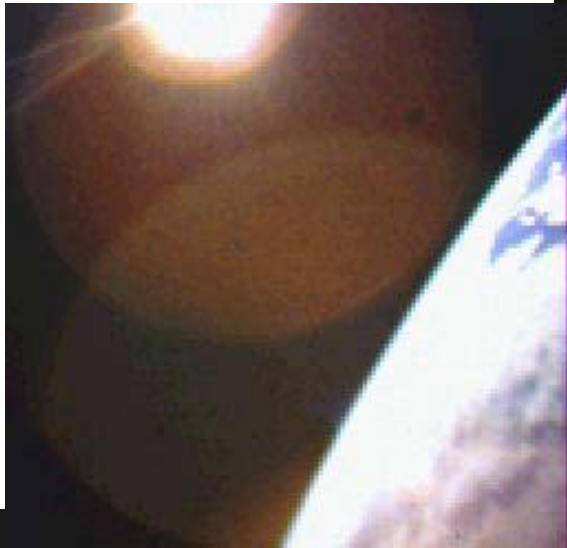
Operations Experience



- Training Objectives
 - Successfully make contact with a CubeSat
 - Download and decode AX.25 digital data.
- Trans-Pacific Collaboration with University of Tokyo
- Autonomous Beacon 
 - Locating the CubeSat after deployment
 - Acquisition of signal
 - Health status / contingency mode
- Normal CubeSat
 - 1/2 to 1 watt RF
- U of Tokyo (XI-IV)
 - Only 80 mW beacon: Morse Code
 - Comes in crystal clear!



XI-IV Images

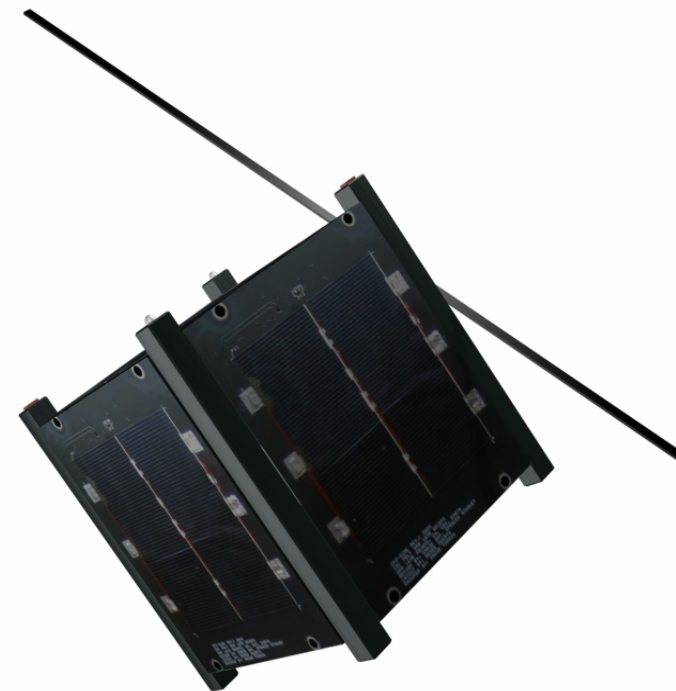
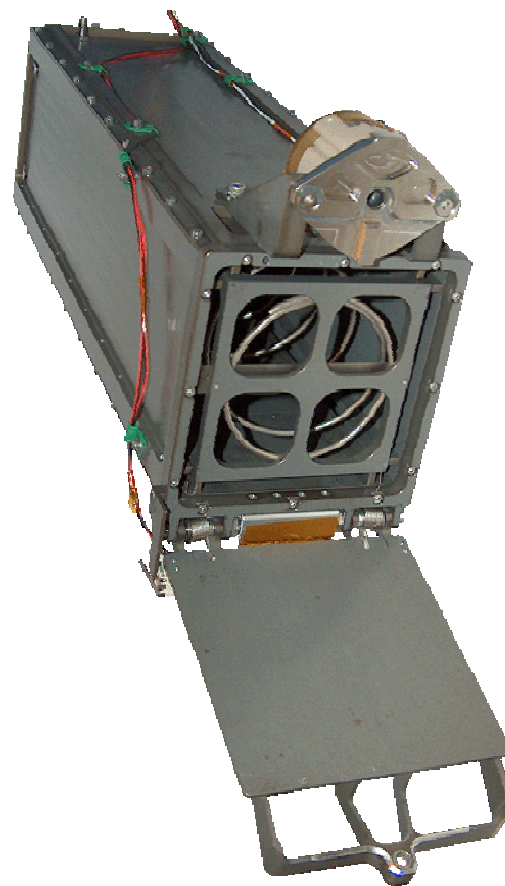


