

The background of the slide features a faint, light gray image of a satellite structure, showing various panels and components. The main title 'SMARTSat' is centered in a white rectangular box with a black border.

SMARTSat

Shape Memory Alloy Research
Technology Satellite

Allison Barnard

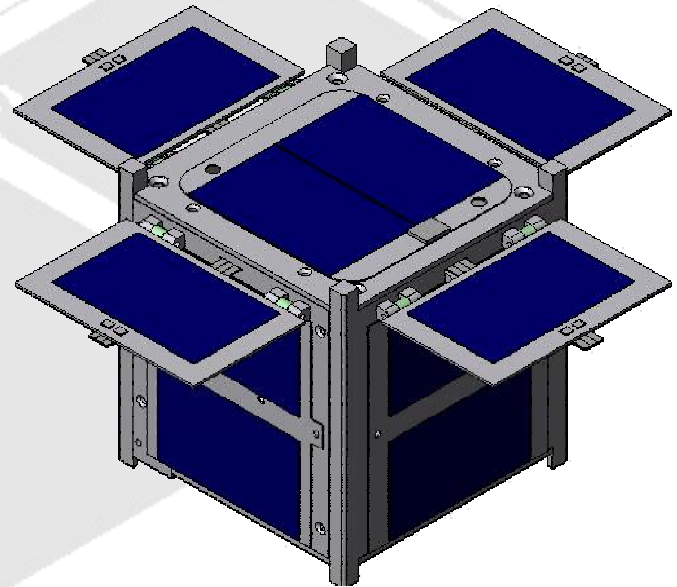
Alicia Broederdorf

Texas A&M University
Space Engineering Institute



Outline

- Introduction / Mission Objectives
- Systems Overview
- Power Analysis
- Thermal Analysis
- Mass Budget
- Balloon Testing



Introduction

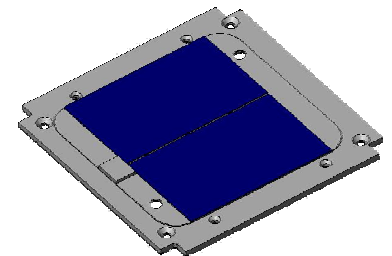
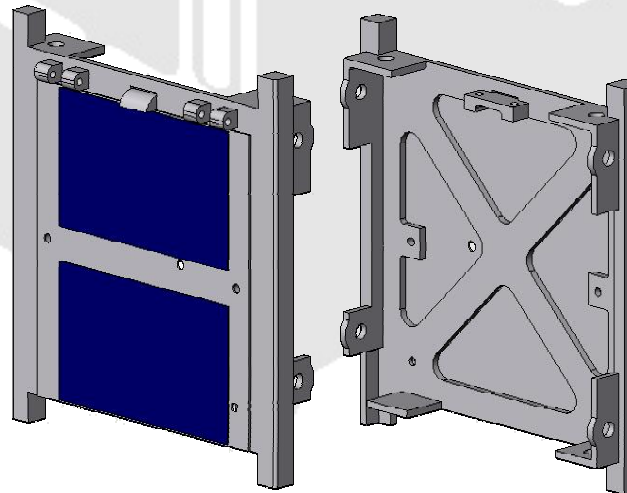
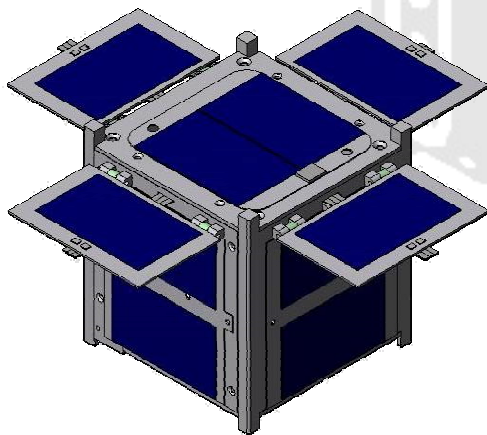
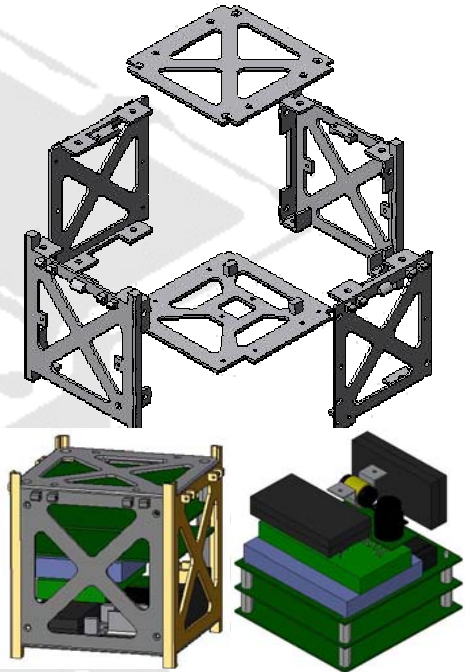
- The Space Engineering Institute program at Texas A&M's Spacecraft Technology Center is a partnership with NASA that is focused on providing an opportunity for undergraduate students to work in teams on projects directly related to the space industry.
- One team of 5 to 15 students has been designing a CubeSat for several semesters.

