

# COSMIC X-RAY BACKGROUND NANOSAT

Spring 2011 CubeSat Developer's Workshop

Tyler G. Rose, *Student Project Lead*

Benjamin K. Malphrus, *Mentor*

Kevin Z. Brown, *Mentor*



# MISSION – TEAM

- Morehead State University (MSU)

*Benjamin Malphrus, Kevin Brown, Bob Twiggs, Jeff Kruth, Robert Kroll, Thomas Pannuti, Margaret Powell, Andrew Cavins, Jedidiah Reader, Brad Schneider, Tyler Rose*

- UC Berkeley

*Garrett Jernigan*

- Noqsi Aerospace, Ltd.

*John Doty, Matthew Wampler-Doty*

- Lawrence Livermore National Laboratories (LLNL)

*Lance Simms*

- Sonoma State University (SSU)

*Steve Anderson, Lynn Cominsky, Kamal Prasad*



# MISSION – DESCRIPTION

- Very few flux measurements of high energy cosmic X-ray background have been made
- Make precise measurements of the cosmic X-ray background (CXRB)
  - Intended range: 30-50 keV
  - Valuable for many reasons:
    - Ensure proper background subtraction when studying objects near the same emission (outskirts of clusters and groups of galaxies)
    - About 30% of the emission is unaccounted for considering discrete sources and clustered phenomena
      - Origin?
    - Lends insight into the evolution of primordial galaxies



# MISSION – DESCRIPTION

- Selected for ELaNa VI with expected flight for 2012
- Orbit
  - Moderate inclination
  - Altitude approximately 500 km
- 2U CubeSat
  - 1U – Payload
  - 1U – Support



# MISSION - CONSTRAINTS

- Time – project completion date scheduled for Dec. 2012
  - Keep it simple
- Drive costs to a minimum
  - Keep it simple
  - Maximize subsystem reuse
  - Utilize internal resources – prototyping, manufacturing, testing
- 3 degrees, 3 sigma accuracy for attitude knowledge
  - Post-process ADCS sensor data to reduce payload data
  - Spin stabilize

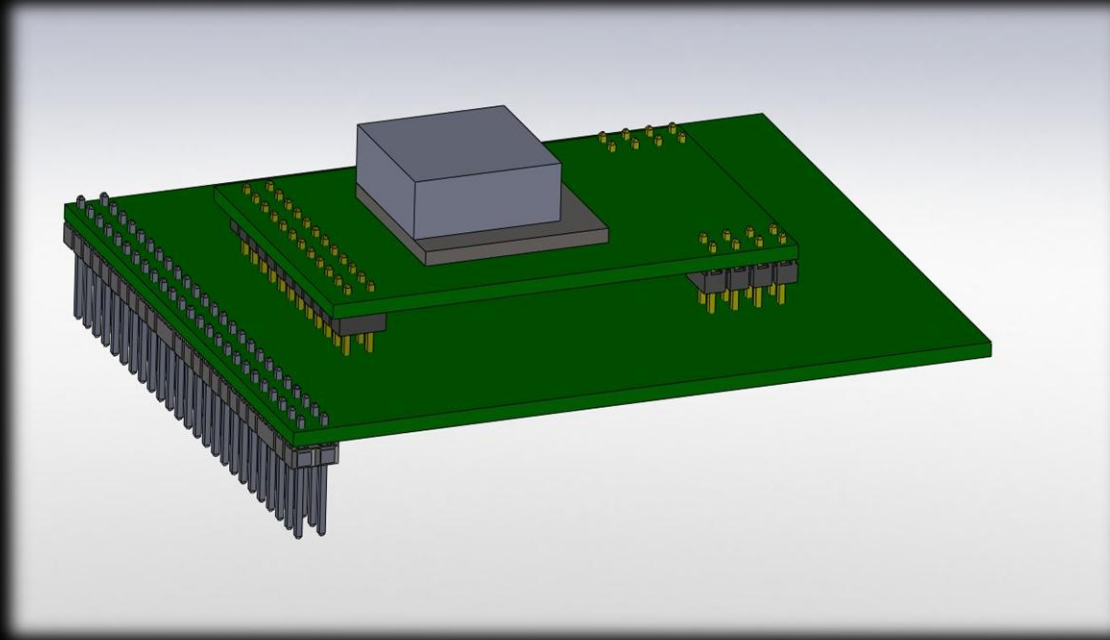


# PAYLOAD

- Cadmium Zinc Tellurium (CZT) Detector Array
  - Goal: < 5% flux measurement precision
  - Designed by UC Berkeley, LLNL, Noqsi Aerospace, and SSU
  - Features a collimator for preventing stray particles
  - Shielding - layered lead, copper, and tantalum