Downloaded Earth Images: <http://polysat.calpoly.edu/EarthNetwork.php>

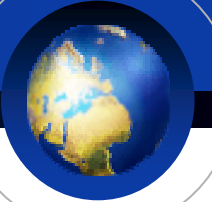
Deployment to First Contact



- Launch
- P-POD deployment
- Antenna deployment
- First beacon
- First possible pass
- First contact



DNEPR 2 – April 17th 2007



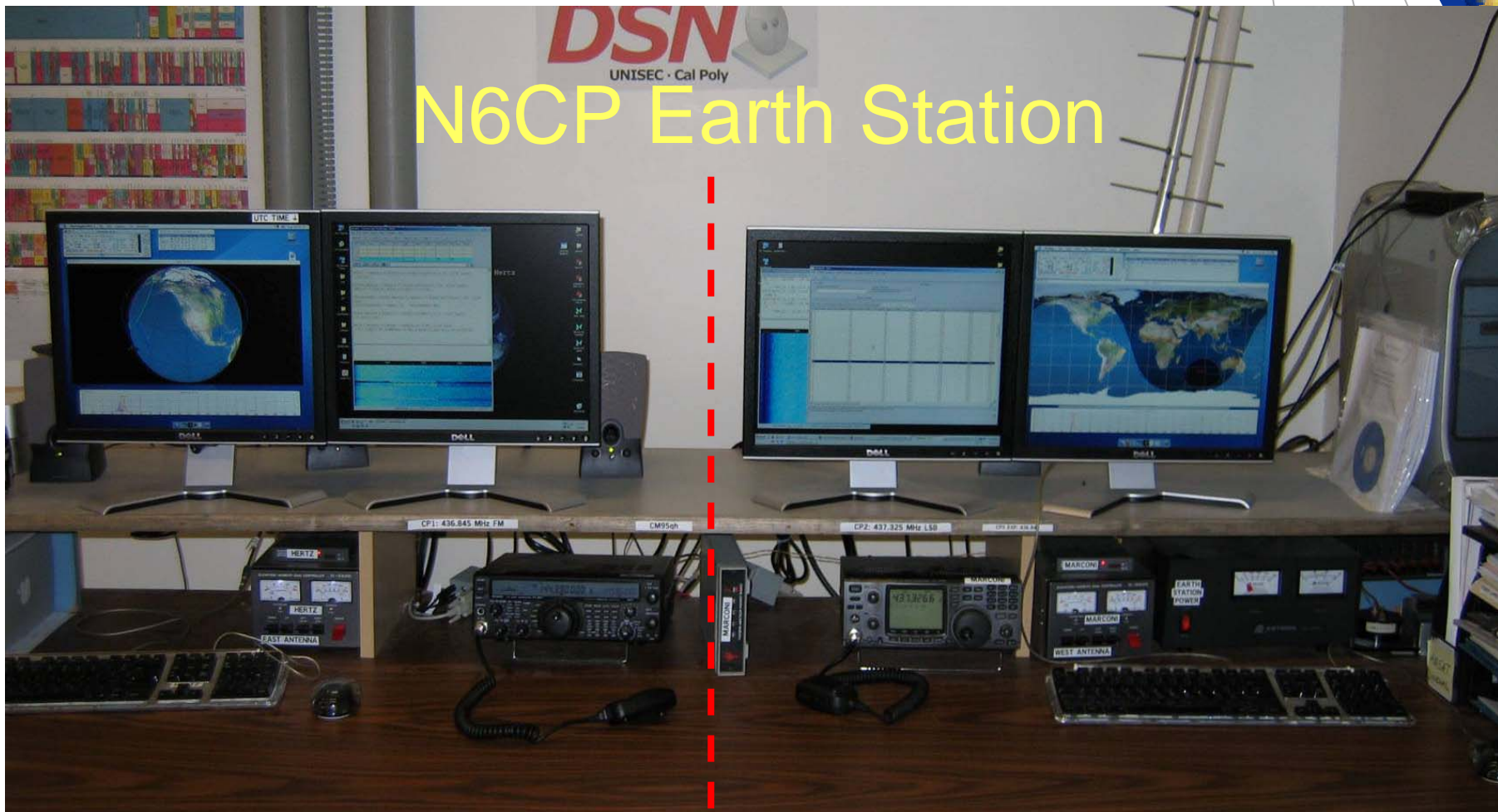
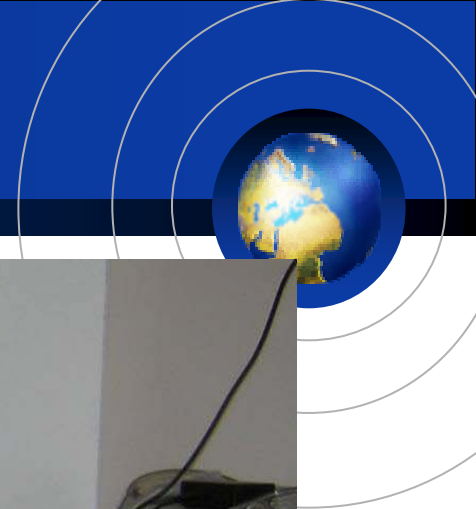
- CP2.1 manifested as CP4
 - Energy Storage and Dissipation Experiments
 - Test and Characterize CPBus



