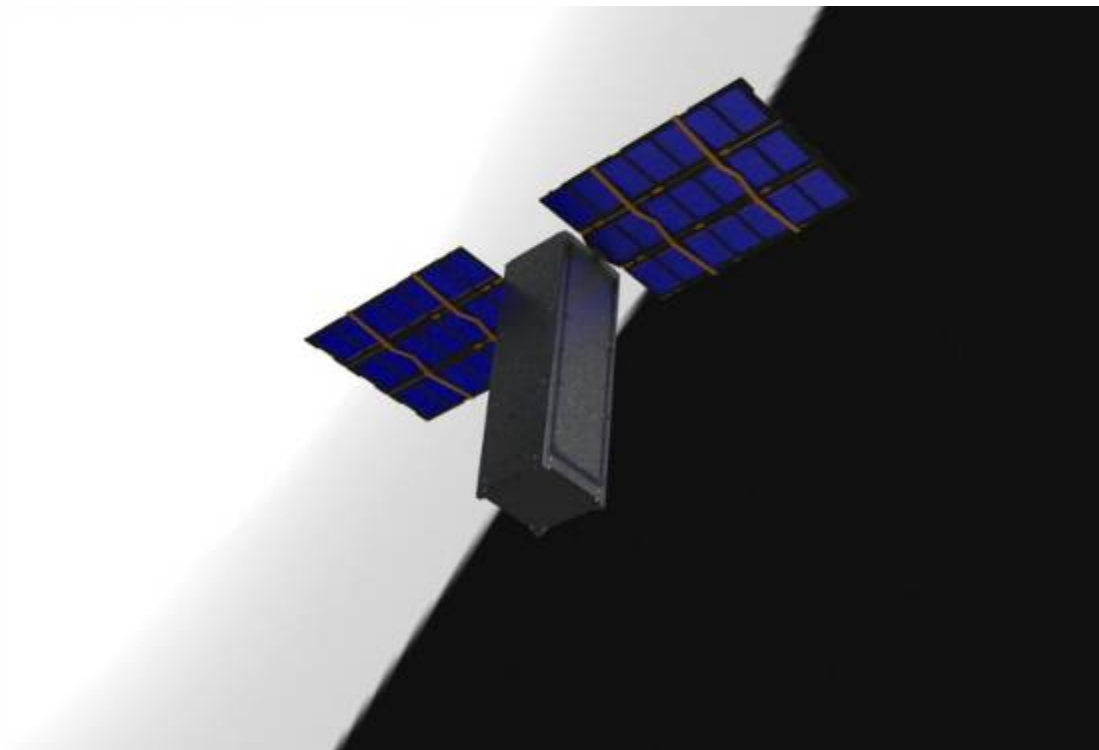




# Innovative High Specific Performance (HaWK) Solar Array

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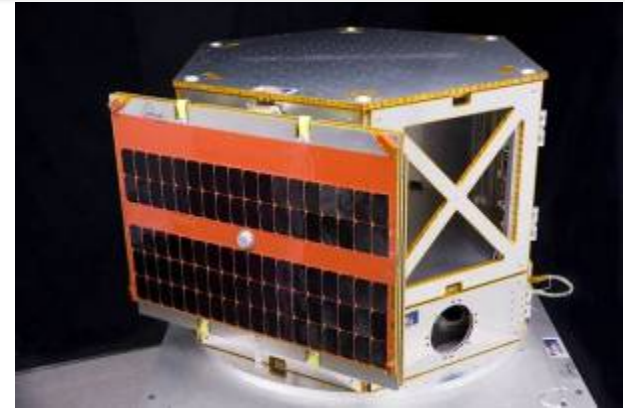
**MMA Design LLC**  
**6 August, 2011**





# MMA Design Overview

- Company Details
  - Colorado company
  - Founded in 2007
  - Aerospace and Design Engineering Firm
  - Nederland, Colorado Engineering Facility
  - Boulder, Colorado Test Facility
  - Broomfield, Colorado Machine shop
- Three Primary Business Areas
  - Space Power Systems
  - Space Structures
  - Electro-Mechanical Systems
- Current System Engineered Products
  - dragNET De-orbit Modules
  - HaWK High Performance Solar Arrays
  - Modular Bus Structures
  - ESPA-Class Modular Solar Arrays
  - Gimbals