Mission Objectives

- Demonstrate the use of Shape Memory Alloys to deploy solar panels.
- Demonstrate an attitude determination algorithm using input from a magnetometer and sun sensors.
- Take and transmit pictures of Earth.

Structure

- Six panels of Aluminum 6061
 - Integrated side rails
- Cover panels on all sides
 - Ground plane for solar cells
 - Radiation shielding
- Integrated mounting brackets for components



Command and Data Handling/ Communications

- Microprocessor
 - DragonBallVZ
 - Processing power for attitude determination
 - High radiation tolerance
 - Low power
- Microcontrollers for redundancy
- Radio
 - Yaesu VX-2R
 - Modified to reduce mass and space
- TNC
 - PicoPacket
 - 1200 Baud
 - Smallest complete TNC available
 - Modified to reduce power, mass, and space



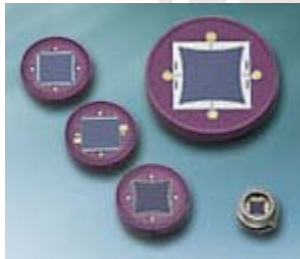
Attitude Determination and Control

Attitude Determination:

- Magnetometer
 - Honeywell HMC 2003
 - Three-axis magnetic sensor



- Sun Sensors
 - Hamamatsu position-sensitive detectors



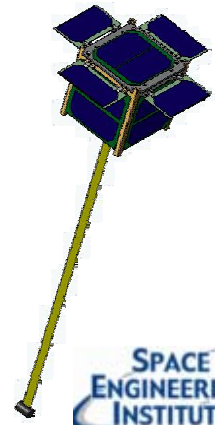
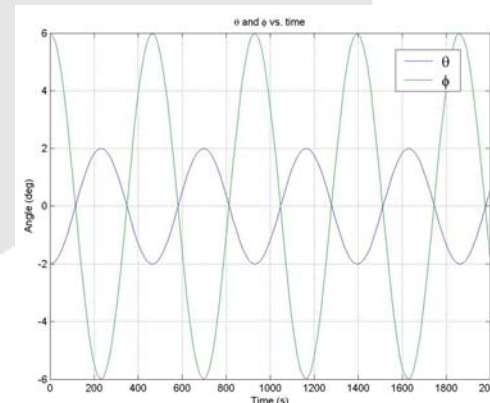
- Kalman Filter

Attitude Control

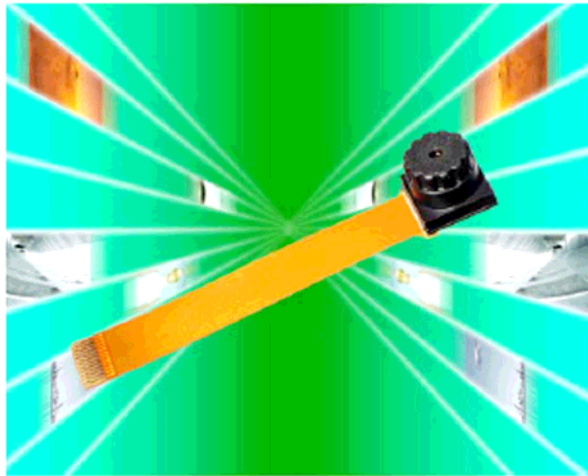
- Magnetorquers (active)



- Gravity Gradient boom (passive)
 - Gravity holds the long axis perpendicular to earth's surface