- CP3
 - Attitude Determination using a suite of sensors
 - Attitude Control using Magnetorquers in each side panel
 - Observation Imagers: lots of data to download!



Parallel Operations



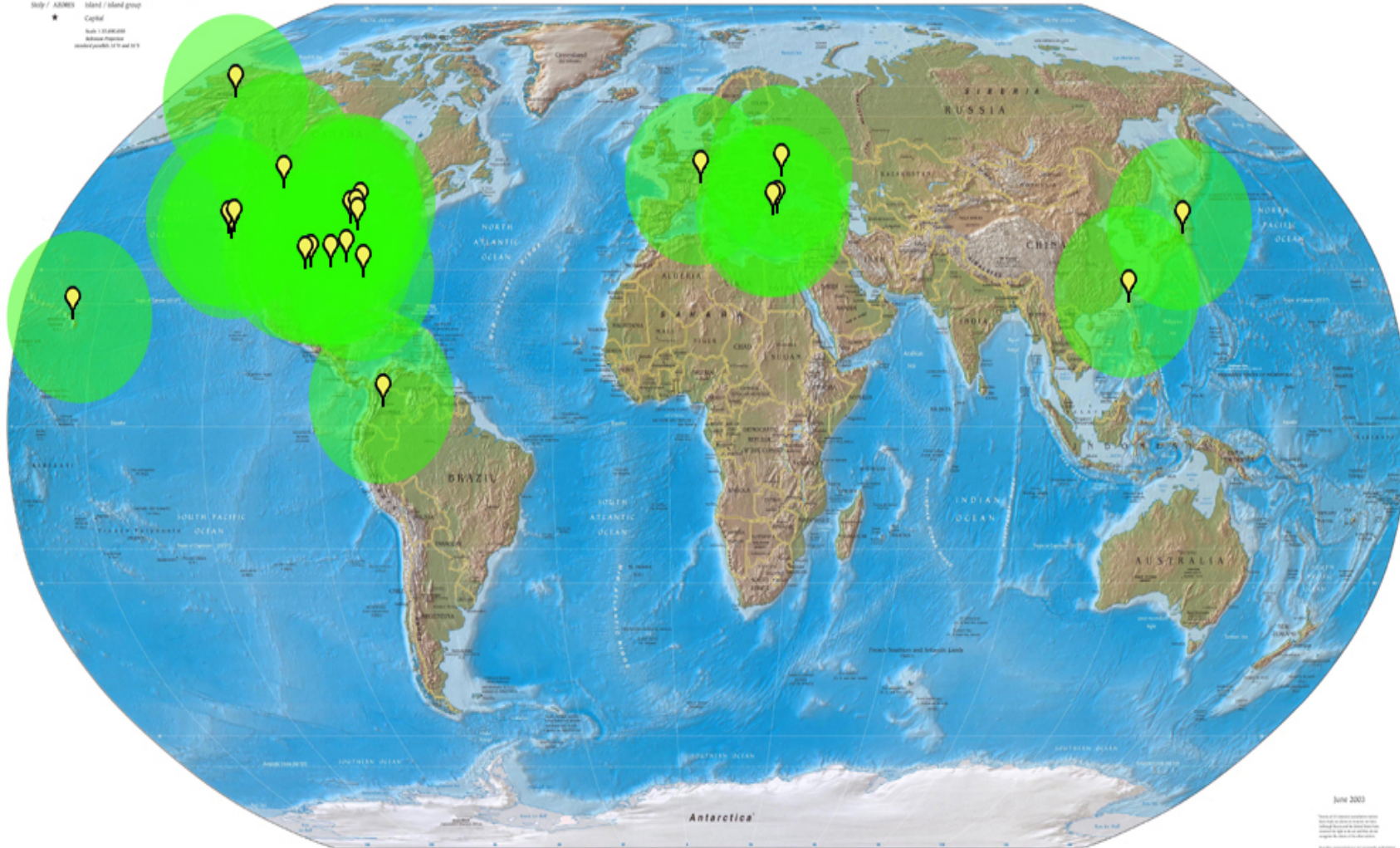
- Yeasu FT-847 and Icom IC-910
- Yaesu G-5500
- MixW Software TNC
- Mac Doppler Pro for tracking

The Ground Station Network



Physical Map of the World, June 2003

AUSTRALIA Independent state
Bermuda Dependency or area of special sovereignty
Isip / ASISIS Island / island group
● Capital
Scale: 1:10,000,000
Antarctica
Antarctic Peninsula and Subantarctic Islands
Antarctic Peninsula and Subantarctic Islands



June 2003

© 2003 National Aeronautics and Space Administration
All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording, or by any information storage and retrieval system, without the prior written permission of NASA.

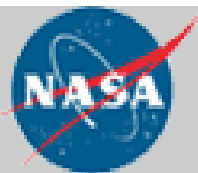
NSAS-03-001

GENSO Background



- Global Educational Network for Satellite Operators
- Originally started with the Japanese to combat interference
- Started under the International Space Education Board, a collaboration between CSA, ESA, JAXA, and NASA
- Approved on 5 October 2006 for 2 years
- Project to link low-cost earth stations

Canada 



National Aeronautics
and Space Administration

元素



What is GENSO



- A system to link ground stations using the internet
- Only 1200/9600 baud data for now
- Three parts:
 - Central server
 - Authentication and registration
 - Mission Control Client
 - Scheduling of Ground Station Servers
 - 1 MCC per satellite developer
 - Ground Station Servers
 - Actual interface between rotors/radio and internet