**MMA's PnP Bus and MDSAS Solar Array**

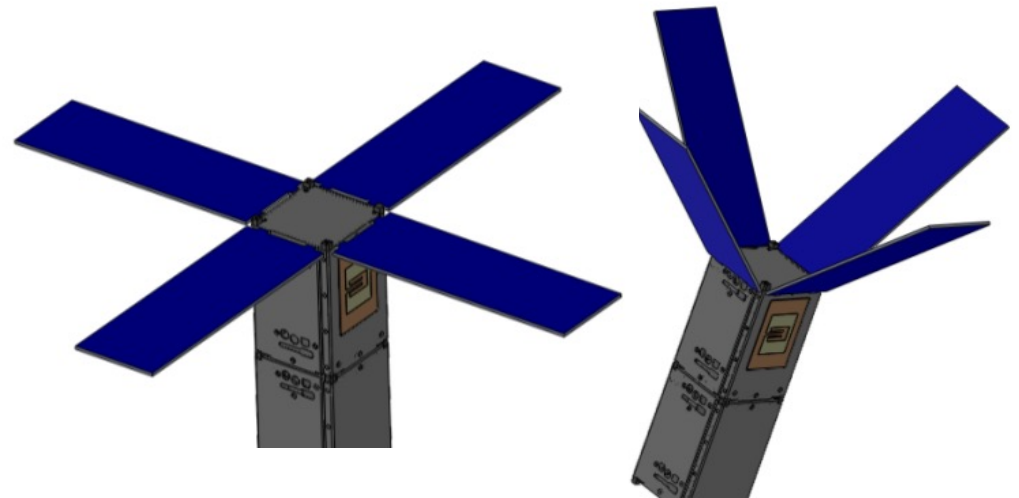


**MMA's dragNET De-orbit Module**



# Current State of the Art NanoSat Solar Array

- Typical Features
  - No Sun Tracking
  - Body mounted or deployed fixed wings
  - 60 W/kg
  - 21 W Peak Power
  - 5 W OAP





# System Performance Metrics

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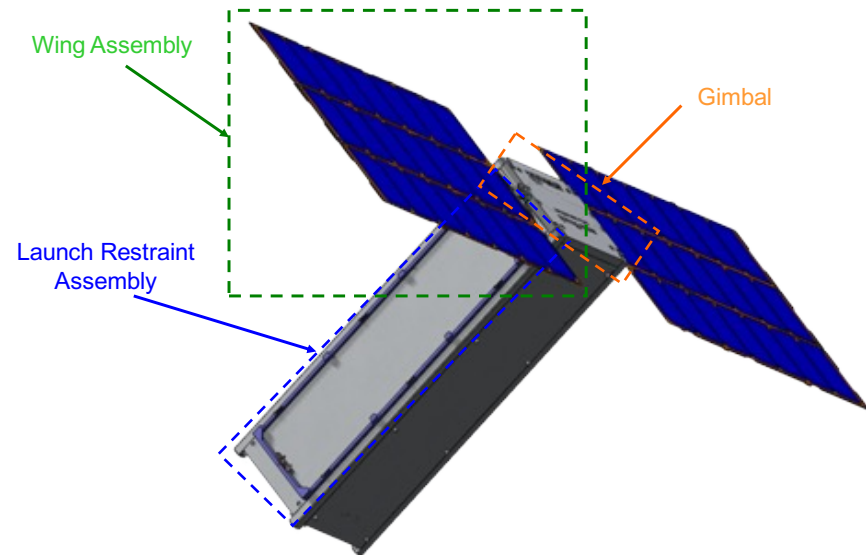
- Specific power  $\geq 125$  W/kg
- Ability to sun track to dramatically increase Orbital Average Power (OAP)
- Peak power  $\geq 35$  W using existing triple junction CICs
- Stowed position volume using only the unused space between P-Pod and CubeSat
- Highly modular and PnP compatible, reconfigurable based on mission needs





# NanoSat HaWK Solar Array

- Features
  - Sun tracked continuous high power
  - De-orbit < 25 years from 700 km orbit
  - Maximizes volume and mass for payloads
  - 130 W/kg (>200% increase)
  - 36 W Peak Power
  - 22 W OAP (>300% increase)
  - 0.6 kg System Mass
  - Standard or IMM CICs
  - Modular and scalable to 100 W peak power and 50 W OAP

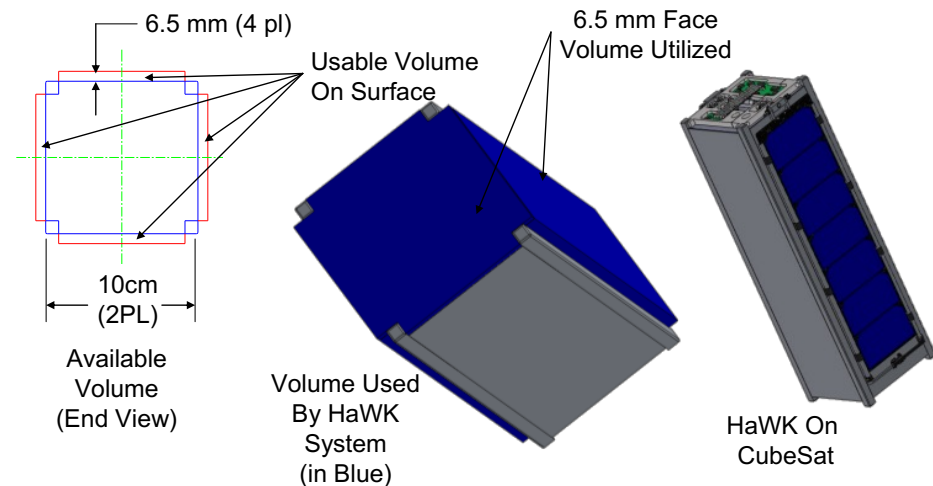


**MMA's NanoSat HaWK is Patent Pending**



# CubeSat HaWK Packaging

- Innovative system packaging
- Uses available 6.5 mm space between P-Pod and CubeSat
- Maximizes mission payload volume and mass
- High mass and volume efficiency
- Highly modular architecture