Camera

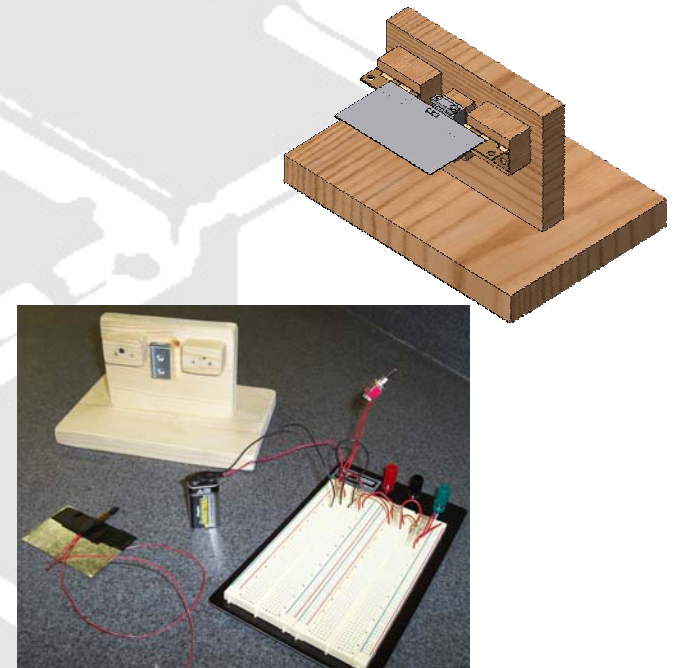
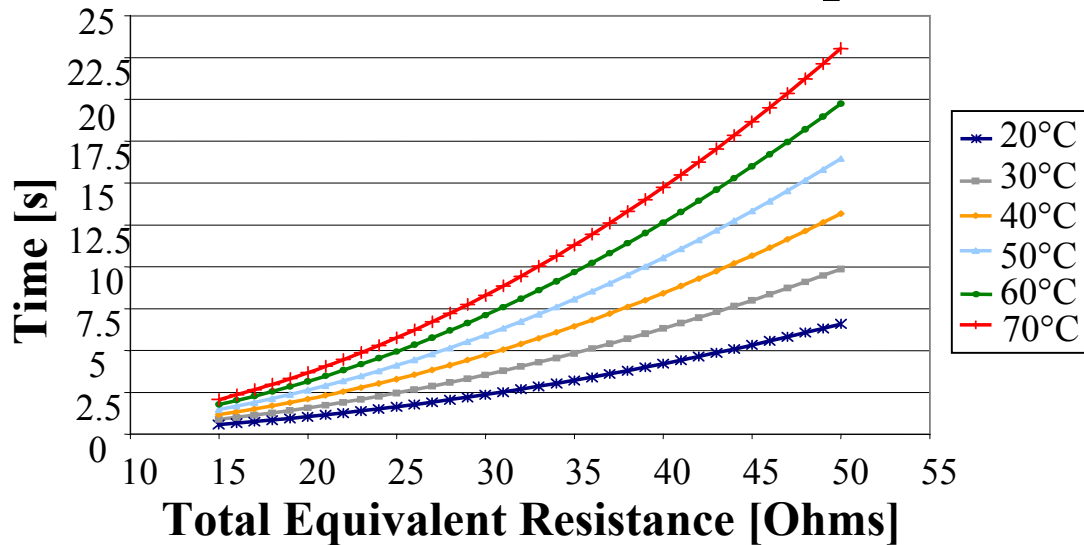


- SXGA Camera Module
 - Dialog Semiconductor
 - 1.3 Mega pixels
 - JPEG compression
 - Low power consumption

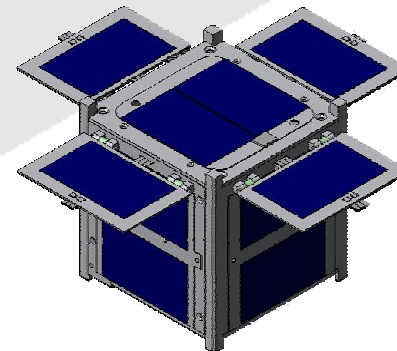


Shape Memory Alloy System

Time to Heat SMA Strip



- Shape memory alloy (SMA) strips will deploy four panels each with an additional solar cell
 - Lightweight
 - Controlled deployment
 - Very simple system