Central Server



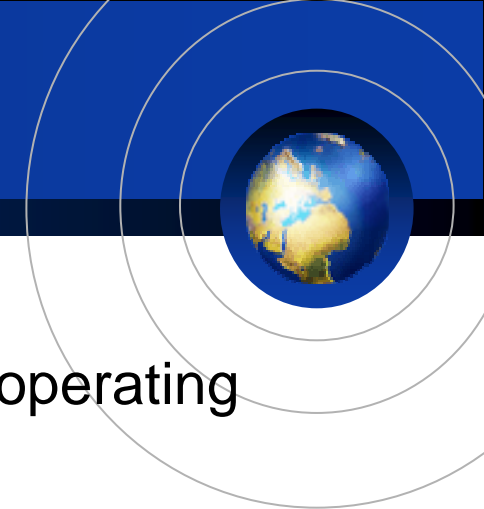
- 3 central servers located around the world
 - Europe
 - California (Cal Poly or SRI)
 - Japan
- Tasked with Authentication and Registration only
 - Registration of IP addresses of GSS and MCC
 - Statistics
- All other functions (scheduling, data transfer) will go peer-to-peer between Mission Control Clients and Ground Station Servers
 - This keeps the load off a single server when system scales up

Mission Control Client



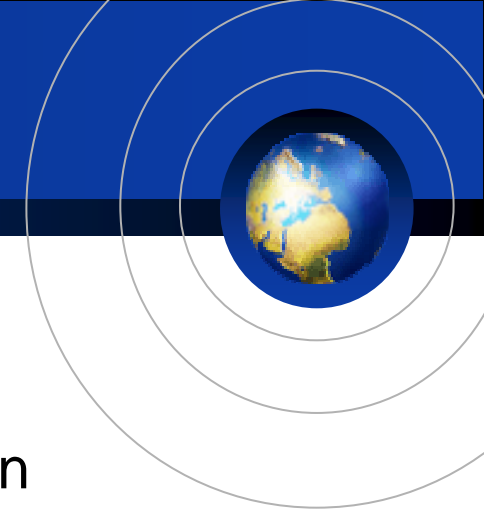
- A program that runs on a personal computer that can control Ground Station Servers
- Uses the Central Servers to get IP addresses for individual GSS, then contacts the GSS's directly to:
 - Schedule an active session
 - Download decoded data
 - Control the radios and rotors to track a satellite during an active session
 - IRC Client ?
 - Skype Client?

Ground Station Server



- Compatible with a majority of ground stations currently operating
- “Passive” tracking:
 - Will continuously track all satellites it can decode
 - Will forward data on to MCC
- “Active” tracking:
 - Someone at a MCC is actively controlling the rotors and radio, looking at the decoded data, and listening to the audio
 - Must be scheduled prior to satellite pass and cleared with GSS
 - Requires offline interaction and parties that know each other
- Store audio/data locally and stream to MCC as bandwidth allows
- IRC and/or Skype client?

“Standard” Earth Station



- Icom IC-910 radio with computer interface
- M² OR2800P-DC for Azimuth and MT-1000 for elevation
- Symek TNC 31S
 - Possibly software in future
- Antennas:
 - 2MCP22 for 145 MHz
 - 436CP42UG for 437 MHz
 - 1 meter dish for S-band (downlink only)

CP3 and CP4 status



- CP4 (CP2.1)
 - Heard beacon most every pass at Cal Poly
 - In pre-ops mode, beacons every 5 minutes
 - Decoded data packet last night – cold with too much power
- CP3
 - Not heard from yet
 - Haven't really tried
 - Only one left that hasn't been heard from
- Due to downlink mode, we need good keps to decode packets
 - Space-Track still having trouble with 16 objects
 - Need more time

Questions?



Thanks!

ppatel@calpoly.edu
bklofas@calpoly.edu

polysat.calpoly.edu
www.cubesat.org



POLYSAT