# PAYLOAD



Early CAD model of payload CZT detector array

# ADCS

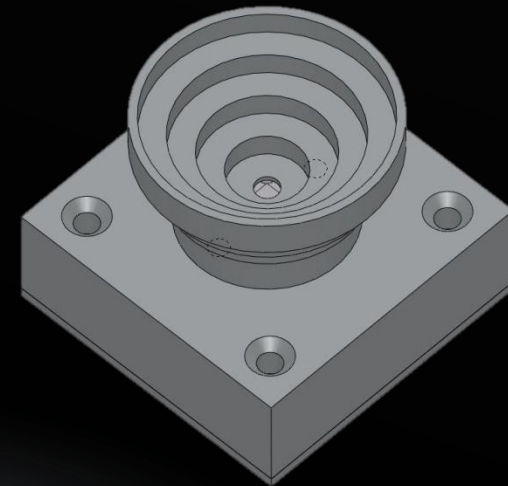
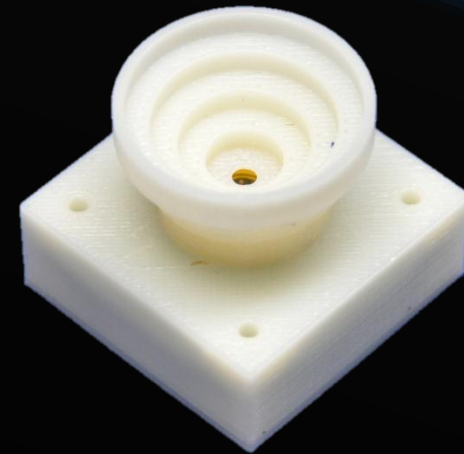
- Determination
  - Sun Sensors
    - Coarse (CSS)
    - Medium (MSS)
    - Fine (FSS)
  - Canopus Pippin
  - Magnetometer
  - MEMS Gyro
- Control
  - Magnetorquers
  - Simulink simulation for control tuning





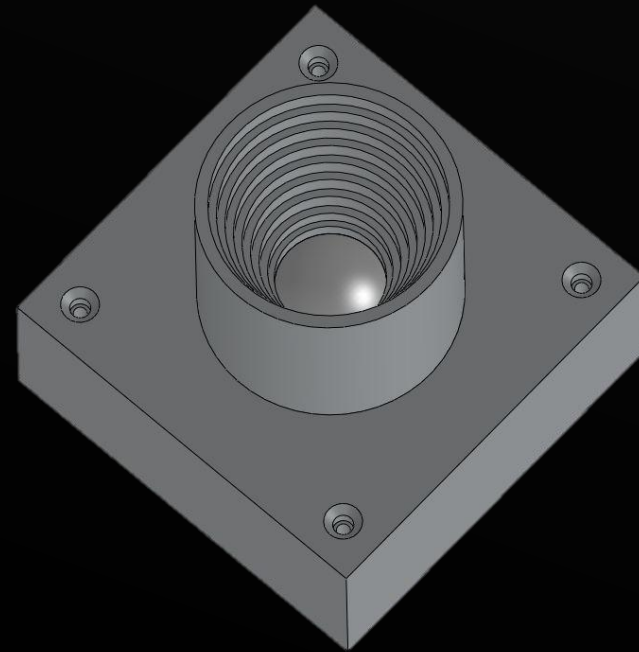
# ADCS - DETERMINATION

- Sun Sensors
  - Coarse, Medium, and Fine angular resolution
  - Sun pointing
    - Boresight
  - Testing through rapid-prototyped parts
- (Right) CAD Model
- (Right Top) Rapid-prototyped sun sensor assembled



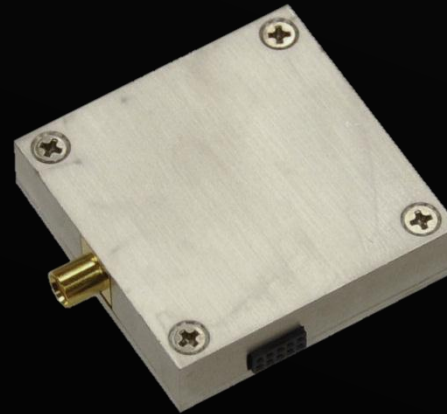
# ADCS - DETERMINATION

- Canopus Pipper
  - Star Sensor
  - Determine roll rate
  - Testing
    - Rapid-prototype frame and collimator
    - Calibrate on ground
- (Right) CAD Model



# COMM

- Radios:
  - AstroDev CII:
    - UHF-UHF Transceiver
  - AstroDev Beryllium 2:
    - S-Band Transmitter
- Antennas:
  - Steel tape whip antennas



# C&DH PROCESSOR

- Texas Instruments:
  - OMAP 3530
    - ARM Cortex-A8, 720 MHz
    - Linux OS
    - Power efficient



# POWER

- Body mount solar cells and fold out panels
  - Sun pointing: moderate incident angles - no MPPT
- Batteries – lithium ion
  - Higher capacity
- In-house designed direct energy transfer
  - Keep it simple
  - Quick turn-around



# STRUCTURE

- Complete CAD model before manufacturing
  - Leverages previous design work
- Rapid-prototyped and machined onsite
  - Quick turn-around
  - Lower costs



# GROUND STATIONS

- 21 meter Space Tracking Antenna at MSU
  - S-Band communication
- Dual Band Yagi Antenna
  - UHF communication
- Portable Satellite Tracking Kits
  - Primarily an E / PO effort
  - Dual Band Yagi Antennas



# ESTIMATED TIMELINE

Cosmic X-Ray Background Nanosat (CXBN) Mission Timeline													
#	Event	2011											
		Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov	Dec
1	Science Mission Concept	█											
2	Spacecraft Design Concept		█	█									
3	Payload Requirements Defined			█	█								
4	Design / Prototype Phase			█	█	█							
5	Development / Production Phase				█	█	█	█					
6	Preliminary Design Review				█								
7	Eng. Model Prototype & Production				█	█	█	█					
8	Eng. Model Functional Testing						█	█	█				
9	Interface Control Document Received								█				
10	Critical Design Review								█				
11	Flight Unit Orders								█	█			
12	Flight Systems Fabrication / Assembly								█	█	█		
13	Flight Payload Fabrication / Assembly								█	█	█		
14	Flight Payload Integration									█			
15	Flight Model Functional Testing									█	█		
16	Test Results Provided										█		
17	Preflight Testing onsite (2U Only)											█	█
18	Preflight Testing offsite (2U Only)												█
19	Comprehensive Test Report												█





# CONCLUSION

- On pace for delivery of a rapidly constructed 2U
  - Start to finish – 8 months!