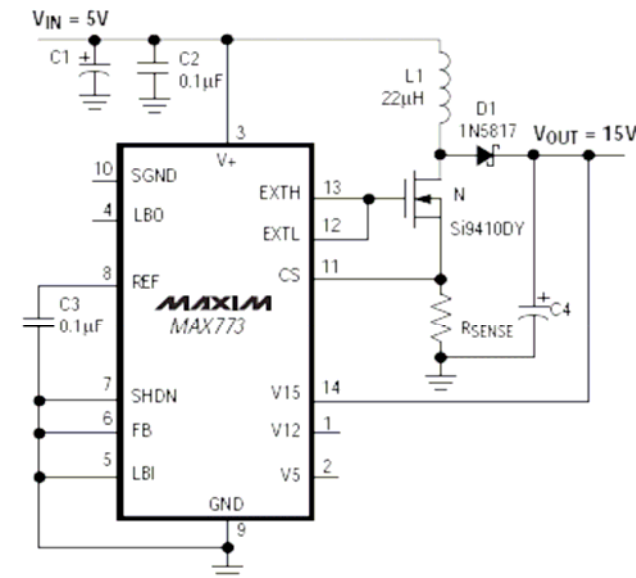
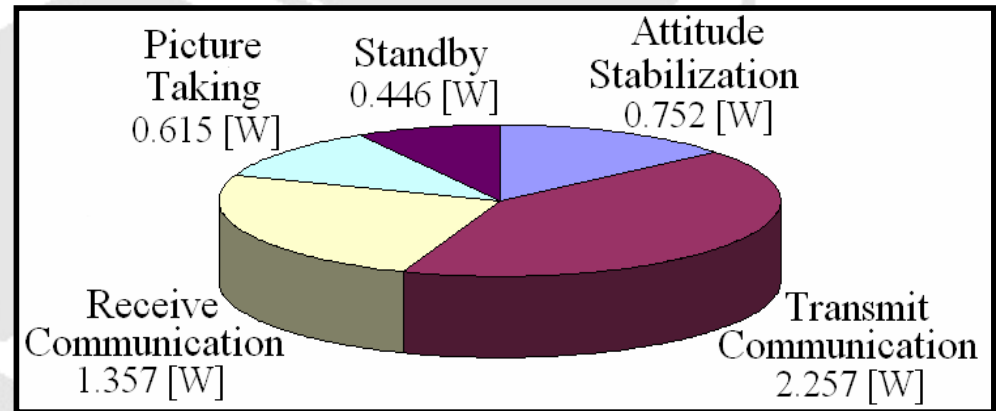


Power Subsystem

- Power Storage
 - 3.7V Lithium Ion Batteries
 - Two in series, 1950 mAh
 - MAX 1737 Charger
 - 300kHz
 - 90% Conversion Efficiency
- Power Converters
 - Buck
 - MAX 758A (+5V)
 - MAX 649 (+5V/+3.3V/+3V/adj.)
 - Boost
 - MAX 770 (+5V/adj.)
 - MAX 773 (+15V/adj.)
 - Buck/Boost
 - Max 743 (+5V/+15V/+12V)
- Super Capacitors
 - Capacitance: 2F
 - Voltage Rating: 5V