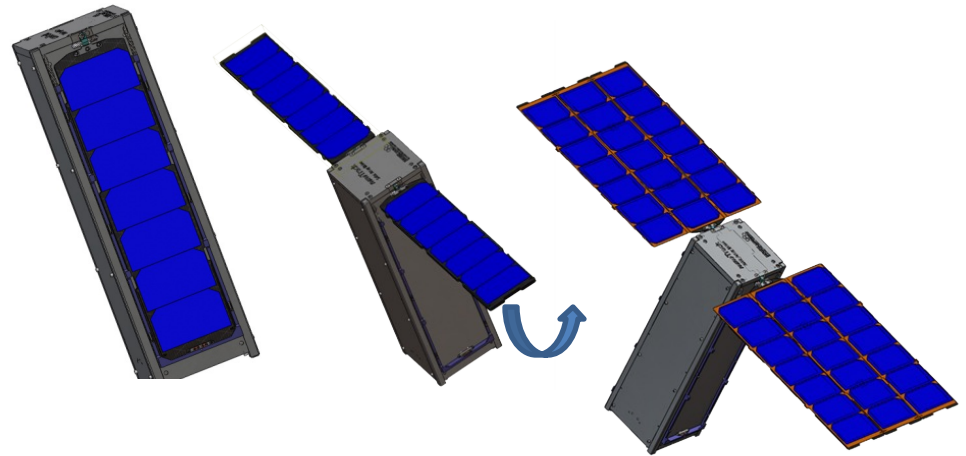


## HaWK Stowed Packaging



# HaWK Deployment Sequence

- Initiate launch release, simple heater circuit power
- Root spring rotates center panel
- Spring pre-loaded Flip-out side panels unfold
- Deployed state reached at hinge hard stop
- Enable and command SADA to articulate in sun tracking mode



**Stowed to Deployed and Tracking Mode**



# HaWK Wing

- Graphite panel
- Kapton overlayment
- Spectrolab UTJ CICs or equivalent
- Soldered interconnects (typically < 2 year missions)
- Mass efficient deployed structure



**HaWK Engineering Unit**

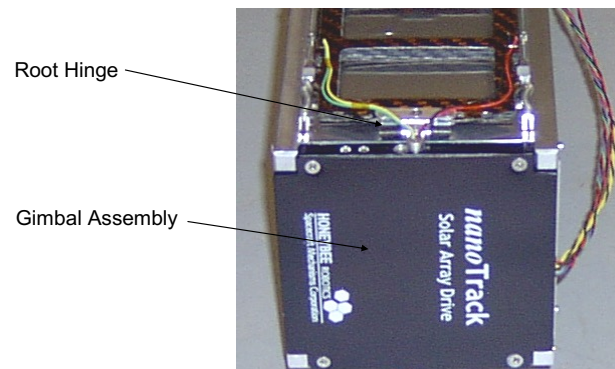






# HaWK SADA

- Partnered with Honeybee Robotics to jointly develop nanoTrack
- Patent Pending
- 3U CubeSat bus form factor – fits in 6.5 mm unused space on end
- Dual wing single axis rotation
- $\pm 180$  deg range of motion

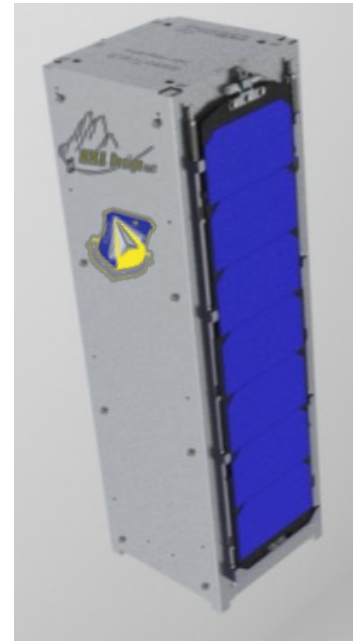


HaWK SADA Engineering Unit and Test Box



# HaWK Hold Down Release Mechanism (HDRM)

- High margin release design
- HDRM supports wings during launch environment
- Initiate simple heater circuit
- HDRM releases for wing deployment



**HaWK Stowed**



# HaWK Engineering Unit Deployed





# HaWK Engineering Unit Stowed





# Conclusion

- HaWK establishes State of the Art performance exceeding all system performance metrics
  - 130 W/kg
  - 22 W OAP
  - 36 W peak power
  - Efficient packaging
  - Sun tracking
- Technical Readiness Level 4/5
- Currently under Phase II SBIR development with AFRL
- Space Act Agreement with NASA to apply to future NASA missions

