



# Smart Nanosatellite Attitude Propagator (SNAP 2.0)

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CubeSat Developers' Workshop

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#### Kentucky Space Missions



#### New NanoRacks/CubeLab Standard on the ISS, July 2010



First Student Built Satellites to be Launched by NASA (ELaNa/Glory) February 23rd, 2011



ATK

Balloon-I, July 2008



Garvey P-12A



First CubeSats Ejected into Sub-Orbital Space, March 2010



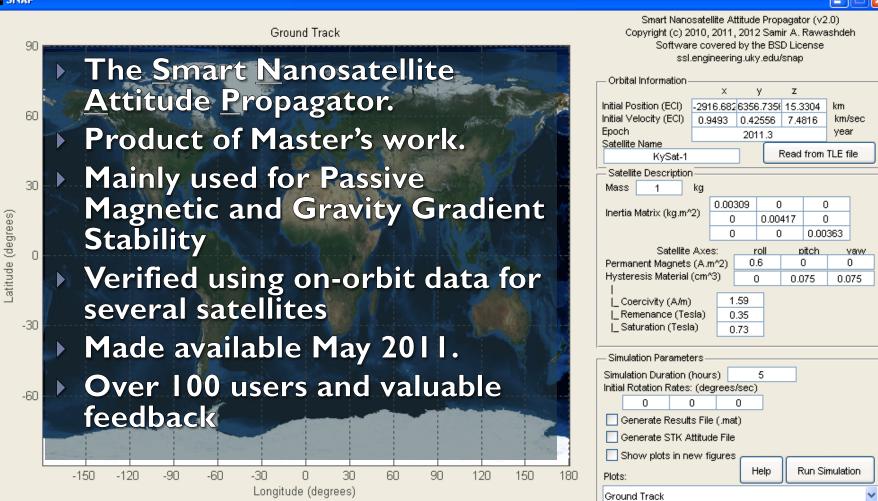
First Flight, Composite Super-Loki, December 2007

#### **Presentation Overview**

- What is SNAP? (an attitude propagator)
- How it works
- Example: Passive Magnetic Stability
- Status since release
- What's new this Summer?
- Capabilities and moving forward.
- How to get a copy

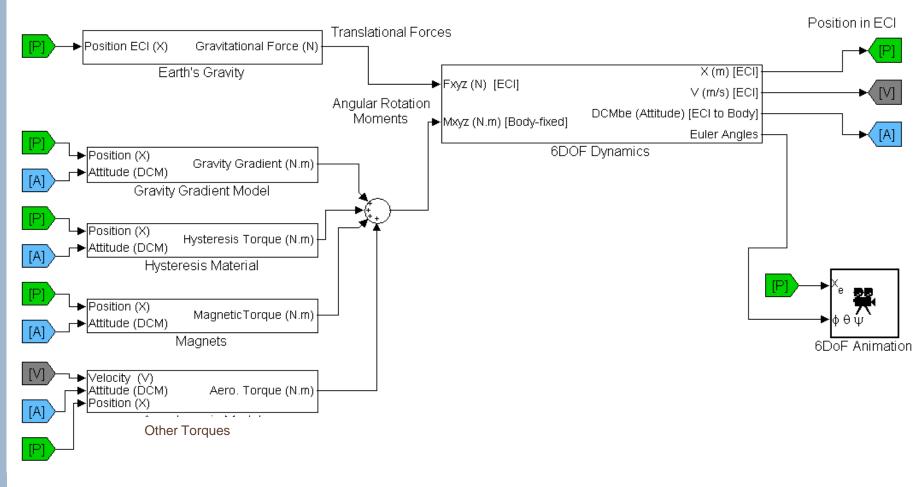
### What is SNAP?





#### How SNAP works

Kentucky Space - Orbital Environment Simulator



## Capability

#### Adjustable Spacecraft Description and Orbit

- Inertia Matrix
- Magnets and Hysteresis Material
- Orbital Elements
- Simulate Effect of Orbital Environment on Satellite Attitude

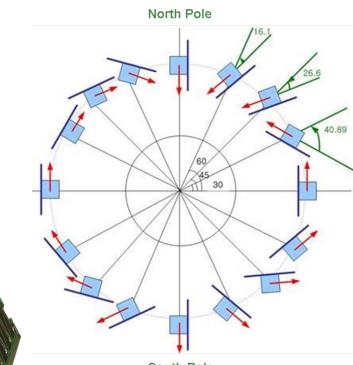
#### Response Plots

- Satellite attitude relative to nadir, magnetic field, velocity vector
- Angular rates
- Individual environmental torques
- Export to MATLAB
- Export to STK