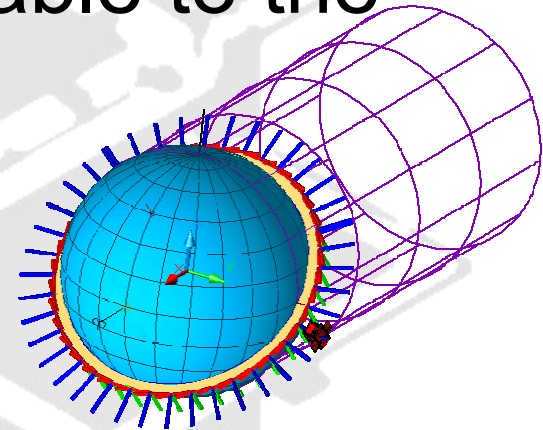


Power Modes

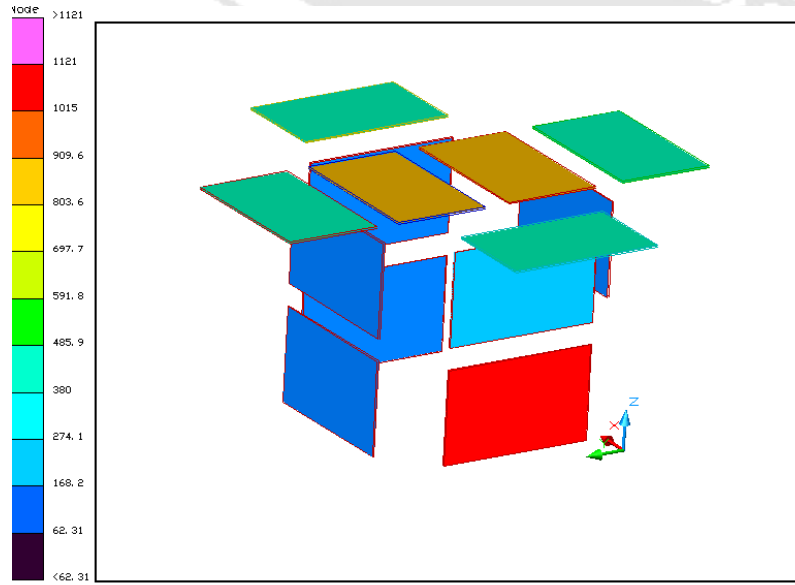
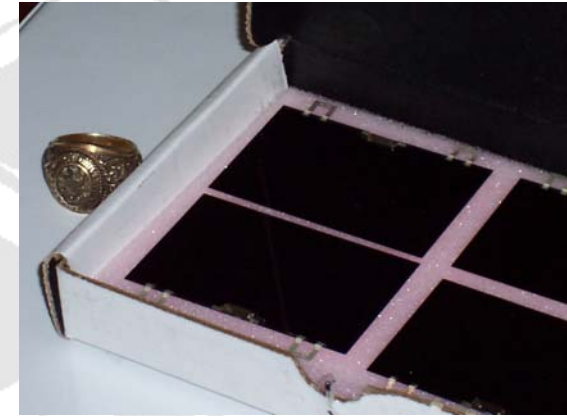
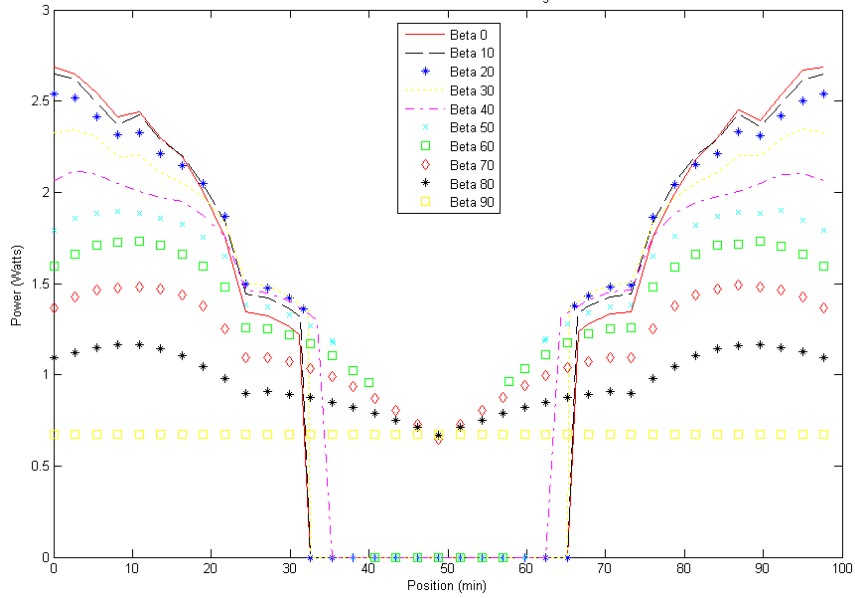


Power Analysis

- Used Thermal Desktop and RadCad to analyze solar power available to the satellite during its orbit.
- Satellite was simulated to remain stable on its axes during orbit, approximating the attitude control system.
- Data output provided solar energy input in W/m^2 for each cell at 39 positions during one orbit. Each TecStar solar cell has a 22% beginning of life efficiency.

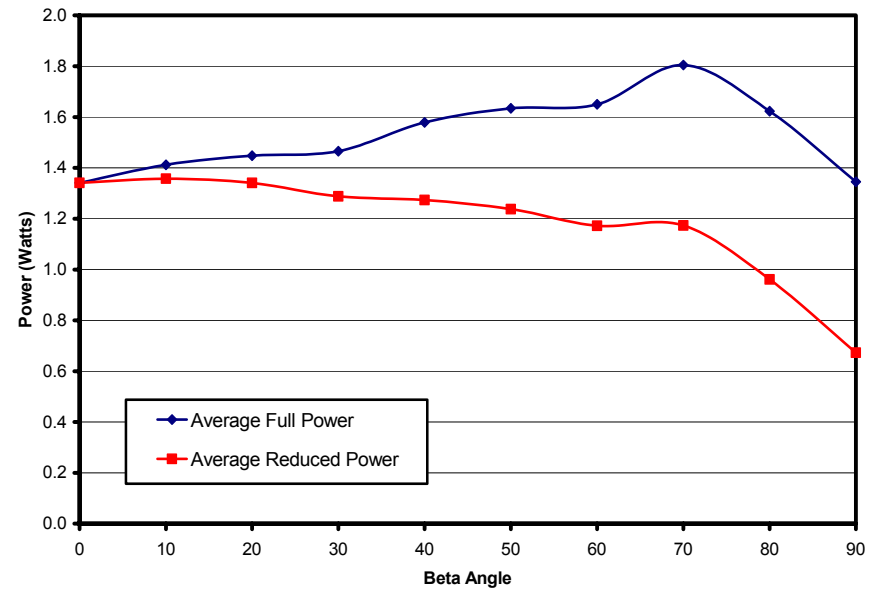


Reduced Power Produced at Beta Angles



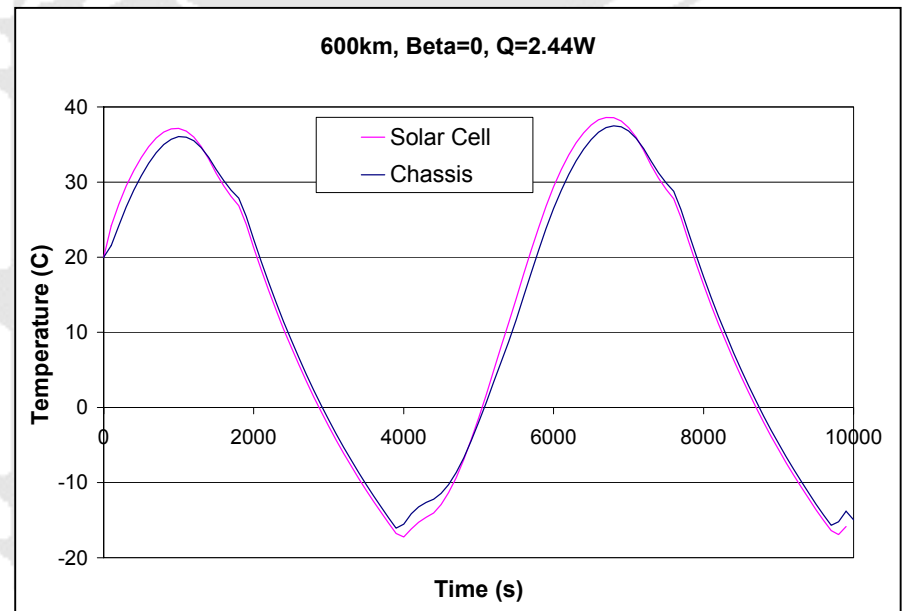
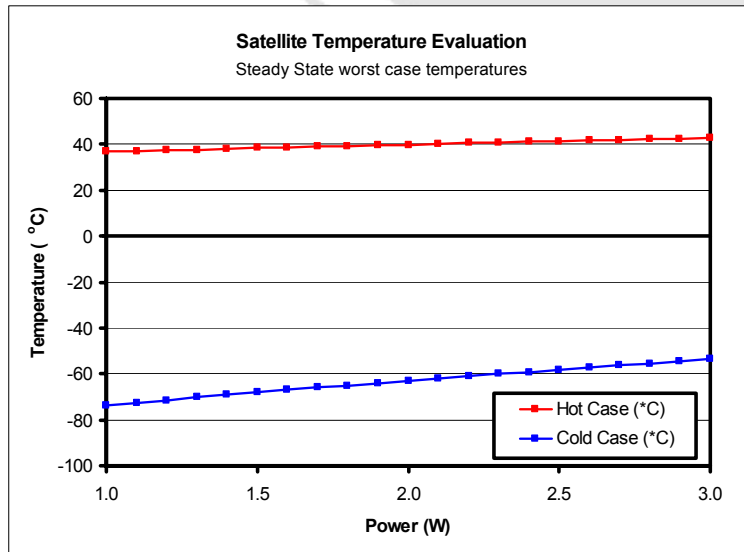
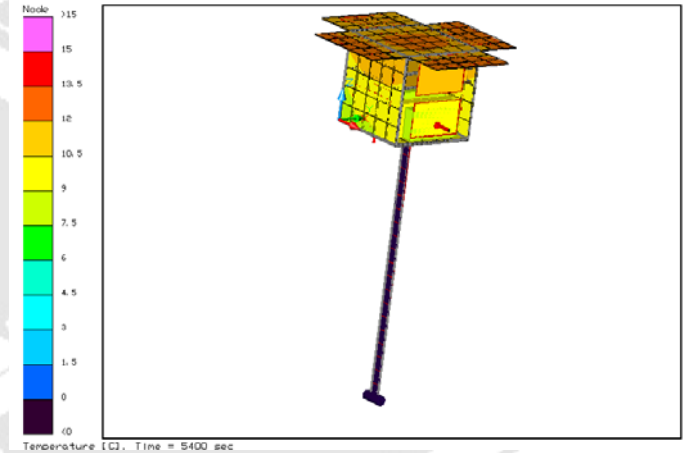
Orbit Time = 5049.29, pos = 33, Direct incident flux [SA], W/m²