### Passive Magnetic Stability

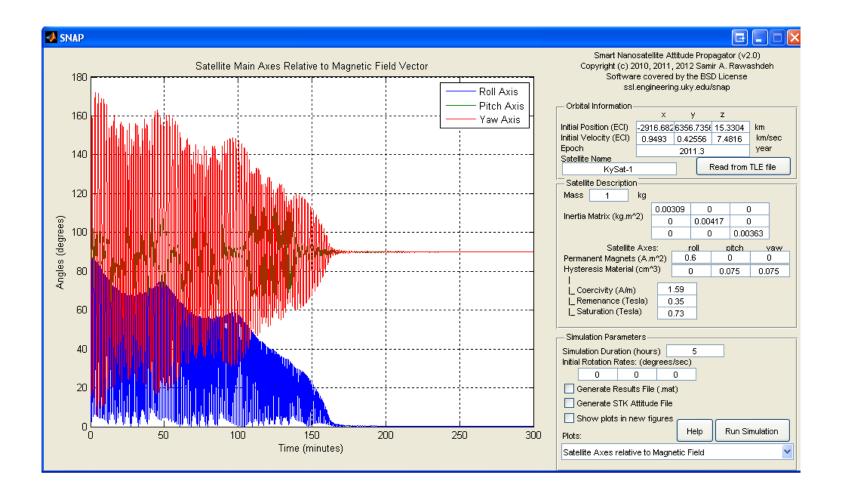
- Implemented on KySat-I
- Polar Orbit
- Align with Magnetic Field
  - Permanent Magnets
- Dampen Motion
  - Hysteresis Material (HyMu80)





South Pole

#### Attitude Response

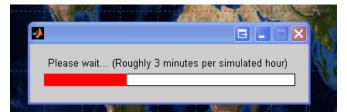


#### KySat-1: Animation

Play Video

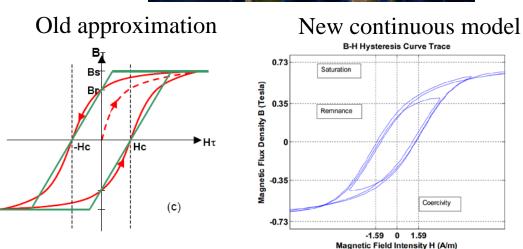
### What's new in SNAP 2.0?

 It's slower... but more accurate (shortened time-step)



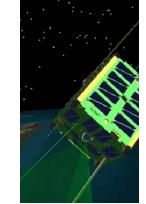
 Higher fidelity Magnetic Hysteresis Model

 Flexibility for additions and Improvements.

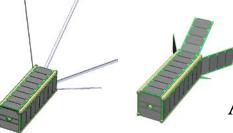


### Potential

- Power generation profiling
- Aerodynamic Stabilization with Magnetic Hysteresis damping for ISS altitudes

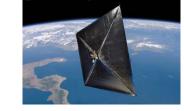


KySat-1 Illumination



Aerostable Concepts, UKY

Model solar pressure for solar sailing

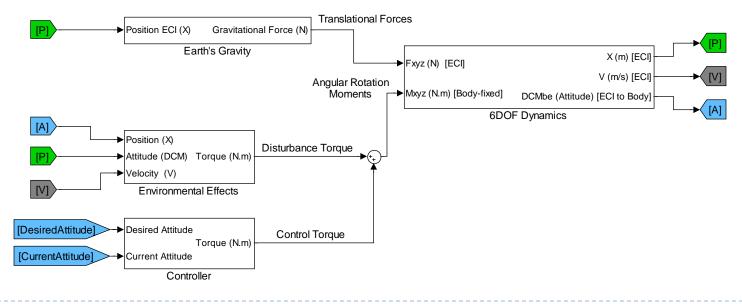


Nanosail-D, NASA

Reaction wheels, torque coils, momentum wheels.

#### Active Attitude Control

- Compare desired attitude with actual attitude
- Study attitude control system effectiveness against disturbance torques
- Tune control algorithms.
- Quantify slew rates and tracking accuracy.



#### Conclusion

#### Download SNAP

- <u>http://ssl.engineering.uky.edu/snap/</u>
  (Or just Google "CubeSat SNAP")
- New user forum for questions and file exchange
- Share models you create
- Advanced capabilities beyond SNAP are available at UKY

### Thank You

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