Average Power Comparison



Thermal Analysis

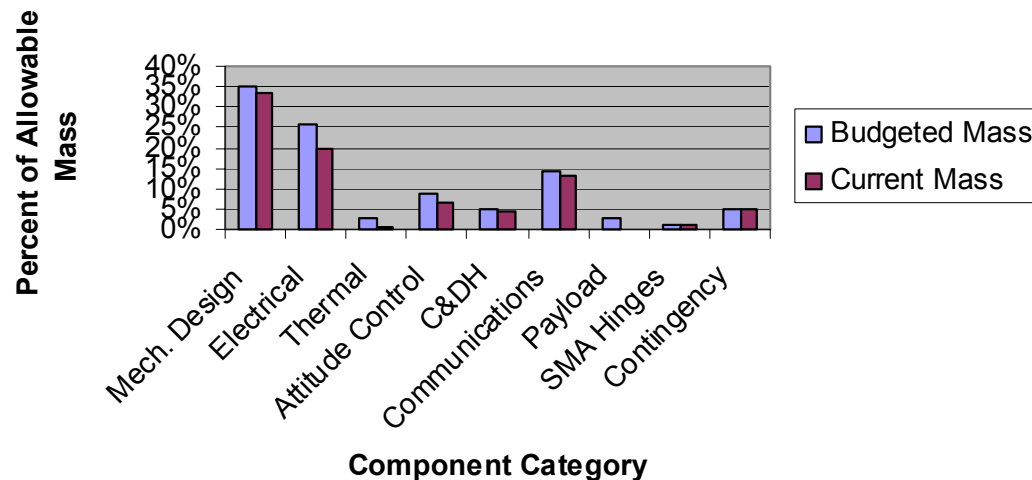
- **Single-node analysis**
 - sphere used in place of the satellite, with equivalent surface area
- **Hot and cold case analyzed**
- **Thermal Desktop model being developed**



Mass Budget

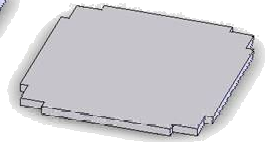
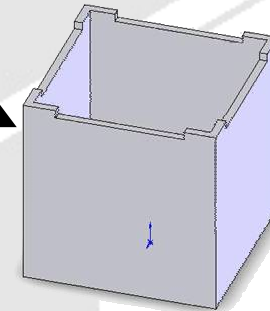
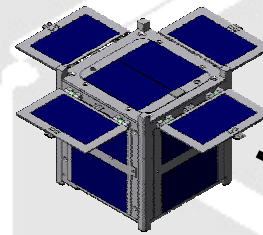
Component Category	Budgeted Mass	Current Mass
Mech. Design	35.00%	33.60%
Electrical	26.00%	19.80%
Thermal	2.50%	0.50%
Attitude Control	8.50%	6.50%
C&DH	5.00%	4.20%
Communications	14.50%	13.00%
Payload	2.50%	0.16%
SMA Hinges	1.00%	0.92%
Contingency	5.00%	5.00%

Budgeted Mass vs. Current Mass Distribution



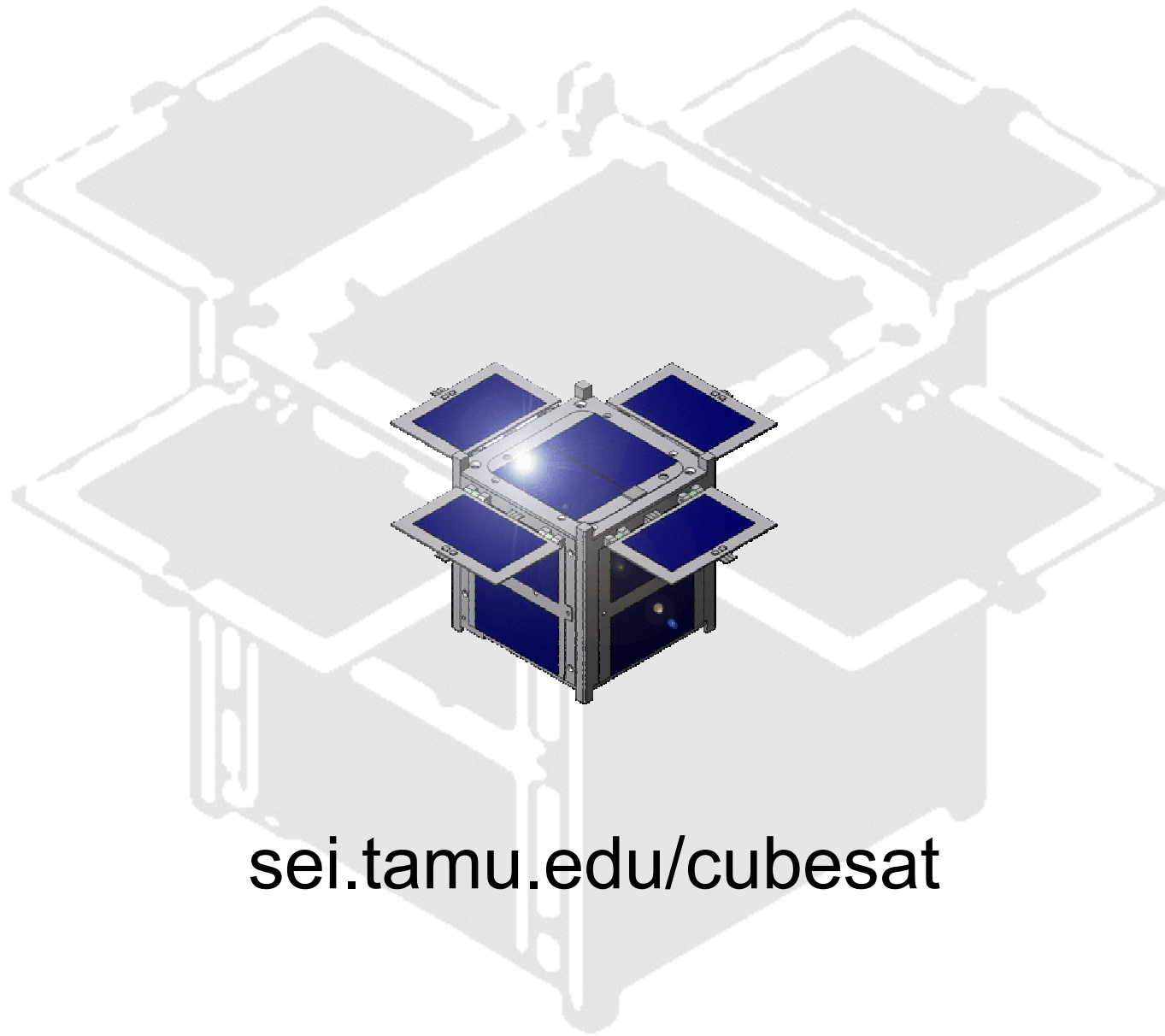
Balloon Testing

- SMARTBox is the high altitude balloon platform for testing SMARTSat components in a near space environment.
- Components and subsystems can be tested at altitudes around 100,000 feet, and recovered after testing using the tracking system.



Conclusions

- Teamwork and communication is extremely important, especially with such a large team with different skill and experience levels, working on different schedules.
- Initial design phase has been completed. Subsystems are moving into the prototyping and testing stages.
- Prototypes will be tested on balloon launches beginning in the fall of 2006.



sei.tamu.edu/cubesat